# PLL frequency synthesizer for tuners BU2621F

The BU2621F is a PLL frequency synthesizer designed for use in car stereos, high-fidelity audio systems, and CD radio cassettes. Featuring low power consumption, low superfluous radiation, and two separate frequency measurement counter systems, this chip is ideal for high-performance systems.

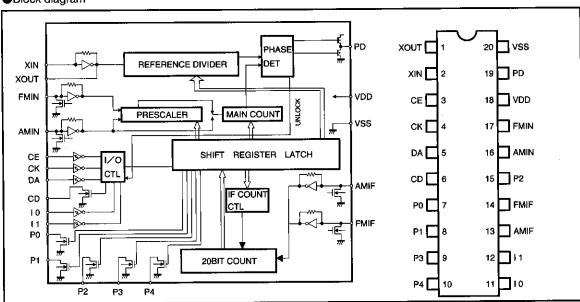
#### Applications

Car stereos, mini components, radio cassettes, receivers, and other frequency generating devices

#### Features

- 1) Built-in high-speed prescaler can divide 130MHz
- Low power-consumption (during operation: 6mA PLL OFF 300 μA Typ.)
- 3) Seven standard frequencies: 50kHz, 25kHz, 12.5kHz, 10kHz, 9kHz, 5kHz, and 1kHz.
- Two counter systems for intermediate frequency detection.
- 5) Unlock detection circuit.
- 6) Five output ports.
- 7) Two input ports.
- 8) Serial data input (CE.CK.DA)
- 9) Phase comparison output.

#### Block diagram



## ●Absolute maximum ratings (Ta = 25°C)

Parameter	Symbol	Limits	Unit	Conditions
Supply voltage	$V_{DD}$	-0.3~7.0	٧	VDD
Maximum input voltage 1	V <sub>IN1</sub>	-0.3~7.0	٧	CE, CK, DA, I <sub>0</sub> , I <sub>1</sub>
Maximum input voltage 2	V <sub>IN2</sub>	-0.3~V <sub>DD</sub> +0.3	٧	XIN, FMIN, AMIN, FMIF, AMIF, Io, I1
Maximum output voltage 1	Vouri	-0.3~10.0	٧	P <sub>0</sub> ,P <sub>1</sub> ,P <sub>2</sub> ,P <sub>3</sub> ,P <sub>4</sub> ,CD
Maximum output voltage 2	V <sub>OUT2</sub>	-0.3~V <sub>DD</sub> +0.3	٧	PD,XOUT
Maximum output current	Іоит	0~4.0	mA	P <sub>0</sub> ,P <sub>1</sub> ,P <sub>2</sub> ,P <sub>3</sub> ,P <sub>4</sub> ,CD
Power dissipation	Pd	* 450	mW	
Operating temperature	Topr	-40~85	°	
Storage temperature	Tstg	<b>−55∼125</b>	Ĉ	

<sup>\*</sup> Reduced by 4.5mW for each Increase in Ta of 1°C over 25°C.

## ●Recommended operating conditions (Ta = 25°C)

Parameter	Symbol	Min.	Тур.	Max.	Unit
Supply voltage	V <sub>DD</sub>	4.0	_	6.0	٧

## Pin description

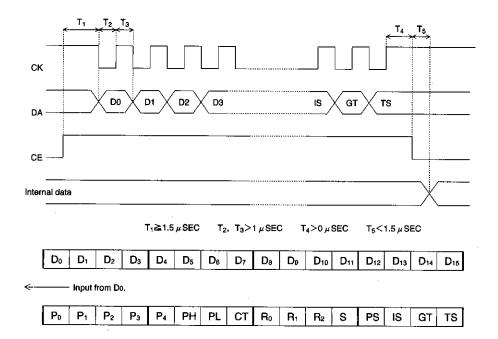
Pin No.	Symbol	Pin name	Function	1/0
1	XOUT	Crystal oscillation	For generation of standard frequency and internal clock.	OUT
2	XIN	terminal	Connected to 7.2 MHz crystal oscillator.	IN
3	CE	Chip enable	When CE is H, DA is synchronous with the rise of CK and	
4	CK	Clock signal	read to the internal shift register. DA is then latched at the timing of the fall of CE. Also, output data is output from the	IN
5	DA	Serial data	CD terminal synchronous to the rise of CK.	
6	CD	Count data	Frequency data and unlock data are output.	Nch open drain
7	PO			
8	P1	0.4	Control of the contro	
9	P3	Output port	Controlled on the basis of input data.	,
10	P4		,	
11	10		Selected on the basis of control data, then output to the	IN
12	11	Input port	CD terminal.	Schmidt input
13	AMIF	AMIF input	Intermediate frequency input for AM	IN
14	FMIF	FMIF input	Intermediate frequency input for FM	IN
15	P2	Output port	Controlled on the basis of input data.	Nch open drain
16	AMIN	AM input	Local input for AM	iN
17	FMIN	FM input	Local input for FM	IN
18	VDD	Power supply	Power supply, with 4.0V to 6.0V applied voltage.	
19	PD	Phase comparison output	High level when value obtained by dividing local output is	3-state
20	VSS	GROUND	higher than standard frequency. Low level when value is lower. High impedance when value is same.	

ullet Electrical characteristics (unless other specified, Ta = 25°C, VDD = 5.0V)

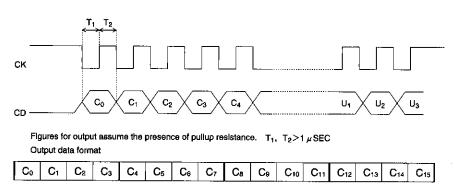
	· ·	· ·						
Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions		
Supply current	l <sub>DD1</sub>	_	6.0	10.0	mA	FM <sub>IN</sub> =130MHz,100mVrr	ns	
Quiescent circuit current	I <sub>DD2</sub>	_	0.3	1.0	mA	No input, PLL=OFF	· · · · · · · · · · · · · · · · · · ·	
"H" level input voltage	Vн	0.8V <sub>DD</sub>	_	_	٧	CE,CK,DA,I <sub>0</sub> ,I <sub>1</sub>		
"L" level input voltage	VIL	_	_	0.2V <sub>DD</sub>	٧	CE,CK,DA,I <sub>0</sub> ,I <sub>1</sub>		
"H" level input current 1	l <sub>iH1</sub>	_	_	1.0	μΑ	CE,CK,DA,I <sub>0</sub> ,I <sub>1</sub>	V <sub>IN</sub> =V <sub>DD</sub>	
"H" level input current 2	l <sub>IH2</sub>	[	0.3	-	μA	XIN	V <sub>IN</sub> =V <sub>DD</sub>	
"H" level input current 3	Іінэ		6.0		μА	FMIN,AMIN,FMIF,AMIF	V <sub>IN</sub> =V <sub>DD</sub>	
"L" level input current 1	I <sub>IL1</sub>	-1.0	_	_	μA	CE,CK,DA,I <sub>0</sub> ,I <sub>1</sub>	V <sub>IN</sub> =V <sub>SS</sub>	
"L" level input current 2	I <sub>IL2</sub>	<u>-</u>	-0.3	_	μΑ	XIN	V <sub>IN</sub> =V <sub>SS</sub>	
"L" level input current 3	liLa		-6.0		μΑ	FMIN,AMIN,FMIF,AMIF	V <sub>IN</sub> =V <sub>SS</sub>	
"L" level output voltage 1	V <sub>OL1</sub>		0.2	0.5	٧	P <sub>0</sub> ,P <sub>1</sub> ,P <sub>2</sub> ,P <sub>3</sub> ,P <sub>4</sub> ,CD	l <sub>0</sub> =1.0mA	
"OFF" level leak current 1	l <sub>OFF1</sub>	. –	_	1.0	μΑ	P <sub>0</sub> ,P <sub>1</sub> ,P <sub>2</sub> ,P <sub>3</sub> ,P <sub>4</sub> ,CD	V <sub>0</sub> =10V	
"L" level output voltage 2	Vol2	_	_	0.3	٧	FMIN,AMIN,FMIF,AMIF	I <sub>OUT</sub> =0.1mA	
"H" level output voltage	Vон	V <sub>DD</sub> -1.0	V <sub>DD</sub> -0.25	_	٧	PD	I <sub>OUT</sub> =-1.0mA	
"L" level output voltage	V <sub>OL4</sub>	_	0.15	1.0	V	PD	I <sub>OUT</sub> =1.0mA	
"OFF" level leak current 2	l <sub>OFF2</sub>			100	nA	PD	V <sub>OUT</sub> =V <sub>DD</sub>	
"OFF" level leak current 3	loff3	-100			nA	PD	V <sub>OUT</sub> =V <sub>SS</sub>	
Internal feedback resistor 1	R <sub>F1</sub>		10	-	МΩ	XIN		
Internal feedback resistor 2	R <sub>F2</sub>	_	500	_	kΩ	FMIN,AMIN,FMIF,AMIF		
Input frequency 1	F <sub>IN1</sub>	_	7.2	_	MHz	XIN,sine wave,C coupling	9	
Input frequency 2	F <sub>IN2</sub>	10	-	130	MHz	FMIN,sine wave,C coupl	ing V <sub>IN</sub> ≕50mVrms	
Input frequency 3	F <sub>IN3</sub>	0.5	_	30	MHz	AMIN,sine wave,C couplin	g V <sub>IN</sub> =70mVrms	
Input frequency 4	F <sub>iN4</sub>	0.4	-	16	MHz	FMIF,AMIF,sine wave,C α	ouplingV <sub>IN</sub> =70mVm:	
Input amplitude 1	V <sub>IN1</sub>	50	_	1.5	Vrms	FMIN,sine wave,C coupling		
Input amplitude 2	V <sub>IN2</sub>	70	_	1.5	Vrms	AMIN,FMIF,AMIF,sine w	ave,C coupling	
Minimum pulse width	TW		1.0		μs	CK,DA		
Input rise time	TR	_	-	500	ns	CE,CK,DA		
Input fall time	TF	_		500	ns	CE,CK,DA		

O Not designed for radiation resistance.

## ●Circuit operation Input data format



Output data format CE output is set to LO.



C16 C17 C18

- Input done from Co.

C<sub>19</sub> U<sub>0</sub>

U₁

U<sub>2</sub> U<sub>3</sub>

#### Explanation of the data

(1) Division data: For Do through D₁₅ (When S = 1, use D₄ through D₁₅.)

D <sub>0</sub>	D <sub>1</sub>	D <sub>2</sub>	Dз	D <sub>4</sub>	[) <sub>5</sub>	D <sub>6</sub>	D <sub>7</sub>	D <sub>8</sub>	De	D <sub>10</sub>	D <sub>11</sub>	D <sub>12</sub>	D <sub>13</sub>	D <sub>14</sub>	D <sub>15</sub>
Exam	Examples:														
Divid	ded fre	quenc	y = 11	06 (D)	÷2=5	53 (D):	=229(H	1) S=0							
1	0	0	1	0	1	0	0	0	1	0	0	0	0	0	0
Divi	ded fre	quenc	y = 11	07 (D)	=453	(H) S	=1, P	S=1							
1	1	0	0	1	0	1	0	0	0	1	0	0	0	0	0
Divided frequency = 926 (D) =39E (H) S=1, PS=0															
×	×	×	×	0	1	1	1	1	0	0	1	1	1	0	0

- (2) CT: Frequency measurement beginning data
  - 1: Begins measurement.
  - 0 : Resets internal counter, FMIF and AMIF go to pulldown.
- (3) Output port control data: Po, P1, P2, P3, P4
- (4) PL PH: Control of charge pump output

PH = 0, PL = 0 PLL operation

PH = 0, PL = 1PD LO level

PH = 1, PL = 0 PD HI level

PH = 1, PL = 1

PD LO level

(5) Ro, R1, R2, standard frequency data

	Data						
R₀	R₁	R₂	Standard frequency				
0	0	0	25kHz				
0	0	1	12.5kHz				
0	1	0	50kHz				
0	1	1	10kHz				
1	0	0	5kHz				
1	0	1	9kHz				
1	1	0	1kHz				
1	1	1	* PLL OFF				

- \* FMIN = pulldown, AMIN = pulldown, PD = high impedance
- (6) S:switch between FMIN and AMIN
  - 0:FMIN
  - 1: AMIN

When IF counter is in operation

- 0:FMIF
- 1: AMIF
- (7) PS: If this bit is set to ON while AMIN is selected, swallow counter division is possible.

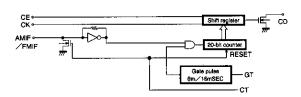
- (8) IS: Input port selection
  - 0:10 1:11
- (9) GT: Frequency measurement time and unlock detection ON/OFF

СТ	GT	Frequency measurement	Unlock detection	Data output
0	0	OFF	OFF	NG
0	1	OFF	ON	
1	0	ON Gate time = 8mSEC	ON	ОК
1	1	ON Gate time = 16mSEC	ON	

- (10) TS: Test data
- (0) is input

#### Frequency counter

(1) Structure



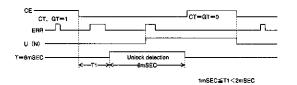
(2) How the frequency counter operates

When control data CT equals 1, the 20-bit counter and the amp go into operation. When CT equals 0, amp input goes to pulldown and the counter is reset. Measuring time (gate pulse) is selected (8mSEC/16mSEC) on the basis of control data GT. When control data CT equals 0, the counter is reset.

## (3) Explanation of output data

D0: LSB D<sub>19</sub>: MSB Unlock detection

When control data GT equals 1, or CT equals 1, the unlock detection circuit goes into operation for 8 mSEC. When CT equals 1, the unlock detection circuits stops operating before the frequency counter gate pulse is emitted. When CT equals 0, or GT equals 0, the unlock detection circuit is reset.

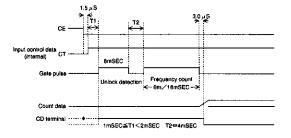


## Explanation of the output data

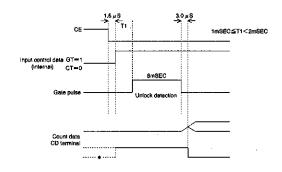
U0	U1	U2	U3					
0	0	0	0			ERR	<	1.1 μ SEC
1	0	0	0	1.1 <i>μ</i> SEC	<	ERR	<	2.2 μ SEC
1	1	0	0	$2.2\mu\mathrm{SEC}$	<	ERR	<	$3.3\mu\mathrm{SEC}$
1	1	1	0	$3.3\mu\mathrm{SEC}$	<	ERR	<	4.4 μ SEC
1	1	1	1	$4.4~\mu\mathrm{SEC}$	<	ERR		

# Frequency counter and unlock detection

(1) When CT = 1: Frequency count and unlock detection are carried out.

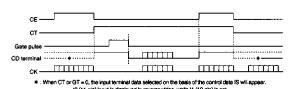


(2) When CT = 0 and GT = 1: Only unlock detection is carried out.

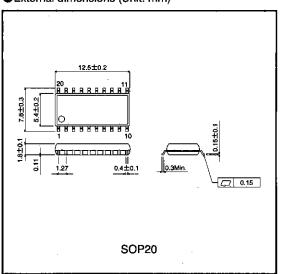


#### Explanation of CD terminal

When frequency measurement or unlock detection is finished, the CD terminal goes to LO to indicate that the count and unlock detection have finished. It also synchronizes with CK to output counter data. When the next data is input, it goes to HI.



#### ●External dimensions (Unit: mm)



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