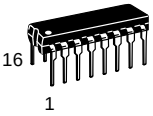
MC74HC195

4-Bit Universal Shift Register
High–Performance Silicon–Gate CMOS

The MC74HC195 is identical in pinout to the LS195. The device inputs are compatible with standard CMOS outputs, with pull up resistors, they are compatible with LSTTL outputs.

This static shift register features parallel load, serial load (shift right), hold, and reset modes of operation. These modes are tabulated in the Function Table, and further explanation can be found in the Pin Description section.

- Output Drive Capability: 10 LSTTL Loads
- Outputs Directly Interface to CMOS, NMOS, and TTL
- Operating Voltage Range: 2 to 6 V
- Low Input Current: 1 μA
- High Noise Immunity Characteristic of CMOS Devices
- In Compliance with the Requirements Defined by JEDEC Standard No. 7A
- Chip Complexity: 150 FETs or 37.5 Equivalent Gates

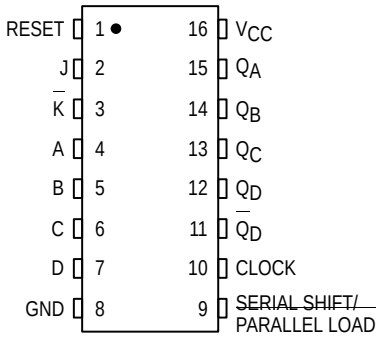


N SUFFIX
PLASTIC PACKAGE
CASE 648–08

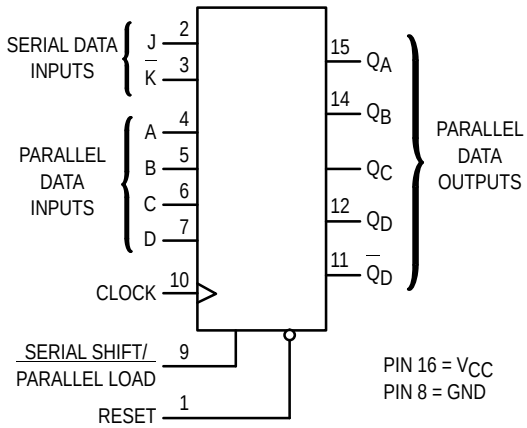
ORDERING INFORMATION

MC74HCXXXN Plastic

PIN ASSIGNMENT



LOGIC DIAGRAM



FUNCTION TABLE

Inputs									Outputs						
			Serial		Parallel										
Reset	Shift/ Load	Clock	J	K	A	B	C	D	Q_A	Q_B	Q_C	Q_D	$\overline{Q}_D$	Operating Mode	
L	X	X	X	X	X	X	X	X	L	L	L	L	H	Reset	
H	L	↑	X	X	a	b	c	d	a	b	c	d	d	Parallel Load	
H	H	L	X	X	X	X	X	X	No Change					Hold	
H	H	↑	L	H	X	X	X	X	Q_{A0}	Q_{A0}	Q_{Bn}	Q_{Cn}	$\overline{Q}_{Cn}$	Retain First Stage	Serial Shift
H	H	↑	L	L	X	X	X	X	L	Q_{An}	Q_{Bn}	Q_{Cn}	$\overline{Q}_{Cn}$	Reset First Stage	
H	H	↑	H	H	X	X	X	X	H	Q_{An}	Q_{Bn}	Q_{Cn}	$\overline{Q}_{Cn}$	Set First Stage	
H	H	↑	H	L	X	X	X	X	Q_{An}	Q_{An}	Q_{Bn}	Q_{Cn}	$\overline{Q}_{Cn}$	Toggle First Stage	

H = high level (steady state)
L = low level (steady state)
X = don't care
↑ = transition from low to high level.
a, b, c, d = the level of steady–state input at inputs A, B, C, or D, respectively.

Q_{A0} = the level of Q_A before the indicated steady–state input conditions were established.
Q_{An}, Q_{Bn}, Q_{Cn} = the level of Q_A, Q_B, or Q_C, respectively, before the most recent ↑ transition of the clock.

MAXIMUM RATINGS*

Symbol	Parameter	Value	Unit
V_{CC}	DC Supply Voltage (Referenced to GND)	– 0.5 to + 7.0	V
V_{in}	DC Input Voltage (Referenced to GND)	– 1.5 to V_{CC} + 1.5	V
V_{out}	DC Output Voltage (Referenced to GND)	– 0.5 to V_{CC} + 0.5	V
I_{in}	DC Input Current, per Pin	± 20	mA
I_{out}	DC Output Current, per Pin	± 25	mA
I_{CC}	DC Supply Current, V_{CC} and GND Pins	± 50	mA
P_D	Power Dissipation in Still Air Plastic DIP†	750	mW
T_{stg}	Storage Temperature	– 65 to + 150	°C
T_L	Lead Temperature, 1 mm from Case for 10 Seconds (Plastic DIP)	260	°C

This device contains protection circuitry to guard against damage due to high static voltages or electric fields. However, precautions must be taken to avoid applications of any voltage higher than maximum rated voltages to this high–impedance circuit. For proper operation, V_{in} and V_{out} should be constrained to the range GND ≤ (V_{in} or V_{out}) ≤ V_{CC}.

Unused inputs must always be tied to an appropriate logic voltage level (e.g., either GND or V_{CC}). Unused outputs must be left open.

* Maximum Ratings are those values beyond which damage to the device may occur.
Functional operation should be restricted to the Recommended Operating Conditions.
†Derating — Plastic DIP: – 10 mW/°C from 65° to 125°C
For high frequency or heavy load considerations, see Chapter 2 of the Motorola High–Speed CMOS Data Book (DL129/D).

RECOMMENDED OPERATING CONDITIONS

Symbol	Parameter		Min	Max	Unit
V_{CC}	DC Supply Voltage (Referenced to GND)		2.0	6.0	V
V_{in}, V_{out}	DC Input Voltage, Output Voltage (Referenced to GND)		0	V_{CC}	V
T_A	Operating Temperature, All Package Types		– 55	+ 125	°C
t_r, t_f	Input Rise and Fall Time (Figure 1)	V_{CC} = 2.0 V	0	1000	ns
		V_{CC} = 4.5 V	0	500	
		V_{CC} = 6.0 V	0	400	

DC ELECTRICAL CHARACTERISTICS (Voltages Referenced to GND)

Symbol	Parameter	Test Conditions	V_{CC} V	Guaranteed Limit			Unit
				– 55 to 25°C	≤ 85°C	≤ 125°C	
V_{IH}	Minimum High–Level Input Voltage	V_{out} = 0.1 V or V_{CC} – 0.1 V $\|I_{out}\|$ ≤ 20 μA	2.0 4.5 6.0	1.5 3.15 4.2	1.5 3.15 4.2	1.5 3.15 4.2	V
V_{IL}	Maximum Low–Level Input Voltage	V_{out} = 0.1 V or V_{CC} – 0.1 V $\|I_{out}\|$ ≤ 20 μA	2.0 4.5 6.0	0.3 0.9 1.2	0.3 0.9 1.2	0.3 0.9 1.2	V
V_{OH}	Minimum High–Level Output Voltage	V_{in} = V_{IH} or V_{IL} $\|I_{out}\|$ ≤ 20 μA	2.0 4.5 6.0	1.9 4.4 5.9	1.9 4.4 5.9	1.9 4.4 5.9	V
		V_{in} = V_{IH} or V_{IL} $\|I_{out}\|$ ≤ 4.0 mA $\|I_{out}\|$ ≤ 5.2 mA	4.5 6.0	3.98 5.48	3.84 5.34	3.70 5.20	
V_{OL}	Maximum Low–Level Output Voltage	V_{in} = V_{IH} or V_{IL} $\|I_{out}\|$ ≤ 20 μA	2.0 4.5 6.0	0.1 0.1 0.1	0.1 0.1 0.1	0.1 0.1 0.1	V
		V_{in} = V_{IH} or V_{IL} $\|I_{out}\|$ ≤ 4.0 mA $\|I_{out}\|$ ≤ 5.2 mA	4.5 6.0	0.26 0.26	0.33 0.33	0.40 0.40	
I_{in}	Maximum Input Leakage Current	V_{in} = V_{CC} or GND	6.0	± 0.1	± 1.0	± 1.0	μA
I_{CC}	Maximum Quiescent Supply Current (per Package)	V_{in} = V_{CC} or GND I_{out} = 0 μA	6.0	8	80	160	μA

NOTE: Information on typical parametric values can be found in Chapter 2 of the Motorola High–Speed CMOS Data Book (DL129/D).

AC ELECTRICAL CHARACTERISTICS (C_L = 50 pF, Input $t_r = t_f$ = 6 ns)

Symbol	Parameter	V_{CC} V	Guaranteed Limit			Unit
			– 55 to 25°C	≤ 85°C	≤ 125°C	
f_{max}	Maximum Clock Frequency (50% Duty Cycle) (Figures 1 and 5)	2.0 4.5 6.0	6.0 30 35	4.8 24 28	4.0 20 24	MHz
t_{PLH}, t_{PHL}	Maximum Propagation Delay, Clock to any Q or Q_D (Figures 1 and 5)	2.0 4.5 6.0	145 29 25	180 36 31	220 44 38	ns
t_{PLH}, t_{PHL}	Maximum Propagation Delay, Reset to any Q or $\overline{Q_D}$ (Figures 2 and 5)	2.0 4.5 6.0	150 30 26	190 38 33	225 45 38	ns
t_{TLH}, t_{THL}	Maximum Output Transition Time, Any Output (Figures 1 and 5)	2.0 4.5 6.0	75 15 13	95 19 16	110 22 19	ns
C_{in}	Maximum Input Capacitance	—	10	10	10	pF

NOTES:
1. For propagation delays with loads other than 50 pF, see Chapter 2 of the Motorola High–Speed CMOS Data Book (DL129/D).
2. Information on typical parametric values can be found in Chapter 2 of the Motorola High–Speed CMOS Data Book (DL129/D).

		Typical @ 25°C, V_{CC} = 5.0 V	
C_{PD}	Power Dissipation Capacitance (Per Package)*	95	pF

* Used to determine the no–load dynamic power consumption: $P_D = C_{PD} V_{CC}^2 f + I_{CC} V_{CC}$. For load considerations, see Chapter 2 of the Motorola High–Speed CMOS Data Book (DL129/D).

TIMING REQUIREMENTS (Input $t_r = t_f$ = 6 ns)

Symbol	Parameter	V_{CC} V	Guaranteed Limit			Unit
			– 55 to 25°C	≤ 85°C	≤ 125°C	
t_{su}	Minimum Setup Time, A, B, C, D, J, or K to Clock (Figure 3)	2.0 4.5 6.0	100 20 17	125 25 21	150 30 26	ns
t_{su}	Minimum Setup Time, Serial Shift/Parallel Load to Clock (Figure 4)	2.0 4.5 6.0	100 20 17	125 25 21	150 30 26	ns
t_h	Minimum Hold Time, Clock to A, B, C, D, J, or $\overline{K}$ (Figure 3)	2.0 4.5 6.0	3 3 3	3 3 3	3 3 3	ns
t_h	Minimum Hold Time, Clock to Serial Shift/Parallel Load (Figure 4)	2.0 4.5 6.0	3 3 3	3 3 3	3 3 3	ns
t_{rec}	Minimum Recovery Time, Reset Inactive to Clock (Figure 2)	2.0 4.5 6.0	5 5 5	5 5 5	5 5 5	ns
t_w	Minimum Pulse Width, Clock (Figure 1)	2.0 4.5 6.0	80 16 14	100 20 17	120 24 20	ns
t_w	Minimum Pulse Width, Reset (Figure 2)	2.0 4.5 6.0	80 16 14	100 20 17	120 24 20	ns
t_r, t_f	Maximum Input Rise and Fall Times (Figure 1)	2.0 4.5 6.0	1000 500 400	1000 500 400	1000 500 400	ns

NOTE: Information on typical parametric values can be found in Chapter 2 of the Motorola High–Speed CMOS Data Book (DL129/D).

PIN DESCRIPTION

DATA INPUTS

A, B, C, D (Pins 4, 5, 6, 7)

Parallel data inputs.

OUTPUTS

Q_A, Q_B, Q_C, Q_D, $\overline{Q}_D$ (Pins 15, 14, 13, 12, 11)

Parallel data outputs.

CONTROL INPUTS

Clock (Pin 10)

Clock input. The shift register is completely static, allowing Clock rates down to DC in a continuous or intermittent mode.

Serial Shift/Parallel Load (Pin 9)

Shift or load control. A low level applied to this pin allows data to be loaded from the parallel inputs. Data is loaded with the positive transition of the Clock input. A high level allows data to be shifted in the manner dictated by the J and K control inputs.

Reset (Pin 1)

A low level applied to this pin resets all stages and forces all outputs low.

J, $\overline{K}$ (Pins 2, 3)

Shift Control. With Serial Shift/Parallel Load high, J and $\overline{K}$ control the mode of operation, as illustrated in the Function Table.

J = L, $\overline{K}$ = H

With a positive transition of the Clock input, each bit is shifted to the right (in the direction Q_A toward Q_D) one stage and stage A maintains its previous state.

J = H, $\overline{K}$ = L

With a positive transition of the Clock input, each bit is shifted right (in the direction of Q_A toward Q_D) one stage and the Q_A output is inverted.

J = $\overline{K}$ = L

With a positive transition of the Clock input, each bit is shifted right (in the direction Q_A toward Q_D) one stage and a low is loaded into stage A.

J = $\overline{K}$ = H

With a positive transition of the Clock input, each bit is shifted right (in the direction Q_A toward Q_D) one stage and a high is loaded into stage A.

SWITCHING WAVEFORMS

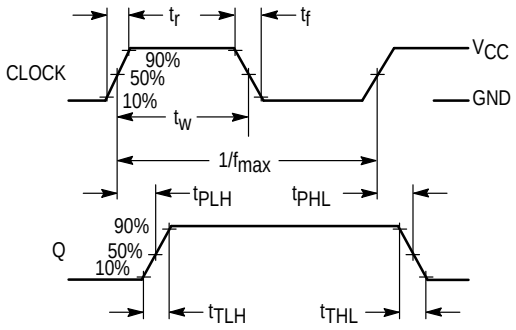


Figure 1.

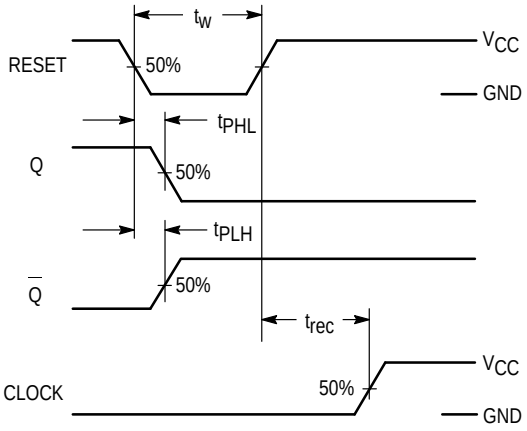


Figure 2.

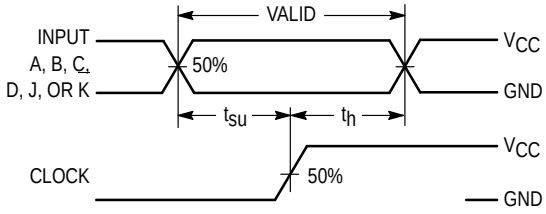


Figure 3.

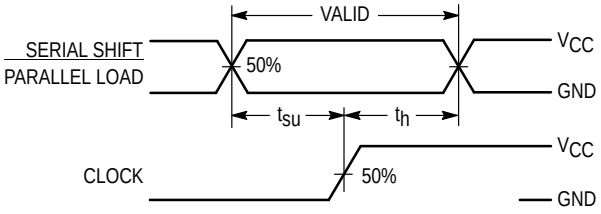
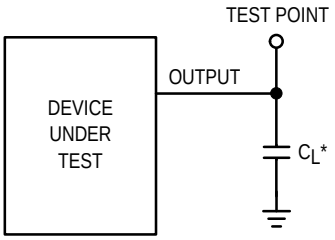


Figure 4.

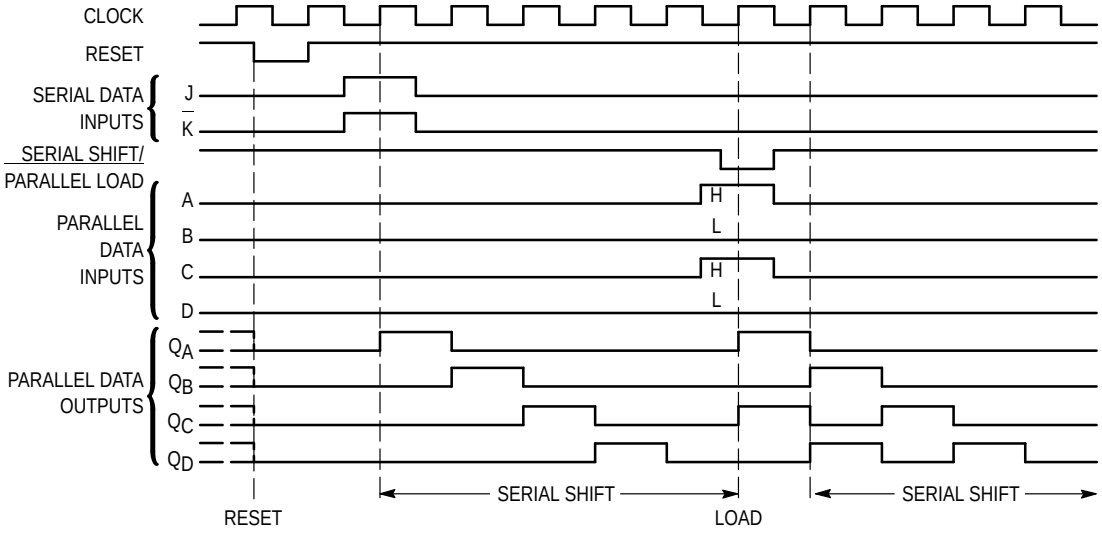
TEST CIRCUIT



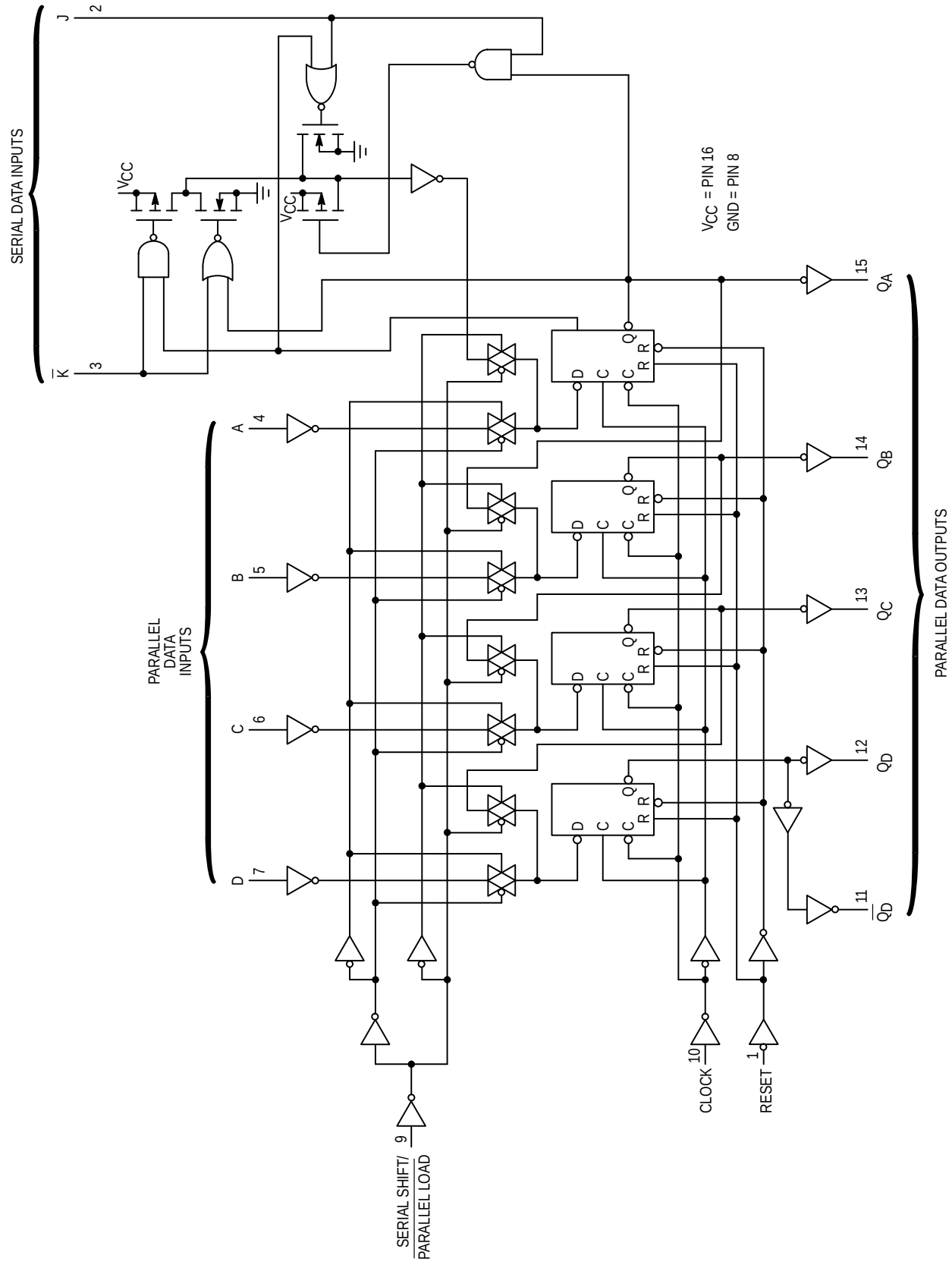
* Includes all probe and jig capacitance

Figure 5.

TIMING DIAGRAM

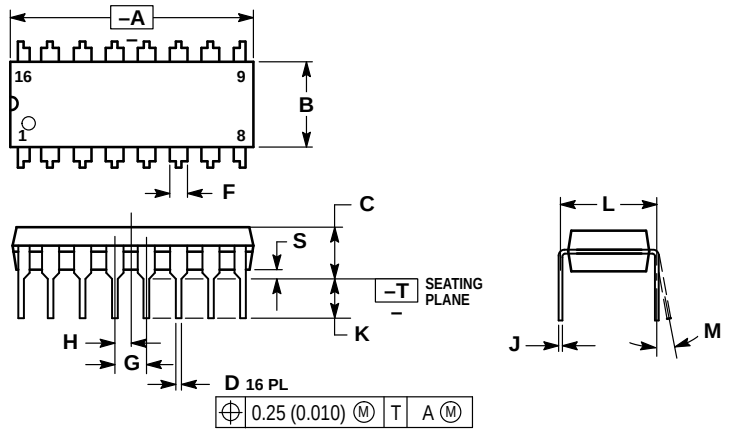


EXPANDED LOGIC DIAGRAM



OUTLINE DIMENSIONS

N SUFFIX
PLASTIC PACKAGE
CASE 648–08
ISSUE R



NOTES:
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: INCH.
3. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
4. DIMENSION B DOES NOT INCLUDE MOLD FLASH.
5. ROUNDED CORNERS OPTIONAL.

	INCHES		MILLIMETERS	
DIM	MIN	MAX	MIN	MAX
A	0.740	0.770	18.80	19.55
B	0.250	0.270	6.35	6.85
C	0.145	0.175	3.69	4.44
D	0.015	0.021	0.39	0.53
F	0.040	0.070	1.02	1.77
G	0.100 BSC		2.54 BSC	
H	0.050 BSC		1.27 BSC	
J	0.008	0.015	0.21	0.38
K	0.110	0.130	2.80	3.30
L	0.295	0.305	7.50	7.74
M	0°	10°	0°	10°
S	0.020	0.040	0.51	1.01

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