# Read/Write Amplifier for FDD BH6625FS

The BH6625FS is a 4-mode read/write IC designed for floppy disk drives, and has an active filter that can be set according to transfer rate. Any of multiple write current settings can be selected, and inner edge/outer edge switching is done internally.

### Applications

Floppy disk drives (1MB, 1.6MB and 2MB)

#### Features

- 1) Internal active filter with multiple settings that can be selected for multiple Q and fo.
- 2) Time domain filter that is internally switchable according to transfer rate.
- 3) Any of multiple write current settings can be selected, and inner track / outer track switching is done internally.

●Absolute maximum ratings (unless otherwise noted, Ta=25℃)

Parameter	Symbol	Limits	Unit	
Supply voltage	Vcc	+7	V	
Operating temperature	Торя	0~+70	°C	
Storage temperature Tste		-55~+125	Ĵ	
Digital input voltage	VI	-0.5~Vcc+0.3	V	
RW pin voltage	VRW	+15	v	
LVS output voltage	VLVS	Vcc+0.3	v	
ED pin voltage	VER	Vcc+0.3	v	
Power dissipation	P⊳	650*	mW	

\* Reduced by 6.5mW for each Increase in Ta of 1°C over 25°C.

### Recommended operating conditions (Ta=25°C)

Parameter	Symbol	Min.	Тур.	Max.	Unit
Power supply voltage	Vcc	4.5	5.0	5.5	v

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Block diagram



(Note) Use a short pattern for Vcc, and keep the Impedance between Vcc and GND low by inserting a bypass capacitor.

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# Pin description and input/output circuit



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Pin No.	Name	Equivalent circuit	Function
21	XLVS		External low level voltage detection pin Open collector output when low level voltage is detected. Switches to low level when Vcc drops below the specified voltage
22	MONI		Preamplifier output and differentiator output monitoring Monitor is switched with pin 1 (WCC)
23	AGND		Analog ground
24	RCC		Filter (LPF, BPF) cutoff frequency and TDF 1st M/M pulse width setting resistor connection
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●Electrical characteristics (unless otherwise noted, Ta=25℃, Vcc=5V) Current consumption

Parameter	Symbol	Min.	Тур.	Max.	Unit		Conditions
Current consumption, Standby	ICCST	_	245	400	μA	*1	
Current consumption, Read	ICCR	_	28	42	mA	*1	
Current consumption, Write	ICCW		8.5	15	mA	*2	

\*1 RRCC=2.0 [kΩ] (XHD=H) \*2 RWCC=2.4 [kΩ] (When 2MB inner edge, XTR2=-high level, excluding /WR and IER)

Low level voltage detection circuit

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
Threshold voltage 1	VTH1+	—	4.05	4.30	V	When power supply voltage rises, internal LVS/write protect.
	VTH1-	3.60	3.85	4.10	V	When power supply voltage falls, internal LVS/write protect.
Threshold voltage 2	VTH2+	-	3.95	4.20	٧	When power supply voltage rises, external LVS
Threshold Voltage 2	VTH2-	3.50	3.75	4.00	V	When power supply voltage falls, external LVS
Hysteresis voltage	VH	50			mV	
Output voltage, low level	VOL			0.40	V	Vcc=2.5 [V] IOL=0.2 [mA]
Output leakage current	IOH	_	_	10	μA	

### **Recovery time**

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
POWER·SAVE→READ	TR2		-	500	μs	by XPS
READ→ERASE	TR3			6	μs	by XEG
READ→WRITE	TR4		<u> </u>	4	μs	by XWG
WRITE→READ	TR5E		_	20	μs	by XEG
	TR5W	-		160	μs	by XWG
SIDE0++SIDE1	TR6		_	40	μs	by XS1
1MB↔2MB	TR7	_	_	40	μs	by XHD

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### Preamplifier

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
Voltage gain (1)	GVD1	43	46	49	dB	f=125[kHz], VIN=2.5[mVp-p] (XTR1=L) (differential)
Voltage gain (2)	GVD2	46	49	52	dB	f=125[kHz], VIN=2.5[mVp-p] (XTR1=H) (differential)
SIDE0 ↔ SIDE1 crosstalk	GCTLK	50	_	_	dB	f=125[kHz], VIN=100[mVp-p] (differential) * 3
Differential input resistance	RID	—	3.3		kΩ	8.0 [k $\Omega$ ] input resistance, //5.5 [k $\Omega$ ] damping resistance
Input conversion noise voltage	VN		2.5	3.7	μ Vrms	f=500[Hz]~1[MHz]
Input sink current	ISINK		180		μA	
Differential input voltage amplitude tolerance (1)	VIN1		_	5.0	mVp-p	5% distortion (sinewave input) (XTR1=L)
Differential input voltage amplitude tolerance (2)	VIN2	_	-	3.5	mVp-p	5% distortion (sinewave input) (XTR1=H)
Common mode rejection ratio	CMRR	50	_		dB	f=125[kHz], VIN=100[mVp-p] *3
Power supply rejection ratio	PSRR	40	-		dB	f=250[kHz], VIN=100[mVp-p] *3

Preamplifier/LPF/differentiator (BPF)

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
Filter time constant accuracy	EFIL	-10	—	+10	%	*3
Total gain (preamplifier/ LPF/differentiator) (1)	GVDD1	40.5	44.5	48.5	dB	f=250[kHz], VIN=2.5[mVp-p] (differential) (2MB, XTR1=L, FILC=H)
Total gain (preamplifier/ LPF/differentiator) (2)	GVDD2	43.5	47.5	51.5	dB	f=250[kHz], VIN=2.5[mVp-p] (differential) (2MB, XTR1=H, FILC=H)
Differentiator output peaking frequency setting range	fo	0.1	_	0.5	MHz	Defined according to typical value in the settings

\*3 RRCC=2.0 [kΩ] (XHD=L, XTR1=H, F2=L, FILC=H)

Comparator and pulse shaper

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
TDF M/M pulse width accuracy (1)	TDF1	-10	_	+10	%	XHD=H, F2=L (Typ.: 2470[ns]) f=62.5[kHz]~125[kHz] *4
TDF M/M pulse width accuracy (2)	TDF2	-10	-	+10	%	XHD=H, F2=H (Typ.:2040[ns]) f=62.5[kHz]~125[kHz] *4
TDF M/M pulse width accuracy (3)	TDF3	-10	_	+10	%	XHD=L, F2=H/L (Typ.:1230[ns]) f=125[kHz]~250[kHz] *4
RD pulse width	TRD	270	400	530	ns	Judgment level 1.5 [V]
Rise time	TTLH		-	70	ns	Rise time till 0.4 [V] - 2.0 [V]
Fall time	TTHL			70	ns	Fall time till 2.0 [V] - 0.4 [V]
Peak shif	P. S.	-	_	1.0	%	f=250[kHz], VIN=1[mVp-p] (differential)
Output "L" level voltage	VOL			0.5	V	
Output "H" level voltage	VOH	2.7	_		V	Rise level at 0.4 [V] to 70 [ns]

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### Write circuit

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
Write current adjust ment range	IWR	2.0	-	20	mA0-p	
Write current accuracy	ACIW	-7.0	_	+7.0	%	*5
Write current pairability	∆IWR	-1.0	_	+1.0	%	RWCC=2.4[kΩ]
Write current supply voltage dependency	PSIW	-4.0	-0.8	+3.0	%/V	RWCC= $2.4[k\Omega]$
Output saturation voltage	VSATRW	-	0.4	1.0	V	IWR=12[mA]
Off-state leakage current	ILKRW1	_	<u> </u>	20	μA	Unselected side
	ILKRW2	_	_	50	μA	Selected side
Minimum write data pulse width	TWD	70	_	_	ns	
Write current inner track/ outer track ratio precision	ACIWTR	±10× (I	Ratio of inner edge	to outer edge)	%	*6

\*5 RWCC=2.4 [kΩ] , adapted for desiredsetting of XTR1, XTR2
\*6 Error in setting ratio (reference: XTR1=L, XTR2=L)

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### Erase output

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
Erase current adjustment range	IER	_	-	40	mA	
Output saturation voltage	VSATER	_	0.2	0.6	v	IER=40[mA]
Output leakage current	IOH	-	-	10	μA	OFF, ED0 = ED1 = Vcc

### Logic input

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
Input voltage, high level	VIH	2.0	-	_	v	Excluding FILC
Input voltage, low level	VIL			0.8	V	Excluding FILC
Input voltage hysteresis	VH	0.15			v	Applies to XWD, XWG, XEG, XS1
Input current, low level	IIL1	_	50	100	μA	Vcc=5[V] VIL=GND Applies to XWG, XEG, XHD
	VIH	4.2		_	V	Applies to FILC
	VIM	2.0	2.5	3.0	V	Applies to FILC
Tri-state interface	VIL	-	—	0.8	V	Applies to FILC
	IIH	_	50	100	μA	Vcc = 5[V], VIH = 5[V], applies to FILC
	IIL		50	100	μA	Vcc = 5[V], VIL = 0[V], applies to FILC

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### Read characteristics

Density				1MB				1.6MB		2MB	
Transfer rate			FILC	250[kbps]		300[kbps]		500[kbps]		500[kbps]	
Input		XHD	NO CARE	HI		н		LOW		LOW	
	Mode	F2	NO CARE	LOW		HI		н		LOW	
	Track	XTR1 (XSWF)	NO CARE	Outer track LOW	Inner track HI	Outer track LOW	Inner track HI	Outer track	Inner track HI	Outer track LOW	Inner track Hl
Output	Filter	fo [kHz] Characteristic * 1	Н	144	162	171	192	324	422	384	358(C)
			OPEN	167	182	201	216	309	400	336	361 (B)
			LOW	139	162	165	192	301	384	350	361 (B)
	TDF	[nSEC]	NO CARE	2470		2040		1230		1230	

Note) \* 1 (B) Chebyshev characteristics. (C) All are Butterworth characteristics except 2MB inner edges with high-ripple Chebyshev characteristics. (However RRCC=2.0 [kΩ] )

Total filter peak frequency setting

 $f_0 = a / (RRCC [k\Omega] + 0.09) [kHz]$ 

FILC	"H"	"M"	"L"	
a =	300	353	290	250 [kbps] outer track
	339	380	339	250 [kbps] inner track
	357	420	345	300 [kbps] outer track
	401	451	401	300 [kbps] inner track
	677	646	629	500 [kbps] outer track (when F2 = H)
	882	836	732	500 [kbps] inner track (when F2 = H)
	803	702	732	500 [kbps] outer track (when $F2 = L$ )
	748	754	←	500 [kbps] inner track (when F2 = L)

TDF time constant setting

250 [kbps] : T = 940 × RRCC [k $\Omega$ ] +590 [ns] 300 [kbps] : T = 745 × RRCC [k $\Omega$ ] +550 [ns] 500 [kbps] : T = 377 × RRCC [k $\Omega$ ] +476 [ns]

### OWrite current switching ratio

	Track	Outer edge <			> Inner edge	
	XTR1	L.	-	н		
	XTR2	L	Н	L	Н	
	2MB	0.450	0.400	0.350	0.300	
sity	1.6MB	0.500	0.450	0.400	0.350	
Density	1MB (250kbps)	0.933	0.833	0.766	0.677	
	1MB (300kbps)	1.000	0.900	0.800	0.700	

Write current setting

$$lwr = \frac{24.0}{RWCC [k\Omega]} [mA]$$

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#### Measurement circuit



Fig. 2

### Circuit operation

#### (1) Read

The input signal from the head coils from each side of the disc is amplified by the preamplifier and then differentiated. The filter time constant can be set externally. After differentiation, the differential output is input to the comparator. The time domain filter detects zero cross, and the output is converted to read data. The monostable multivibrator width can be set externally, while the read data pulse width is a constant 400ns.

# (2) Write

Input write data are converted to toggle movements by the internal flip-flops, operating the write driver. The write driver current is supplied by the write current generator, but the externally set current can be controlled according to density and by selecting inner track/outer track

(3) Erase

An open collector output pin is used, and the erase current is set with a resistor between it and the head. (4) Power supply

When the low level voltage detector detects a drop in the supply voltage, writing and erasing are prohibited.

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### Operation notes

(1) Use a short pattern for Vcc, and a sufficiently wide AGND and DGND. Keep the impedance between Vcc and GND low by inserting a bypass capacitor.

(2) Use a pattern that will minimize interference between digital signals and the head.

### Electrical characteristic curves





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