**Datum inc** Handbook of Time Code Formats



### THE COMPANY

From its inception in 1968, Datum has been involved in the highly specialized field of precision timing instrumentation. Today, the company designs and manufactures the most comprehensive array of time and frequency products in the industry. Our customers include most agencies of the U.S. Government as well as commercial and governmental entities throughout the western world. Ranging from miniature displays to complete range timing systems, Datum's products include off-the-shelf equipment as well as customized instrumentation tailored to specific customer requirements. Applications are as diverse as deep space exploration programs, medical research and vehicle test operations.

Datum's technical management staff is committed to ongoing product development. As new technologies evolve, our designs are evaluated and, when appropriate, upgraded to reflect the newest innovations.

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### FOREWORD

The Handbook of Time Code Formats is provided as a reference for timing instrumentation users. It contains a compilation of the time code formats most commonly employed by industry and U.S. Government agencies at the time of printing. In addition, the handbook contains brief discussions of time definitions, standard time broadcasts, methods of time determination and time error vs. accuracy reference material.

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#### INTRODUCTION

The use of coded timing signals to assist in the correlation of data began to take on widespread importance in the early 1950's. Timing signals were used for the correlation of data recorded on oscillographs, strip charts, printers, magnetic tapes and film.

The instrumentation requirements of the nation's missile and space programs were the forces behind the development of Timing Instrumentation and Time Code Formats. In the mad ICBM-weapon-systems rush and in the stampede into space, the development of systematic, efficient timing techniques was neglected. The use, definition and application of Time Code Formats was completely arbitrary and left to the individual ingenuity of each agency and each design engineer.

The evolution of the hundreds of Time Code Formats in use in the early 60's has resulted in more general usage of standardized formats, some of which are described on the following pages. Other formats have been abandoned as programs were completed or have died due to non-use. The Inter-Range Instrumentation Group (IRIG) was responsible for standardization of Time Code Formats and timing techniques. This standardization has resulted in more widespread use of Timing equipment and Timing techniques in such commercial activities as air traffic control, medical instrumentation, law enforcement, public utility, etc.

Information contained in this book has been gathered from IRIG, Hewlett-Packard and NBS standard publications.

#### SELECTION AND USE OF TIME CODE FORMATS

Coded time signals, commonly called "Time Code Formats", some of which are contained in this Handbook, are primarily used to provide correlation of multiple data sources and multiple data points during the monitoring or recording of various types of data. Precise time, related to world-wide time scales, is of critical importance in monitoring spaceship launching and tracking activities. Time intervals, rather than world-wide time, are important in monitoring processes: recording measurements and performance for weapon systems testing, flight testing, medical research, etc. Time, when recorded with data, serves as a convenient means of correlating various types of data recorded on different medias. Time also becomes a convenient reference for data retrieval should analysis of a recording be desired in the future.

Selecting a Time Code Format involves evaluation of the accuracy and data resolution being recorded, as well as an evaluation of the specific recording media. The bandwidth of the recording device governs the rate of the Time Code Format and, therefore, its resolution. The accuracy of the time and the Time Code Format depends primarily on the source of the Format and its relationship to world-wide time or on the accuracy of its individual frequency sources (refer to Appendix). Thus, various time codes are defined at different rates and different resolutions.

Referring to the IRIG standards, the Time Code Formats defined are established to support such high-speed data acquisition as camera instrumentation, as well as such very slow-speed data acquisition required for oscillographs or strip chart recorders.

When the Time Code Format is to be transmitted or when the specific recording device requires signal conditioning, additional characteristics are usually incorporated. Most common is the addition of a sine wave carrier, amplitudemodulated by the Time Code Format. This permits the signal to be conveniently transmitted by means of telephone communications or perhaps by means of being recorded on lower-bandwidth magnetic tape recorders.

#### ABBREVIATIONS

- PDM PULSE DURATION MODULATION
- **PWM** PULSE WIDTH MODULATION
- TCW TIME CODE WORD
- TOD TIME OF DAY
- **Hz** An abbreviation for HERTZ. The derived unit of frequency (cycles per second).
- kHz KILOHERTZ (1000 HERTZ)
- ppm PULSES PER MINUTE
- pps PULSES PER SECOND
- ms MILLISECOND (0.001 second)
- μs MICROSECOND (0.000001 second)
- fph FRAMES PER HOUR
- fpm FRAMES PER MINUTE
- fps FRAMES PER SECOND
- UTC UNIVERSAL TIME COORDINATED. (The U.S. Naval Observatory is responsible for maintaining the reference for time and time interval for the Department of Defense per DOD Directive 5160.51, 1 Feb. 1965.)
- BCD BINARY CODED DECIMAL
- CF CONTROL FUNCTION
- SBS STRAIGHT BINARY SECONDS
- **STOD** SECONDS TIME OF DAY
- BIT BINARY DIGIT
- LEAST SIGNIFICANT BIT
- MSB MOST SIGNIFICANT BIT
- PAM PULSE AMPLITUDE MODULATION
- PWC PULSE WIDTH CODED

### GLOSSARY OF TERMS

| ACCURACY (CODE)           | The correctness of CODE<br>DIGIT WEIGHTING   | POSITION IDENTIFIER     | An ELEMENT denoting the<br>position of a portion or all of   |  |
|---------------------------|--|-------------------------|--|--|
| BINARY NUMBER<br>SYSTEM   | A number system which uses<br>two symbols, usually denoted<br>by "0" and "1", and has two<br>as its base. Not to be con-<br>fused with CODE DIGIT<br>WEIGHTING | PULSE                   | a CODE WORD<br>A variation of a quantity<br>whose value is normally con-<br>stant; the variation is charac-<br>terized by a "rise" and a<br>"decay" and has a finite<br>"duration" |  |
| CODE DIGIT                | One of a definite set of ELE-<br>MENTS, the set comprising a<br>CODE WORD. Each code<br>digit is individually and<br>numerically weighted                      | REFERENCE MARKER        | A periodic combination of<br>ELEMENTS which establishes<br>that instant of time defined by<br>the CODE WORD  |  |
| CODE DIGIT<br>WEIGHTING   | The numerical value assigned<br>to a particular CODE DIGIT<br>position   | SECOND<br>TIME INTERVAL | The basic unit of TIME<br>Time interval indicates the<br>duration of a segment of time   |  |
| CODE WORD (TIME)          | A definite set of ELEMENTS<br>which collectively convey in-<br>formation defining an instant<br>of time  | STANDARD REFERENCE      | without reference to when the<br>time interval begins and ends<br>The basic repetition rate<br>chosen as the common time   |  |
| ELEMENT                   | One of the parts of which any time signal is composed  | THE .                   | reference for all other IN-<br>STRUMENTATION TIMING.   |  |
| FORMAT                    | The arrangement of ELE-<br>MENTS within a group  | TIME                    | (usually 1 pps)<br>Time signifies epoch; that is,  |  |
| INDEX COUNT               | The number which identifies<br>a specific ELEMENT position<br>with respect to a REFER-<br>ENCE MARKER  |                         | the designation of an instant<br>on a selected time scale and<br>is used in the sense of TIME<br>of day  |  |
| INSTRUMENTATION<br>TIMING | A parameter serving as the<br>fundamental independent var-<br>iable in terms of which data<br>may be correlated  | TIME CODE ZERO (Tco)    | The instant of time defined<br>by all CODE WORDS as zero.<br>It is derived from and coinci-<br>dent with an ELEMENT of   |  |
| INDEX MARKERS             | Uncoded periodic interpolat-<br>ing ELEMENTS   |                         | the STANDARD REFERENCE   |  |
| ON TIME                   | The state of any ELEMENT<br>being coincident with the<br>STANDARD REFERENCE<br>TIME  | TIME FRAME              | The TIME INTERVAL between<br>consecutive REFERENCE<br>MARKERS containing all ELE-<br>MENTS of a time FORMAT.   |  |

#### INTER-RANGE INSTRUMENTATION GROUP STANDARD INSTRUMENTATION TIMING FORMATS

#### General

In the early 1950s it became apparent that efficient interchange of test data between the various test ranges and contractor, university and Government laboratories would require time code standardization. This task of standardization was assigned to the Tele-Communications Working Group (TCWG) of the IRIG in October of 1956. The original IRIG standards were accepted by the Steering Committee in 1960. IRIG publication No 104-60 defined the original IRIG Formats. This document was later revised and then reprinted in August, 1970 as Document No. 104-70. The current Document is No. 200-70 (it differs from No. 104-70 in title page only). More information regarding the efforts of IRIG and the availability of IRIG standards can be gained by contacting the Secretariat, Range Commander's Council, White Sands Missile Range, New Mexico 88002. More detail concerning the individual range synchronization and instrumentation timing can be obtained by referring to IRIG Document 103-59, "Instrumentation Timing Systems" brochure.

#### **Description of Formats**

In the IRIG family, individual Time Code Formats are alphabetically designated 'A', 'B', 'D', 'E', 'G', and 'H'. These are defined in IRIG Document No. 104-70. IRIG 'C', originally defined in IRIG Document No. 104-60, has been eliminated and effectively replaced by IRIG 'H'. Various signal forms are described in the IRIG Document. Identification numbers have been developed in accordance with the following procedure.

| Rate Designation:   | A) 1000 pps<br>B) 100 pps<br>D) 1 ppm<br>E) 10 pps<br>G) 10000 pps<br>H) 1 pps   |
|---------------------|--|
| Form Designation:   | <ol> <li>Pulse, width-coded</li> <li>Sine wave, amplitude-modulated</li> </ol>   |
| Carrier/Resolution: | <ul> <li>0) No carrier/index count interval</li> <li>1) 100 Hz/10 ms</li> <li>2) 1000 Hz/1 ms</li> <li>3) 10000 Hz/0.1 ms</li> <li>4) 100000 Hz/0.01 ms</li> </ul> |
| Coded Expressions:  | 0) BCD, CF, SBS<br>1) BCD, CF<br>2) BCD<br>3) BCD, SBS   |
|                     | ignals are recognized to be standard<br>with the IRIG standard:  |

| Format A | Format B | Format D | Format E | Format G | Format H |  |  |
|----------|----------|----------|----------|----------|----------|--|--|
| A000     | B000     | D001     | E001     | G001     | H001     |  |  |
| A003     | B003     | D002     | E002     | G002     | H002     |  |  |
| A130     | B120     | D111     | E111     | G141     | H111     |  |  |
| A133     | B123     | D112     | E112     | G142     | H112     |  |  |
|          |          | D121     | E121     |          | H121     |  |  |
|          |          | D122     | E122     |          | H122     |  |  |
|          |          |          |          |          |          |  |  |



#### IRIG FORMAT 'A' - GENERAL

- 1. TIME FRAME: 0.1 second
- 2. CODE DIGIT WEIGHTING OPTIONS: BCD, SB or both:
- a. Binary Coded Decimal Time-of-Year CODE WORD 34 binary digits.
  - (1) Seconds, minutes, hours, days and 0.1 seconds. Recycles yearly.
- b. Straight Binary Time-of-Day CODE WORD 17 binary digits.

(1) Seconds only.

Recycles each 24 hours. (86399)

#### 3. CODE WORD STRUCTURE:

- a. **BCD.** Word begins at INDEX COUNT 1. Binary-coded elements occur between POSITION IDENTIFIER ELE-MENTS (seven for seconds; seven for minutes; six for hours; ten for days; four for 0.1 seconds) until the CODE WORD is complete. A POSITION IDENTIFIER occurs between decimal digits in each group to provide separation for visual resolution.
- b. **SB.** Word begins at INDEX COUNT 80. Seventeen binary-coded elements occur, with a POSITION IDEN-TIFIER between the 9th and 10th binary-coded elements.
- **4. LEAST SIGNIFICANT DIGIT:** Occurs first, except for fractional seconds information, which occurs following the day-of-year information.
- 5. ELEMENT RATES AVAILABLE:
  - a. 1000 per second (basic Element rate)
  - b. 100 per second (POSITION IDENTIFIER rate)
  - c. 10 per second (Frame rate)

#### 6. ELEMENT IDENTIFICATION:

- a. "On-Time" reference point for each Element is its leading edge.
- b. INDEX MARKER duration: 0.2 milliseconds (Binary Zero or uncoded Element)
- c. CODE DIGIT duration: 0.5 milliseconds (Binary one)
- d. POSITION IDENTIFIER: 0.8 milliseconds
- e. REFERENCE MARKER: Two consecutive POSITION IDENTIFIERS.

(The "on-time" point, to which the CODE WORD refers, is the leading edge of the second POSITION IDENTIFIER.)

- RESOLUTION: 1 millisecond (unmodulated); 0.1 millisecond (modulated).
- 8. CARRIER FREQUENCY: 10 kHz when modulated.



- 1. TIME FRAME: 1.0 second.
- 2. CODE DIGIT WEIGHTING OPTIONS: BCD, SB or both:
- a. Binary Coded Decimal Time-of-Year CODE WORD 30 binary digits.

(1) Seconds, minutes, hours and days. Recycles yearly.

b. Straight Binary Time-of-Day CODE WORD — 17 binary digits.

(1) Seconds only. Recycles each 24 hours. (86399)

#### 3. CODE WORD STRUCTURE:

- a. BCD: Word begins at INDEX COUNT 1. Binary-coded elements occur between POSITION IDENTIFIER ELE-MENTS (seven for seconds, seven for minutes; six for hours; ten for days) until the CODE WORD is complete. A POSITION IDENTIFIER occurs between decimal digits in each group to provide separation for visual resolution.
- b. **SB:** Word begins at INDEX COUNT 80. Seventeen binary-coded elements occur with a POSITION IDEN-TIFIER between the 9th and 10th binary-coded elements.
- 4. LEAST SIGNIFICANT DIGIT: occurs first.

#### 5. ELEMENT RATES AVAILABLE:

- a. 100 per second (basic Element rate)
- b. 10 per second (POSITIVE IDENTIFIER Rate)
- c. 1 per second (Frame Rate)

#### 6. ELEMENT IDENTIFICATION:

- a. "On-Time" reference point for each Element is its leading edge.
- b. INDEX MARKER duration: 2 milliseconds (Binary zero or uncoded Element)
- c. CODE DIGIT duration: 5 milliseconds (Binary one)
- d. POSITION IDENTIFIER duration: 8 milliseconds
- e. REFERENCE MARKER one per second: Two consecutive POSITION IDENTIFIERS.
- (The "On-Time" point, to which the CODE WORD refers, is the leading edge of the second POSITION IDENTIFIER.)
- RESOLUTION: 10 milliseconds (unmodulated); 1 millisecond (modulated).
- 8. CARRIER FREQUENCY: 1 kHz when modulated.



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#### IRIG FORMAT 'D' - GENERAL

#### 1. TIME FRAME: 1 hour

 CODE DIGIT WEIGHTING OPTIONS: Binary Coded Decimal Time-of-Year CODE WORD only – 16 binary digits.

a. Hours and days. Recycles yearly.

- 3. CODE WORD STRUCTURE:
  - a. **BCD:** Word begins at INDEX COUNT 20. Binary-coded elements occur between POSITION IDENTIFIER ELE-MENTS (six for hours; ten for days) until the CODE WORD is complete. A POSITION IDENTIFIER occurs between decimal digits in each group to provide separation for visual resolution.
- 4. LEAST SIGNIFICANT DIGIT: Occurs first.

#### 5. ELEMENT RATES AVAILABLE:

- a. 1 per minute (basic Element rate)
- b. 1 per 10 minutes (POSITION IDENTIFIER Rate)
- c. 1 per hour (Frame Rate)

#### 6. ELEMENT IDENTIFICATION:

- a. "On-Time" reference point for each Element is its leading edge.
- b. INDEX MARKER duration: 12 seconds (Binary zero or uncoded Element)
- c. CODE DIGIT duration: 30 seconds (Binary one)
- d. POSITION IDENTIFIER (one per 10 minutes) duration:
   48 seconds (Refers to the leading edge of the succeeding Element).
- e. REFERENCE MARKER (one per hour): Two consecutive POSITION IDENTIFIERS.

(The "On-Time" point, to which the CODE WORD refers, is the leading edge of the second POSITION IDENTIFIER.)

- RESOLUTION: 1 minute (unmodulated); 0.01 seconds (modulated 100 Hz); 0.001 seconds (modulated 1000 Hz)
- 8. CARRIER FREQUENCY: 100 or 1000 Hz when modulated.



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#### IRIG FORMAT 'E' - GENERAL

- 1. TIME FRAME: 10 seconds
- CODE DIGIT WEIGHTING: BCD: Time-of-Year CODE WORD – 26 Binary Digits. Seconds, minutes, hours and days; recycles yearly.
- 3. CODE WORD STRUCTURE:

**BCD:** Word begins at INDEX COUNT 6. Binary-coded Elements occur between POSITION IDENTIFIER ELE-MENTS (three for seconds, seven for minutes; six for hours, ten for days) until the CODE WORD is complete. A POSITION IDENTIFIER occurs between decimal digits in each group to provide separation for visual resolution.

4. LEAST SIGNIFICANT DIGIT: Occurs first.

#### 5. ELEMENT RATES AVAILABLE:

- a. 10 per second (basic Element rate)
- b. 1 per second (POSITION IDENTIFIER Rate)
- c. 0.1 per second (Frame Rate)

#### 6. ELEMENT IDENTIFICATION:

- a. "On-Time" reference point for each Element is its leading edge.
- b. INDEX MARKER duration: 20 milliseconds (Binary zero or uncoded Element)
- c. CODE DIGIT duration: 50 milliseconds (Binary one)
- d. POSITION IDENTIFIER duration: 80 milliseconds (Refers to the leading edge of the succeeding Element).
- e. REFERENCE MARKER (one per 10 seconds): Two consecutive POSITION IDENTIFIERS.

(The "On-Time" point, to which the CODE WORD refers, is the leading edge of the second POSITION IDENTIFIER.)

7. RESOLUTION: 100 milliseconds (unmodulated).

0.01 seconds (modulated 100 Hz); 0.001 seconds (modulated 1 kHz).

8. CARRIER FREQUENCY: 1 kHz or 100 Hz when modulated.



#### IRIG FORMAT 'G' - GENERAL

- 1. TIME FRAME: 0.01 second.
- CODE DIGIT WEIGHTING: BCD Time-of-Year CODE WORD – 38 binary digits.
  - a. Seconds, minutes, hours, days, 0.1 seconds and 0.01 seconds; recycles yearly.
- 3. CODE WORD STRUCTURE: BCD Word begins at INDEX COUNT 1. Binary Coded Elements occur between POSI-TION IDENTIFIER ELEMENTS (seven for seconds; seven for minutes; six for hours; ten for days; four for 0.1 seconds; four for 0.01 seconds) until the CODE WORD is complete. A POSITION IDENTIFIER occurs between decimal digits in each group to provide separation for visual resolution.
- LEAST SIGNIFICANT DIGIT: Occurs first, except for fractional seconds information, which occurs following the Day-of-Year information.

#### 5. ELEMENT RATES AVAILABLE:

- a. 10000 per second (basic Element Rate)
- b. 1000 per second (POSITION IDENTIFIER Rate)
- c. 100 per second (Frame Rate)

#### 6. ELEMENT IDENTIFICATION:

- a. "On-Time" reference point for each element is its leading edge.
- b. INDEX MARKER duration: 0.02 milliseconds (Binary zero or uncoded Element)
- c. CODE DIGIT duration: 0.05 milliseconds (Binary one)
- d. POSITION IDENTIFIER duration: 0.08 milliseconds
- e. REFERENCE MARKER: Two consecutive POSITION IDENTIFIERS.

(The "On-Time" point, to which the CODE WORD refers, is the leading edge of the second POSITION IDENTIFIER.)

- **7. RESOLUTION:** 0.10 milliseconds (unmodulated); 0.01 milliseconds (modulated).
- 8. CARRIER FREQUENCY: 100 kHz when modulated.



#### IRIG FORMAT 'H' - GENERAL

- 1. TIME FRAME: 1 minute
- CODE DIGIT WEIGHTING: BCD Time-of-Year CODE WORD – 23 binary digits. Minutes, hours and days; recycles yearly.
- **3. CODE WORD STRUCTURE:** BCD word begins at INDEX COUNT 10. Binary-Coded Elements occur between POSITION IDENTIFIER ELEMENTS (seven for minutes; six for hours; ten for days) until the CODE WORD is complete. A POSITION IDENTIFIER occurs between decimal digits in each group to provide separation for visual resolution.
- 4. LEAST SIGNIFICANT DIGIT: Occurs first.

#### 5. ELEMENT RATES AVAILABLE:

- a. 1 per second (basic Element Rate)
- b. 1 per ten seconds (POSITION IDENTIFIER Rate)
- c. 1 per minute (Frame Rate)
- 6. ELEMENT IDENTIFICATION:
  - a. "On-Time" reference point for each element is its leading edge.
  - b. INDEX MARKER duration: 0.2 seconds (Binary zero or uncoded Element)
  - c. CODE DIGIT duration: 0.5 seconds (Binary one)
  - d. POSITION IDENTIFIER duration: 0.8 seconds
- e. REFERENCE MARKER: 1 per minute. Two consecutive POSITION IDENTIFIERS.

(The "On-Time" point, to which the CODE WORD refers, is the leading edge of the second POSITION IDENTIFIER.)

- RESOLUTION: 1 second (unmodulated); 0.01 seconds (modulated 100 Hz); 0.001 seconds (modulated 1 kHz).
- 8. CARRIER FREQUENCY: 1 kHz or 100 Hz when modulated.



### IRIG FORMAT 'C' - GENERAL (OBSOLETE) HISTORICAL

- 1. TIME FRAME: 1 minute
- **2. CODE DIGIT WEIGHTING OPTIONS:** Binary Coded Decimal Time-of-Year CODE WORD only 23 binary digits. Minutes, hours and days; recycles yearly.
- 3. CODE WORD STRUCTURE: BCD: Word begins at IN-DEX COUNT 10. Binary-coded Elements occur between POSITION IDENTIFIER Elements (seven for minutes; six for hours; ten for days) until the CODE WORD is complete. A POSITION IDENTIFIER occurs between decimal digits in each group to provide separation for visual resolution.
- 4. LEAST SIGNIFICANT DIGIT: Occurs first.

#### 5. ELEMENT RATES AVAILABLE:

- a. 2 per second (basic Element rate)
- b. 1 per 5 seconds (POSITION IDENTIFIER Rate)
- c. 1 per minute (Frame Rate)

#### 6. ELEMENT IDENTIFICATION:

- a. "On-Time" reference point for each Element is its leading edge.
- b. INDEX MARKER duration: 0.1 seconds (Binary zero or uncoded Element)
- c. CODE DIGIT duration: 0.25 seconds (Binary one)
- d. POSITION IDENTIFIER duration: 0.4 seconds (Refers to the leading edge of the succeeding Element)
- e. REFERENCE MARKER: Two consecutive POSITION IDENTIFIERS.

(The "On-Time" point, to which the CODE WORD refers, is the leading edge of the second POSITION IDENTIFIER.)

- **7. RESOLUTION:** 0.5 seconds (unmodulated); 0.01 seconds (modulated 100 Hz); 0.001 seconds (modulated 1000 Hz).
- 8. CARRIER FREQUENCY: 100 or 1000 Hz when modulated.



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## NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

TIME CODE FORMATS

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#### NASA 36-BIT TIME CODE (GENERAL) (NASA 1 SECOND BCD TIME CODE)

- 1. TIME FRAME: 1 second
- 2. CODE DIGIT WEIGHTING: Binary Coded Decimal Timeof-Year CODE WORD — 30 binary digits. Seconds, minutes, hours and days; recycles yearly.
- **3. CODE WORD STRUCTURE:** BCD: Word begins at IN-DEX COUNT 1. Binary-Coded Elements occur between POSITION IDENTIFIER ELEMENTS in 4-digit groups until the CODE WORD is complete. A CODE DIGIT occurs between decimal digits in each group to provide separation for visual resolution.
- 4. LEAST SIGNIFICANT DIGIT: Occurs first.

#### 5. ELEMENT RATES AVAILABLE:

- a. 100 per second (basic Element Rate)
- b. 1 per second (Frame Rate)

#### 6. ELEMENT IDENTIFICATION:

- a. "On-Time" reference point for each element is its leading edge.
- b. INDEX MARKER duration: 2 milliseconds (Binary zero or uncoded Element)
- c. CODE DIGIT duration: 6 milliseconds (Binary one)
- d. POSITION IDENTIFIER duration: 6 milliseconds
- e. REFERENCE MARKER: Five consecutive POSITION IDENTIFIERS followed by an INDEX MARKER.

(The "On-Time" point, to which the CODE WORD refers, is the leading edge of the INDEX MARKER following the four POSITION IDENTIFIERS.)

- **7. RESOLUTION:** 10 milliseconds (unmodulated); 1 millisecond (modulated).
- 8. CARRIER FREQUENCY: 1 kHz when modulated.



#### NASA 28-BIT TIME CODE (GENERAL) (NASA 1 MINUTE BCD TIME CODE)

- 1. TIME FRAME: 1 minute.
- CODE DIGIT WEIGHTING: Binary Coded Decimal Timeof-Year CODE WORD — 23 binary digits. Minutes, hours and days; recycles yearly.
- **3. CODE WORD STRUCTURE:** BCD: Word begins at IN-DEX COUNT 1. Binary Coded Elements occur between POSITION IDENTIFIER ELEMENTS in four-digit groups until the CODE WORD is complete. A CODE DIGIT occurs between decimal digits in each group to provide separation for visual resolution.
- 4. LEAST SIGNIFICANT DIGIT: Occurs first.

#### 5. ELEMENT RATES AVAILABLE:

- a. 2 per second (basic Element Rate)
- b. 1 per minute (Frame Rate)
- 6. ELEMENT IDENTIFICATION:
  - a. "On-Time" reference point for each element is its leading edge.
  - b. INDEX MARKER duration: 0.1 second (Binary zero or uncoded Element)
  - c. CODE DIGIT duration: 0.3 second (Binary one)
  - d. POSITION IDENTIFIER duration: 0.3 second
  - e. REFERENCE MARKER: Five consecutive POSITION IDENTIFIERS followed by an INDEX MARKER.

(The "On-Time" point, to which the CODE WORD refers, is the leading edge of the INDEX MARKER following the four POSITION IDENTIFIERS.)

- 7. RESOLUTION: 0.5 second (unmodulated); 0.01 second (modulated 100 Hz); 0.001 second (modulated 1000 Hz).
- 8. CARRIER FREQUENCY: 100 Hz or 1000 Hz when modulated.

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TIME -----

#### NASA 20-BIT TIME CODE (GENERAL) (NASA 1-HOUR BCD TIME CODE)

- 1. TIME FRAME: 1 hour.
- CODE DIGIT WEIGHTING: Binary Coded Decimal Timeof-Year CODE WORD — 16 binary digits. Hours and days; recycles yearly.
- **3. CODE WORD STRUCTURE:** BCD: Word begins at INDEX COUNT 1. Binary-coded elements occur between POSITION IDENTIFIER ELEMENTS in four-digit groups until the CODE WORD is complete. A CODE DIGIT occurs between decimal digits in each group to provide separation for visual resolution.
- 4. LEAST SIGNIFICANT DIGIT: Occurs first.

#### 5. ELEMENT RATES AVAILABLE:

- a. 1 per minute (basic Element Rate)
- b. 1 per hour (Frame Rate)

#### 6. ELEMENT IDENTIFICATION:

- a. "On-Time" reference point for each element is its leading edge.
- b. INDEX MARKER duration: 0.2 minutes (binary zero or uncoded Element).
- c. CODE DIGIT duration: 0.6 minutes (Binary One)
- d. POSITION IDENTIFIER duration: 0.6 minutes
- e. REFERENCE MARKER: Five consecutive POSITION IDENTIFIERS followed by an INDEX MARKER

(The "On-Time" point, to which the CODE WORD refers, is the leading edge of the INDEX MARKER following the four POSITION IDENTIFIERS).

- 7. RESOLUTION: 1 minute (unmodulated); 10 milliseconds (modulated 100 Hz); 1 millisecond (modulated 1 kHz)
- 8. CARRIER: 100 Hz or 1 kHz when modulated.



#### NASA SERIAL DECIMAL – SUPPRESSED CARRIER (GEMINI)

#### 1. TIME FRAME: 10 seconds

- CODE DIGIT WEIGHTING: Decimal Time-of-Year CODE WORD. Decimal pulse-coded.
- a. Seconds, minutes, hours and days. A coded pulse is designated by 50 milliseconds of suppressed carrier.
- 3. CODE WORD STRUCTURE:
  - a. DECIMAL: Word begins at INDEX COUNT 2. Decimal elements occur between POSITION IDENTIFIER ELEMENTS in nine-digit groups until CODE WORD is complete. A Code Digit (50 milliseconds of suppressed carrier) represents one decimal count and is added to accumulate the value of each CODE WORD. An INDEX MARKER occurs between code groups to provide separation for visual resolution.
- **4. HOURS CODE WORD:** Occurs first, followed by minutes, seconds and days.
- 5. ELEMENT RATES AVAILABLE:
  - a. 1 per second (POSITION IDENTIFIER Rate)
  - b. 1 per 10 seconds (Frame Rate)
  - All other rates are variable depending on code content.

#### 6. ELEMENT IDENTIFICATION:

- a. "On-Time" reference point for each element is its leading edge.
- b. CODE DIGIT duration: 50 milliseconds (decimal count of one)
- c. POSITION IDENTIFIER duration: 50 milliseconds
- d. REFERENCE MARKER duration: 150 milliseconds
- (The "On-Time" point, to which the CODE WORD refers, is the leading edge of the 150-millisecond reference occurring at 1 per 10 seconds).
- **7. RESOLUTION:** 1 second (POSITION IDENTIFIER); 10 second (Frame Rate); 1 millisecond (Modulated).
- 8. CARRIER: 1 kHz





NASA SERIAL DECIMAL CODE - SUPPRESSED CARRIER -(Gemini)

#### NASA SERIAL DECIMAL – EXALTED CARRIER (APOLLO)

The Exalted Carrier form of NASA serial decimal Time Code is exactly equal to the Suppressed Carrier format. The only difference lies in the method of modulating the 1000 Hz sinewave.





TYPICAL MODULATED CARRIER (1000 Hz)

NASA SERIAL DECIMAL CODE - EXALTED CARRIER -(Apollo)



NOTES

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OTHER COMMONLY USED TIME CODE FORMATS



#### 25 PPS - ONE SECOND - 250 Hz XR3 FORMAT

- 1. TIME FRAME: 1 second
- **2. CODE DIGIT WEIGHTING:** BCD: Time-of-Day CODE WORD 20 binary digits.

a. Hours, minutes, seconds. Recycles every 24 hours.

- **3. CODE WORD STRUCTURE:** BCD: Word begins at INDEX COUNT 1. Binary-coded Elements occur consecutively (six for hours, seven for minutes, seven for seconds) until the CODE WORD is complete.
- 4. MOST SIGNIFICANT DIGIT: Occurs first.
- 5. ELEMENT RATES AVAILABLE:
  - a. 25 per second (basic Element rate). (Four consecutive pulses missing at end of frame)
  - b. 1 per second (Frame rate)

#### 6. ELEMENT IDENTIFICATION:

- a. "On-Time" reference point for each Element is its trailing edge.
- b. Binary zero duration: 12 milliseconds
- c. CODE DIGIT duration: 24 milliseconds (Binary one)
- d. REFERENCE MARKER 1 per second Duration: 36 milliseconds

(The "On-Time" point, to which the CODE WORD refers, is the trailing edge of the REFERENCE MARKER).

- RESOLUTION: 1 second (Frame Rate) (unmodulated).
   40 milliseconds during CODE WORD only. 4 milliseconds (modulated).
- 8. CARRIER FREQUENCY: 250 Hz.


25 PPS - ONE SECOND TIME CODE (250 Hz - XR3)

TIME ----

-

#### 2137 FORMAT

The 2137 Format is exactly the same as the XR3 Format. The 2137 Format modulates a 1000 Hz carrier, thus provides a 1 millisecond resolution.



25 PPS — ONE SECOND TIME CODE (1000 Hz - 2137)

TIME -----

100

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#### FEDERAL AVIATION ADMINISTRATION - NAFEC TIME CODES

- 1. TIME FRAME: Any of five from 10 seconds to 50 milliseconds.
- CODE DIGIT WEIGHTING: Binary Coded Decimal Timeof-Day CODE WORD: from 30 binary digits (50 – ms TF) to 18 binary digits (10 – second TF).
  - a. 0.01 seconds, 0.1 seconds, seconds, minutes and hours; recycles every 24 hours.

#### 3. CODE WORD STRUCTURE:

- a. BCD word begins at INDEX COUNT 1. Binary-coded elements occur between POSITION IDENTIFIER ELEMENTS until the CODE WORD is complete. An INDEX MARKER occurs between each BCD digit and between each Decimal Group to provide separation for visual resolution.
- 4. LEAST SIGNIFICANT DIGIT: Occurs first.

#### 5. ELEMENT RATES AVAILABLE:

Variable from 10 per second (10-second Frame Rate) to 2000 per second (50-ms Frame Rate).

#### 6. ELEMENT IDENTIFICATION:

- a. "On-Time" reference point for each element is its leading edge.
- b. INDEX MARKER duration: Variable from 50 milliseconds (10-second Frame) to 250 microseconds (50 ms Frame).

INDEX MARKER is always positive amplitude (binary zero uncoded Element or Sync Mark).

- c. CODE DIGIT duration: Variable from 50 ms (10-second Frame) to 250 microseconds (50 ms Frame). CODE DIGIT is always negative amplitude (binary one).
- d. POSITION IDENTIFIER same duration as INDEX MARKER — Position Identifier is always two Index Markers and negative in amplitude.
- e. REFERENCE MARKER four consecutive binary ones followed by an INDEX MARKER (binary zero).

(The "On-Time" point, to which the CODE WORD refers, is the leading edge of the INDEX MARKER following the four consecutive ones).

- **7. RESOLUTION:** From 100 milliseconds (10 second Frame) to 500 microseconds (50 millisecond Frame).
- 8. CARRIER: Normally not Carrier modulated.



| Time Code  | TIME   |        |        |  |
|------------|--------|--------|--------|--|
| Frame Rate | A      | В      | С      |  |
| 1F/10 SEC  | 10 SEC | 1 SEC  | 100 MS |  |
| 1F/SEC     | 1 SEC  | 100 MS | 10 MS  |  |
| 5F/SEC     | 200 MS | 20 MS  | 2 MS   |  |
| 10F/SEC    | 100 MS | 10 MS  | 1 MS   |  |
| 20F/SEC    | 50 MS  | 5 MS   | 500 µs |  |

TIME IS: 14 hours, 08 minutes, 32.00 seconds

FEDERAL AVIATION AGENCY NAFEC TIME CODE

#### ATLANTIC MISSILE RANGE FORMAT D1/D5

- 1. TIME FRAME: 1 second
- CODE DIGIT WEIGHTING: Grouped Binary Time-of-Day CODE WORD — 17 binary digits.
  - a. Seconds, minutes and hours. Recycles every 24 hours.
- 3. CODE WORD STRUCTURE:
- a. Binary word begins at INDEX COUNT 1. Grouped binary elements occur (six for seconds, six for minutes, five for hours) until the CODE WORD is complete.
- 4. LEAST SIGNIFICANT DIGIT: Occurs first.

#### 5. ELEMENT RATES AVAILABLE:

- a. 100 per second (basic Element rate)
- b. 10 per second (INDEX MARKER)
- c. 1 per second (Frame Rate)

#### 6. ELEMENT IDENTIFICATION:

- a. "On-Time" reference point for each Element is its leading edge.
- b. INDEX MARKER duration: (100 PPS); 2 milliseconds (Binary zero or uncoded Element)
- c. INDEX MARKER duration: (10 PPS); 4 milliseconds
- d. CODE DIGIT duration: 6 milliseconds (Binary one)
- e. REFERENCE MARKER duration: 8 milliseconds

(The "On-Time" point, to which the CODE WORD refers, is the leading edge of the REFERENCE MARKER).

- RESOLUTION: 10 milliseconds (unmodulated); 1 millisecond (modulated 1 kHz); D5 code
- **8. CARRIER FREQUENCY:** 1 kHz Code designation changed to D5.



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#### DATUM BI-LEVEL SLOW-CODE (5-Rate Selectable)

The DATUM special Bi-Level Slow-Code is designed to provide a convenient and efficient TIME REFERENCE for strip charts and oscillograph records. Five different and unique codes are provided to enable selection of the desired resolution consistent with the paper speed.

The CODE is width modulated, BCD Format. Amplitude modulation is also added to aid in the separation of the coded information.

Each Code Group is separated by a space to aid in fast recognition of the coded data without loss of resolution or inclusion of extraneous pulses. Coded information represents Time-of-Year in seconds, minutes, hours and days.



TIME IS: 191 Days, 14 Hours, 08 Minutes, 32 Seconds

| C<br>O<br>D<br>E | Pulse<br>Rate | Frame<br>Period | Binary<br>Zero | Binary<br>One | Frame<br>Ref.<br>Pulse |
|------------------|---------------|-----------------|----------------|---------------|------------------------|
| 1                | 50 pps        | 1 Sec.          | 4 ms           | 10 ms         | 20 ms                  |
| 2                | 10 pps        | 5 Sec           | 20 ms          | 50 ms         | 100 ms                 |
| 3                | 5 pps         | 10 Sec.         | 40 ms          | 100 ms        | 200 ms                 |
| 4                | 1 pps         | 60 Sec.         | 200 ms         | 500 ms        | 1000 ms                |
| 5                | 1 p/10s       | 10 Min.         | 2 sec          | 5 sec         | 10 sec                 |

DATUM INC. BI-LEVEL – 5-RATE SLOW CODE



#### 48-BIT TIME OF YEAR BINARY CODED DECIMAL (BCD) CODE

- 1. TIME FRAME: 1 second
- CODE DIGIT WEIGHTING: Binary coded decimal timeof-year code word – 48 binary digits. Days, hours, minutes and seconds, FOM; recycles annually.
- 3. CODE WORD STRUCTURE: BCD. Word begins at index 0. Binary coded elements occur in four-digit groups until the code word is complete.
- 4. MOST SIGNIFICANT DIGIT: Occurs first
- 5. INDEX PERIOD: 20 milliseconds

#### 24-BIT TIME OF DAY BINARY CODED DECIMAL (BCD) CODE

- 1. TIME FRAME: 1 second
- CODE DIGIT WEIGHTING: Binary coded decimal timeof-day code word – 24 binary digits. Hours, minutes and seconds; recycles daily.
- 3. CODE WORD STRUCTURE: BCD. Word begins at index 0. Binary coded elements occur in four-digit groups until the code word is complete.
- 4. MOST SIGNIFICANT DIGIT: Occurs first
- 5. INDEX PERIOD: 20 milliseconds



40 Bit Time of Year 24 Bit Time of Day



U.S. STANDARD TIME BROADCAST FORMATS

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#### UNITED STATES STANDARD BROADCAST GENERAL

The National Bureau of Standards maintains three radio stations whose function it is to transmit standard time broadcasts for laboratories and individual users throughout the world. Radio stations WWV and WWVH are high frequency broadcast stations on carrier frequencies of: 2.5 MHz, 5 MHz, 10 MHz and 20 MHz. WWV additionally broadcasts on 25 MHz (see Appendix 'A'). In addition to the two high-frequency radio stations, Radio Station WWVB broadcasts serial time codes at a 60 kHz transmission carrier for accurate frequency measurements within the continental United States.

Radio Stations WWV and WWVH have, in addition to serial Time Codes, voice time announcements and special voice announcements as required, as well as various tone signals. A precise one-second "tick" is also broadcast by both WWV and WWVH for audio determination of Epoch and period time synchronization.

The time being broadcast by WWV, WWVH and WWVB is Universal Time Coordinated (see Appendix 'B') and is maintained to the internationally-agreed time by one-second corrections. Further, the code formats provided by each station provide coded information to enable determination of Universal Time (UTI).

The serial time codes (as part of the radio transmissions) are shown and described on the following pages. Additional information regarding the broadcasts, as well as definitions and user data, is available in Appendix 'B' of this Handbook and available from the National Bureau of Standards, Frequency-Broadcast Services Station 273.02, Boulder, Colorado 80302.



WWV BROADCAST FORMAT (TYPICAL)

### WWV BROADCAST FORMAT (TYPICAL)



#### WWV/WWVH TIME FORMAT

- 1. TIME FRAME: 1 minute
- **2. CODE DIGIT WEIGHTING:** BCD Time-of-Year CODE WORD 30 binary digits.
  - a. Minutes, hours, days and UT correction. 0.01 seconds, 0.1 seconds.
- **3. CODE WORD STRUCTURE:** BCD: Word begins at INDEX COUNT 10 + 30 milliseconds. Binary-coded Elements occur between POSITION IDENTIFIER ELE-MENTS (seven for minutes, six for hours, ten for days, seven for UT correction) until the CODE WORD is complete. POSITION IDENTIFIER occurs between decimal digits in each group to provide separation for visual resolution.
- **4. LEAST SIGNIFICANT DIGIT:** (Minutes) occurs first UT correction occurs after days.

#### 5. ELEMENT RATES AVAILABLE:

- a. 1 per second (basic ELEMENT rate)
- b. 1 per 10 seconds (POSITION IDENTIFIER Rate)
- c. 1 per minute (Frame Rate)

#### 6. ELEMENT IDENTIFICATION:

- a. "On-Time" reference point for each element is 30 milliseconds before the element.
- b. INDEX MARKER duration: 170 milliseconds (Binary zero or uncoded element)
- c. CODE DIGIT duration: 470 milliseconds (Binary one)
- d. POSITION IDENTIFIER duration: 770 milliseconds
- e. REFERENCE MARKER 1 per minute. One POSI-TION IDENTIFIER followed by a missing digit position.

(The "On-Time" point, to which the CODE WORD refers, is the leading edge of an imaginary (missing) POSITION IDENTIFIER following a POSITION IDENTIFIER).

- **7. RESOLUTION:** 1 second (unmodulated); 0.01 second (modulated 100 Hz) (theoretical)
- 8. CARRIER: 100 Hz 100% modulation
- **9. TIME SCALE:** Universal Time Coordinated with coded correction to UT1.



TIME -

NATIONAL BUREAU OF STANDARDS WWV/WWVH Standard Time Code Envelope

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#### WWVB TIME FORMAT

- 1. TIME FRAME: 1 minute
- **2. CODE DIGIT WEIGHTING:** BCD Time-of-Year CODE WORD 35 binary digits.
- a. Minutes, hours, days, UT correction 0.1 seconds, 0.01 seconds, 0.001 seconds.
- 3. CODE WORD STRUCTURE: BCD: Word begins at INDEX COUNT 1. Binary coded elements occur between POSITION IDENTIFIER ELEMENTS (seven for minutes, six for hours, ten for days, 4 for UT corrected) till the CODE WORD is complete. A POSITION IDENTIFIER occurs between decimal digits in each group to provide separation for visual resolution.
- **4. LEAST SIGNIFICANT DIGIT:** (Minutes) occurs first UT correction occurs after days.
- 5. ELEMENT RATES AVAILABLE:
  - a. 1 per second (Basic Element Rate)
  - b. 1 per 10 seconds (POSITION IDENTIFIER Rate)
  - c. 1 per minute (Frame rate)
- 6. ELEMENT IDENTIFICATION:
  - a. "On-Time" reference point for each element is its leading edge.
  - b. INDEX MARKER duration: 0.2 seconds (Binary zero or uncoded element)
  - c. CODE DIGIT duration: 0.5 seconds (Binary one)
  - d. POSITION IDENTIFIER duration: 0.8 seconds
  - e. REFERENCE MARKER 1 per minute. Two consecutive POSITION IDENTIFIERS

(The "On-Time" point, to which the CODE WORD refers, is the leading edge of the second POSI-TION IDENTIFIER).

- 7. RESOLUTION: 1 second (unmodulated)
- 8. CARRIER: 60 kHz (1:10 modulation ratio) suppressed carrier.
- **9. TIME SCALE:** Universal Time Coordinated with coded correction to UT1.



TIME -----

LEAP YEAR SET 1 JAN - 28 FEB DAYLIGHT SET DURING DAY PRIOR TO GMT-5HR OF CHANGE

> NATIONAL BUREAU OF STANDARDS WWVB TIME CODE ONE-PPS CODE ENVELOPE

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APPENDICES

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NOTES

#### APPENDIX 'A' TIME DETERMINATION

#### **1.0 INTRODUCTION**

With the exception of the carrier and format coherency and the pulse-to-pulse precision of the individual format involved, the various Time Code Formats referenced and described in this Handbook are independent of the time scale or of accuracy. Achieving the desired results from the timing device depends upon the precision of the clock providing the timing signals and upon its maintenance. Much has been written on the theoretical and practical requirements and limitations of synchronizing widely separated clocks.

#### 2.0 ELEMENTS OF TIME PRECISION

Three basic elements are required to set and maintain time precision. First, "epoch" time is the time of year in seconds, minutes, hours and days to be presented by the timing device. Next, a consistent time interval, usually one second, must be determined in order to place the timing device in synchronism with the Master System. Thirdly, the rate of time generation, e.g., frequency, must be compared and correlated to ensure that the timing-device time-scale will remain in correspondence, within the precision requirements of the system, to master time.

#### 3.0 METHODS OF SYNCHRONIZATION

There are many ways of synchronizing widely separated clocks to one another. However, two basic approaches provide the fundamental methods of synchronizing to world or universal time. The greatest precision is obtained by transporting a portable clock to each station requiring synchronization. This allows the determination of epoch and period and calibration of time scales. The precision, of course, depends upon the complexity and sophistication of the portable clock and the distance between the timing stations to be synchronized.

A less complex and less accurate method uses the standard time broadcast maintained by the National Bureau of Standards: WWV, WWVH or WWVB. In actuality to perform all three determinations, both high-frequency and very low frequency transmission, or an equivalent means, must be established. In practice, the high frequency broadcasts give sufficient precision to determine epoch and calibration but do not provide sufficient precision for determination of period. This is due to uncertainties of the high frequency broadcast brought about by variation in atmospheric conditions, climate, distance, etc. The use of VLF transmissions provide a more accurate means of frequency comparison. since the same variables are either non-existent or have minimum effect on the reception and determination of the calibrating frequency.

An excellent and considerably more detailed source for synchronization techniques and equipment can be found in the Hewlett-Packard publication, Application Note No. 52. Research into IEEE papers and time and frequency publications available from the National Bureau of Standards will give further information.

#### 4.0 CALIBRATION AND MAINTENANCE OF FREQUENCY SOURCE

The use of high frequency broadcast or local Master Station provides a ready means of determining period and epoch for synchronization of the timing device. A more complex problem, however, exists in calibrating and maintaining the frequency source that is used to develop the basic timescale used for the timing device.

First, a determination as to the desired scale must be made, be it universal time, atomic time, stepped atomic time, or universal time coordinated (refer to Appendix 'B').

The basic frequency source of the timing device must be calibrated to the desired time-scale, which will then determine the quantitative development of the epoch value of time over the desired period of operation. Typical frequency sources for timing devices are derived by Quartz oscillators. The configuration of these Quartz oscillators determines their precision and accuracy per unit time. The variation of these frequency sources results in an offset from the absolute time scale selected, which is termed "time error." The time scale or frequency source must then be periodically recalibrated and the timing device reset to maintain the desired minimum time error with respect to the master synchronizing source.



The equation for total time error is:

$$E = E_{O} + \left(\frac{f_{O}}{f_{r}} - 1\right) t + \frac{at^{2}}{2}$$

This indicates that the total time error at any time t depends upon four variables. Where  $E_0$  is the initial time error,  $f_0$ is the initial frequency setting;  $f_r$  is the reference frequency setting; a is the oscillator aging rate and t is elapsed time. Figure 1 shows a plot of this equation whereby the time error results in a parabola. It should be noted that the frequency change of the oscillator is assumed to be linear in an ever increasing value. A negative slope of the frequency change would invert the parabola. Figure 2 shows the effect of various frequency variations on the time error.

It can be seen then that the time error of a timing device increases exponentially as the frequency of the oscillator drifts. If an oscillator is set precisely to coincide with the Master oscillator, offset is zero and the total time error will be a result only of the aging of the oscillator. The offset of the oscillator will vary the time error on a linear basis as shown in Figure 2.

The Nomograph on the following page can be used as an aid to estimate the time error accumulated over a period of time due to aging and due to offset. In accordance with the equation, these two values should be added to determine the total error of any individual condition. By examining Figure 2 it can be seen that by setting the oscillator consistent with the direction of drift, one can extend the operating period for any given maximum error desired.





FIGURE 2



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#### **1.0 INTRODUCTION**

The Time Code Formats provided by the particular timing device are independent of the time scale and of the precision of any particular device or system. Over the years there have been many time scales utilized and defined; some have been revised and discarded as more accurate methods of time determination have been conceived. Others have been redefined and consolidated in order to reduce the confusion and, hopefully, make the determination of time, e.g., the second and its accumulation, a more useable and understandable quantity.

Presently the majority of the time scales are either derived from or related to the atomic second. The atomic second is defined specifically by a hyperfine transition of the atom of cesium-133. This is defined as the duration of 9,192,631,770 oscillations.

With respect to human endeavors, the most logical and most widespread definition of time comes from the relationship of the earth to the sun, to the moon and to the stars. This relates to man's desire to eat lunch at 12 noon, go to sleep at night and arise in the morning. More complicated, however, are the requirements for accurate astronomical experiments and, therefore, the need for an invariant reference so that meaningful predictions can be made of celestial happenings related to measurable time on earth.

The purpose of this Appendix is to list and briefly define the various time scales; a more comprehensive discussion can be obtained from the Hewlett-Packard publication, Application Note No. 52, as well as other technical and historical publications.

#### 2.0 SOLAR TIME

Solar Time represents the early efforts of man to establish a time scale related to the position of the earth with respect to the sun at uniform intervals. This served the needs of mankind until increased precision of astronomical observations indicated that the earth's rotation was not uniform; that its speed was not constant. Therefore, the relationship of the earth to the sun caused a continuous variation of the second and thus the accumulation of time.

#### 3.0 AVERAGE SOLAR TIME

An attempt was made to develop a coherent non-variable second by averaging the variations due to the orbital uncertainty of the earth's axis. A mean solar second was thus determined to be a mean solar day divided by 86,400. This was still not adequate due to the non-uniformity of the earth's rotation and required an adjustment of approximately one day every four years.

#### 4.0 UNIVERSAL TIME

Because of the need for a uniform time scale throughout the world. Universal Time was defined and based on the rotation of the earth about its axis as with mean Solar Time. Universal Time was developed on the assumption that the earth's rotation was constant and it was chosen so that local noon would occur when the sun was on the local meridian. Basic Universal Time is equivalent to mean Solar Time and is identified as UT0. UT1 and UT2 provide corrections to basic Universal Time to compensate for the rotational uncertainties of the earth and to accommodate seasonal changes. Until recent years, the most widely-used scale was UT2. This time scale was in use at the majority of the nation's missile ranges and tracking facilities. UT2 was maintained and defined by the U.S. Naval Observatory and broadcast worldwide on NBS radio stations WWV and WWVH. In January of 1972, both standard broadcasts converted to the UTC time scale which may be corrected to UT1.

#### 5.0 SIDEREAL TIME

The Sidereal second is determined from the Sidereal day which is strictly defined by observation of the earth with respect to the stars. A Sidereal day is approximately 23 hours, 56 minutes and 4.09 seconds referenced to a mean Solar day. A Solar Year will contain 366.24 Sidereal days. Sidereal time is used by some astronomy researchers for celestial experiments.

#### 6.0 MEAN SIDEREAL TIME

As in the case of mean Solar Time, mean Sidereal Time is an adjustment of Sidereal Time to compensate for the nodding or nutation of the earth's axis.

#### 7.0 EPHEMERIS TIME

The uncertainty of the rotation of the earth on its axis, even when all possible corrections have been made, does not provide an invariable standard. The need for uniform time has lead astronomers to define the Ephemeris second. Ephemeris time is based on the motion of the earth about the sun and is obtained from observations of the motion of the moon about the earth. The International Committee of Weights and Measures defines the Ephemeris second for January 0, 1900 at 12 hours Ephemeris time. The accumulation of time due to the Ephemeris second would result if the sun continued in its apparent instantaneous rate, but corrected for orbital eccentricity and nutation of the earth's axis. It thus appears to be an invariable unit of time for astronomical purposes.



#### APPENDIX 'B' (Continued)

Obviously, the difficulty of making precise measurements of the position of the moon, except over extremely long periods of time, causes the ultimate delay in determination of the Ephemeris second and its degree of accuracy.

#### 8.0 ATOMIC TIME

As discussed earlier, Atomic Time is based on the hyperfine oscillations of the cesium atom. Atomic Time appears to be gaining popularity as the Universal Time interval to be used for the majority of timing requirements. The frequency used to transmit WWVB is derived from the atomic frequency standard, as is the time broadcast by Radio Stations WWV and WWVH. At the present time these time scales are corrected on an internationally-agreed-upon basis, but there appears to be serious discussion suggesting the abandonment of the Universal Time and a move to maintain total compliance to the atomic second.

#### 9.0 UNIVERSAL TIME COORDINATED (UTC)

Universal Time Coordinated is an internationally-agreedupon time scale as defined by the International Time Bureau (BIH).

Prior to January 1972, the UTC time scale was offset, minus 300 parts in 10<sup>-10</sup>, from the internationally-defined atomic frequency. This gave rise then to the term "stepped atomic time," which related to time developed by the Atomic Frequency Standard but which was corrected on a periodic basis to agree with Universal Time.

Time presently being broadcast by WWV, WWVH and WWVB is UTC stepped in one-second increments as nec-

essary to agree with UTC as determined by the International Time Bureau (BIH). The frequency used to accumulate UTC is the atomic scale.

Historically, the National Bureau of Standards has been charged with defining and regulating the atomic frequency standard. The U.S. Naval Observatory has been charged with maintaining Universal Time (UT2). In 1968, it was mutually agreed that UTC (USNO) and UTC (NBS) would be coordinated starting at OOUT on 1 October 1968. At that time the frequency standard at USNO was adjusted to coordinate with the UTC time scale.

#### 10.0 U S TIME STANDARD

The U S Time Standard differs from nominal Universal Time (Greenwich Mean Time) by an integral number of hours. This time is kept by the United States Naval Observatory Master Clock and is now coordinated with the Universal Time Coordinated of the National Bureau of Standards.

#### 11.0 TIME ZONES

The United States is divided into four standard time zones separated by an integral number of hours earlier than Greenwich Mean Time. Greenwich Mean Time is defined as Universal Time. Eastern Standard Time is 5 hours earlier, Central Standard Time is 6 hours earlier, Mountain Standard Time is 7 hours earlier and Pacific Standard Time is 8 hours earlier. There are 24 world time zones, each based on longitude. By international agreement, Greenwich, England is the site of the prime meridian at zero degrees longitude.

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