SEMICONDUCTOR, INC.

# **CAT59C11A** 1K BIT SERIAL E<sup>2</sup>PROM

# **Preliminary**

### **DESCRIPTION**

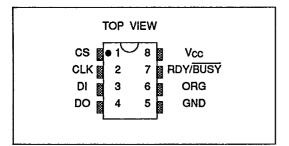
The CAT59C11A is a 1K bit Serial E<sup>2</sup>PROM memory device organized in 64 registers of 16 bits or 128 registers of 8 bits each. Each register can be written (or read) serially by using the DI (or DO) pin. The CAT59C11A is manufactured using Catalyst's advanced CMOS E<sup>2</sup>PROM floating gate technology. It is designed to endure 10,000 erase/write cycles and has a data retention of 10 years. It is packaged in an 8-pin DIP and Small Outline packages. To be offered in a 3V version (CAT33C201).

### **FEATURES**

- Highly reliable CMOS floating gate technology
- Single 5V supply
- 64x16 or 128x8 user selectable serial memory
- Compatible with General Instruments ER5911
- Self timed programming cycle with Autoerase
- Word and chip erasable
- Operating range 0°C to 70°C [industrial temp. range available]
- 10,000 erase/write cycles
- 10 year data retention
- Power-up inadvertent write protection



#### PIN CONFIGURATION

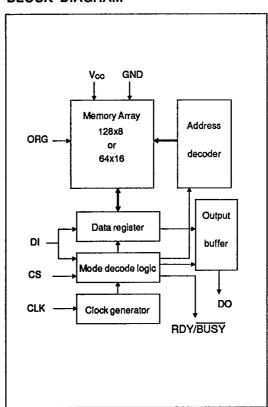


### PIN FUNCTIONS

Chip select
Clock input
Serial data input
Serial data output
+5V power supply
Status output
Ground
Memory organization

Note: When the ORG pin is connected to Vcc, the 64x16 organization is selected. When it is connected to ground, the 128x8 organization is selected. If the ORG pin is left unconnected, then an internal pullup device will select the 64x16 organization.

#### **BLOCK DIAGRAM**



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## **ABSOLUTE MAXIMUM RATINGS \***

Power supply (Vcc) ....+7 V 

\*Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and the functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### DC CHARACTERISTICS

 $(V_{CC} = +5V \pm 10\%, T_A = 0^{\circ}C \text{ to } 70^{\circ}C)$ 

Symbol	Parameter	Conditions		Limits		Unit
2,			Min.	Тур.	Max.	l
lcc1	Current consumption (operating)	DI=0.0V, SK=5.5V V <sub>CC</sub> =5.5V, CS = 5.5V DO unloaded			3	mA
lcc2	Current consumption (standby)	V <sub>CC</sub> = 5.5V, CS = 0 DI = 0, SK = 0			100	μA
ÎLI	Input leakage current	V <sub>IN</sub> = 5.5V			10	μΑ
lLO	Output leakage current	V <sub>OUT</sub> = 5.5V, CS = 0			10	μΑ
ViH	High level input voltage		2.0		Vcc +1	٧
VIL	Low level input voltage		-0.1		0.8	٧
Vон	High level output voltage	loн = -400μA	2.4	<u> </u>		٧
Vol	Low level output voltage	loL = 2.1mA			0.4	٧

### INSTRUCTION SET

Instruction	Start Bit	Opcode	Address		Data		Comments
		•	128 x 8	64 x 16	128 x 8	64 x 16	
READ	1	1000	A <sub>6</sub> - A <sub>0</sub>	A5 - A0			Read address An - Ao
PROGRAM	1	X100	A <sub>6</sub> - A <sub>0</sub>	A5 - A0	D <sub>7</sub> - D <sub>0</sub>	D <sub>15</sub> - D <sub>0</sub>	Program address A <sub>N</sub> - A <sub>0</sub>
PEN	1	0011	0000000	000000			Program enable
PDS	1	0000	0000000	000000			Program disable
ERAL	1	0010	0000000	000000			Erase all addresses
WRAL	1	0001	0000000	000000	D7 - D0	D <sub>15</sub> - D <sub>0</sub>	Write all addresses

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# **AC CHARACTERISTICS**

 $(V_{CC} = +5V \pm 10\%, T_A = 0^{\circ}C \text{ to } 70^{\circ}C)$ 

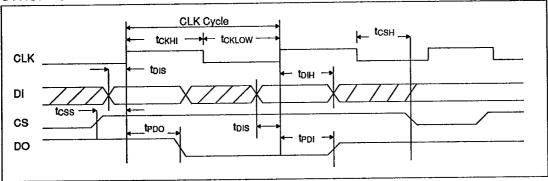
Symbol	Parameter	Conditions	Limits			Unit
			Min.	Тур.	Max.	<u> </u>
tcss	CS setup time		0.2			μs
tcsн	CS hold time		100			ns
tois	DI setup time	C <sub>L</sub> = 100pF	0.4			μs
фін	DI hold time	VoL = 0.8V, VoH = 2.0V	0.4			μs
tPD1	Output delay to 1	V <sub>IL</sub> = 0.45V, V <sub>IH</sub> = 2.4V			2	μѕ
tp:00	Output delay to 0				2	μs
tew	Erase/Write pulse width				10	ms
tskHI	Minimum SK high time		1			μs
tsklow	Minimum SK low time		1			μs
CKMAX	Maximum clock frequency		DC		250	kHz





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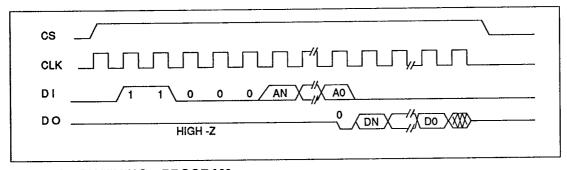
# SYNCHRONOUS TIMINGS



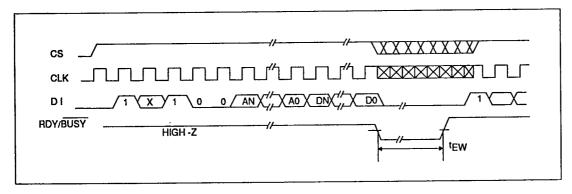
# INSTRUCTION TIMING <ORGANIZATION>

Organization	A <sub>N</sub> (or AN)	D <sub>N</sub> (or DN)
128 x 8	A <sub>6</sub>	D <sub>7</sub>
64 x 16	A <sub>5</sub>	D <sub>15</sub>

### **INSTRUCTION TIMING <READ>**



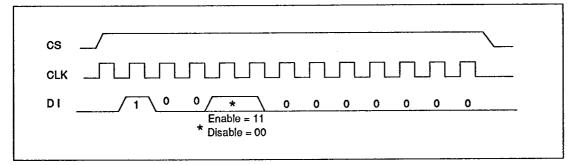
## **INSTRUCTION TIMING < PROGRAM>**



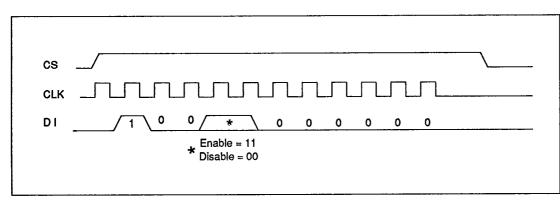
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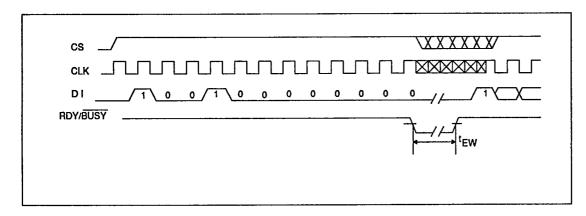
# INSTRUCTION TIMING <PEN, PDS 128 x 8 organization>



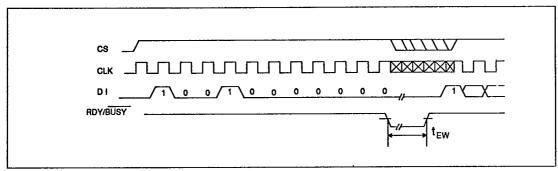
# INSTRUCTION TIMING <PEN, PDS 64 x 16 organization>



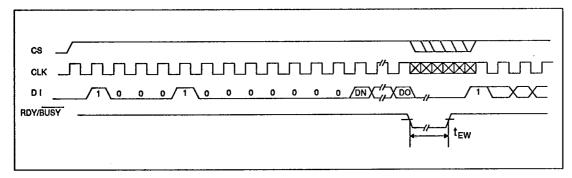
# INSTRUCTION TIMING <ERAL 128 x 8 organization>



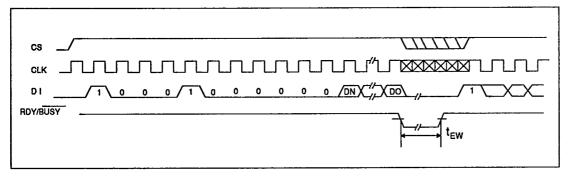
# INSTRUCTION TIMING <ERAL 64 x 16 organization>



## INSTRUCTION TIMING <WRAL 128 x 8 organization>



# INSTRUCTION TIMING <WRAL 64 x 16 organization>



## **DEVICE OPERATION**

The CAT59C11A is a 1024 bit nonvolatile memory intended for use with all standard controllers. The CAT59C11A can be organized as either 64 registers by 16 bits, or as 128 registers by 8 bits. Six 11 bit instructions (12 bit instruction in 128 by 8 organization) control the reading, writing, and erase operations of the device. The CAT59C11A operates on a single 5V supply and will generate on

chip the high voltage required during any programming operations. Instructions, addresses, and write data are clocked into the DI pin on the rising edge of the clock (CLK). The DO pin is normal in a high impedance state except when reading data from the device. The ready/busy status can be determined after a programming operation by polling the RDY/BUSY pin.

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The format for all instructions sent to the CAT59C11A is one logical "1" start bit, a 4 bit op code, a 6 bit address (7 bit address when organized as 128 X 8), and for write operations a 16 bit data field (8 bit data field when organized as 128 X 8).

#### READ

Upon receiving a READ command and address (clocked into the DI pin), the DO pin of the CAT59C11A will come out of the high impedance state. After sending 1 dummy zero bit the 16 bits (or 8 bits) of data located at the address location specified in the instruction will be shifted out. The data bit being shifted out will toggle on the rising edge of the CLK and is stable after the specified time delay (tpD1 and tpD0).

#### **ERASE/WRITE ENABLE AND DISABLE**

The CAT59C11A powers up in the programming disable state. Any programming after power-up or after a PDS (programming disable) instruction must first be preceded by the PEN (programming enable) instruction. Once programming is enabled, it will remain enabled until power to the device is removed or the PDS instruction is sent. The PDS instruction can be used to disable all the CAT59C11A's program and erase functions, and will prevent any accidental programming or erasing of the device. Data can be read normally from the

CAT59C11A regardless of the programming enable/disable status.

#### **PROGRAM**

After receiving a PROGRAM command, address, and the data, the RDY/BUSY pin goes low and the self clocking erase and data store cycle begins. The clocking of the CLK pin is not necessary after the device has entered the self clocking mode. The ready/busy status of the CAT59C11A can be determined by polling the RDY/BUSY pin.

#### **ERASE ALL**

Upon receiving an ERAL command, the RDY/BUSY pin goes low and the self clocking erase sequence starts. The clocking of the CLK pin is not necessary after the device has entered the self clocking mode. The ready/busy status of the CAT59C11A can be determined by polling the RDY/BUSY pin.



#### **WRITE ALL**

Upon receiving a WRAL command and data, the RDY/BUSY pin goes low and the self clocking data store cycle starts. The clocking of the CLK pin is not necessary after the device has entered the self clocking mode. The ready/busy status of the CAT59C11A can be determined by polling the RDY/BUSY pin. It IS necessary for all memory locations to be erased before the WRAL command is executed.