Instruction Manual

Tektronix

DC 504A Counter/Timer 070-4291-00

Warning

The servicing instructions are for use by qualified personnel only. To avoid personal injury, do not perform any servicing unless you are qualified to do so. Refer to the Safety Summary prior to performing service.

Please check for change information at the rear of this manual.

First Edition: January 1983 Last Revised: June 1988

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SERVICING SAFETY SUMMARY

FOR QUALIFIED SERVICE PERSONNEL ONLY

Refer also to the preceding Operators Safety Summary

Do Not Service Alone

Do not perform internal service or adjustment of this product unless another person capable of rendering first aid and resuscitation is present.

Use Care When Servicing With Power On

Dangerous voltages may exist at several points in this product. To avoid personal injury, do not touch exposed connections and components while power is on.

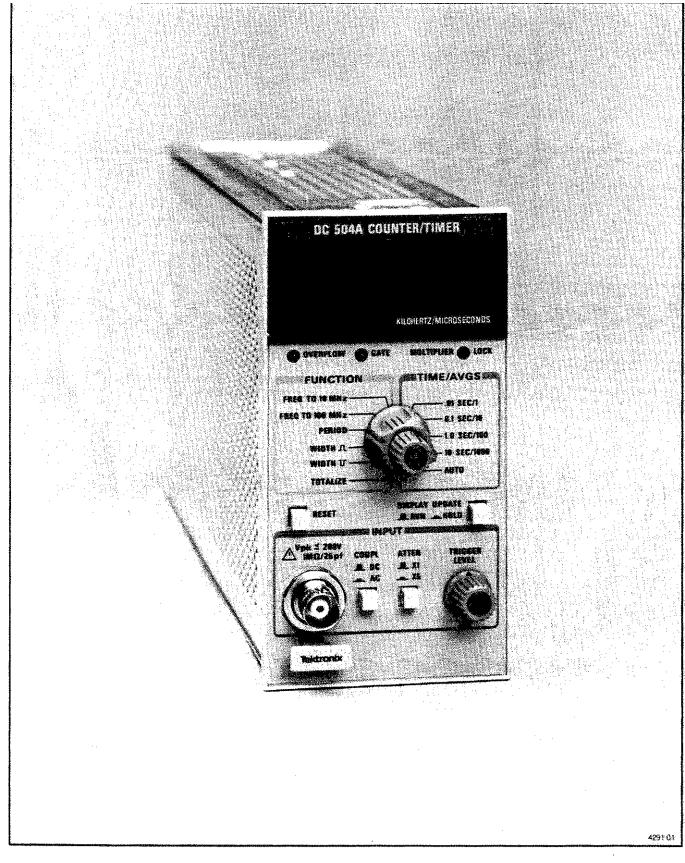
Disconnect power before removing protective panels, soldering, or replacing components.

Do Not Wear Jewelry

Remove jewelry before servicing this instrument. Rings, necklaces, and other metallic objects could come into contact with dangerous voltages and currents.

Power Source

This product is intended to operate from a power module connected to a power source that will not apply more than 250 volts rms between the supply conductors or between either supply conductor and ground. A protective ground connection by way of the grounding conductor in the power cord is essential for safe operation.



DC 504A COUNTER/TIMER

SPECIFICATION

Instrument Description

The TEKTRONIX DC 504A is a multi-function counter/timer designed to operate in one compartment of any TM 500 or TM 5000-Series power module.

Frequency measurements to 100 MHz are within the capability of the DC 504A. Frequencies above 10 MHz are internally prescaled. Measurement of pulse widths and periods at rates up to 2.5 MHz is possible. Width and Period averaging of up to 1000 events is possible. An autorange feature allows the counter to automatically select the gate time (up to one second) or number of averages (up to 100). A $\times 100$ phase-locked loop multiplier automatically increases display resolution by a factor of 100 in the 10 Hz to 25 kHz frequency range. The 10 MHz internal time base provides a single-shot resolution of 100 ns. Input signals can be ac or dc coupled and attenuated by a factor of five. All measurement results are displayed in a six digit LED readout.

No options to the standard DC 504A are available.

Standard Accessories

1 Instruction Manual

NOTE

Refer to the tabbed Accessories page at the rear of this manual for more information.

Performance Conditions

The limits stated in the Performance Requirements column of the following tables are valid only if the DC 504A has been adjusted at an ambient temperature between +20°C and +30°C and is operating at an ambient temperature between 0°C and +50°C unless otherwise stated.

Information given in the Supplemental Information and Description columns of the following tables is provided for user information only and should not be interpreted as performance check requirements.

The DC 504A must be operated or stored in an environment whose limits are described under Environmental Characteristics.

Allow at least 30 minutes warm up time for operation to specified accuracy; 60 minutes after storage in a high humidity environment.

Table 1-1 ELECTRICAL CHARACTERISTICS

| Characteristics | Performance Requirements | Supplemental Information | | | | |
|-------------------------------|---|--|--|--|--|--|
| INPUTS | | | | | | |
| Input Frequency Range | | | | | | |
| Front Panel | Dc coupled, 0 to 100 MHz Ac coupled, 10 Hz to 100 MHz | | | | | |
| Rear Interface | Dc coupled, 0 to 50 MHz Ac coupled, 10 Hz to 50 MHz | | | | | |
| Input Sensitivity | | | | | | |
| ×1 Attenuation | 30 mV rms sinewave (85 mV p-p) to 100 MHz 85 mV p-p pulse at a minimum width of 5 ns | | | | | |
| ×5 Attenuation Accuracy | To make p person at a minimum windir or 5 hs | Within 2% at do | | | | |
| Input Dynamic Range | | | | | | |
| X1 | | 2.0 V p-p signal within a ±2.0 Vdc window | | | | |
| X5 | | 10.0 V p-p signal within a ±10.0 Vdc window | | | | |
| Trigger Level Range | | Typically greater than ± 2V X attenuator setting | | | | |
| Maximum Safe Input Voltage | | | | | | |
| Front Panel | | | | | | |
| ×1 | | 200 V pk; 400 V p-p from dc to 50 kHz, derate to 15 V p-p from 1.33 MHz to 100 MHz | | | | |
| ×5 | | 200 V pk; 400 V p-p from dc to 5 MHz, derate to 20 V p-p at 100 MHz | | | | |
| Rear Interface | | ≤ 4 V pk | | | | |
| nput Impedance | | | | | | |
| Front Panel ×1, ×5 | | 1 MΩ, paralleled by approximately 25 pF | | | | |
| Rear Interface ×1, ×5 | | 50 ohms ± 10% at dc | | | | |

Table 1-1 (cont.)

| Characteristics | Performance Requirements | Supplemental Information | | | | |
|------------------------|---|---|--|--|--|--|
| FUNCTIONS | | | | | | |
| Frequency to 10 MHz | | | | | | |
| Range | Dc coupled, 0 Hz to 10 MHz Ac coupled, 10 Hz to 10 MHz | | | | | |
| Accuracy | | ± 1 count \pm time base error $	imes$ freq | | | | |
| Gate Time | | 10 ms to 10 sec, selectable in decade steps, or autoranging (10 ms to 1 sec only) | | | | |
| Resolution | | | | | | |
| Non-phase-locked | A CANADA | 100 Hz to 0.1 Hz, selectable in decade steps, or autoranging (100 Hz to 1 Hz only) | | | | |
| Phase Locked | | 1 Hz to 0.001 Hz, selectable in decade steps, or autoranging (1 Hz to 0.01 Hz only) | | | | |
| Lock Range | 10 Hz ≤ Freq ≤ 25 kHz | | | | | |
| Multiplication | ×100 | | | | | |
| Lock Time | ≤ 5 seconds | Phase Lock Loop automatically increases resolution whenever loop locks. PLL defeat can be accomplished by an internal jumper. | | | | |
| Frequency to 100 MHz | | | | | | |
| Range | Dc coupled, 0 Hz to 100 MHz Ac coupled, 10 Hz to 100 MHz | | | | | |
| Prescale Factor | ÷ 10 | | | | | |
| Accuracy | | ±1 count ± time base error × freq | | | | |
| Gate Time (Resolution) | | 10 ms to 10 sec (1 kHz to 1 Hz). Selectable in decade steps, or autoranging (10 ms to 1 sec only). | | | | |
| Period AVG | | | | | | |
| Freq Range | Dc coupled, 0 Hz to 2.5 MHz Ac coupled, 10 Hz to 2.5 MHz | Overflows above 99999.9 μs (100 ms) | | | | |
| Number of Averages (N) | | 10° to 10°, selectable in decade steps, or autoranging (10° to 10° only). | | | | |
| Resolution | | 100 ns to 100 ps, selectable in decade steps or autoranging (100 ns to 1 ns only). | | | | |
| Accuracy | | $\pm \frac{100 \text{ ns}}{\text{N}} \pm \text{ time base error} \times \text{period}$ | | | | |
| | | $\pm 1.4 \times \left(\frac{\text{trigger jitter error}}{N}\right)$ | | | | |

Table 1-1 (cont.)

| Characteristics | Performance Requirements | Supplemental Information |
|--------------------|---|---|
| Width AVG | | |
| Freq Range | Dc coupled, 0 Hz to 2.5 MHz Ac coupled, 10 Hz to 2.5 MHz | |
| Slope | Positive | |
| Number of Avgs (N) | | 10° to 10³, selectable in decades, or autoranging (10° to 10² only) |
| Resolution | | $\frac{100 \text{ ns}}{\sqrt{N}}$ |
| Accuracy | | $\pm \frac{100 \text{ ns}}{\sqrt{N}} \pm \text{ time base error} \times \text{ width}$ |
| | | $\pm \frac{\text{start trigger jitter error}}{\sqrt{N}}$ |
| | | $\pm \frac{\text{stop trigger jitter error}}{\sqrt{N}}$ |
| | | + (stop slew rate error start slew rate error |
| | | ±10 ns |
| Width "☐ AVG | | |
| Freq Range | Dc coupled, 0 Hz to 2.5 MHz Ac coupled, 10 Hz to 2.5 MHz | |
| Slope | Negative | |
| Number of Avgs (N) | | 10° to 10° , selectable in decades, or autoranging (10° to 10° only) |
| Resolution | | 100 ns √N |
| Accuracy | | $\pm \frac{100 \text{ ns}}{\sqrt{N}} \pm \text{ time base error} \times \text{ width}$ |
| | | $\pm \frac{\text{start trigger jitter error}}{\sqrt{N}}$ |
| | | $\pm \frac{\text{stop trigger jitter error}}{\sqrt{N}}$ |
| | | + (stop slew rate error - start slew rate error |
| | | ±10 ns . |

Table 1-1 (cont.)

| Characteristics | Performance Requirements | Supplemental Information |
|-----------------|---|--|
| Totalize | | |
| Freq Range | Dc coupled, 0 Hz to 10 MHz Ac coupled, 10 Hz to 10 MHz | Overflows above 999999. Display update run/hold will hold display white counter continues to advance. Releasing run/hold will update display to new value. |

NOTES:

Trigger Jitter Error (in
$$\mu$$
s rms) =
$$\frac{\sqrt{(e_{n'})^2 + (e_{n'})^2 (V)}}{\text{Input slew rate at trigger point } (V/\mu s)}$$

where $e_{n^2}=150~\mu V$ rms typical internal noise $e_{n^2}=$ rms noise of the signal input at the trigger point for a 100 MHz bandwidth.

Trigger slew rate error in
$$\mu s = \frac{\frac{\text{Input hysteresis}}{2}}{|\text{Input slew rate | at trigger point (V/}\mu s)}$$

where Input hysteresis = 30 mV p-p typical.

 $N = Number of periods averaged in PERIOD AVG, or the number of widths averaged in WIDTH AVG <math>\ \square$ or WIDTH AVG $\ \square$.

Time base error is the sum of all errors specified for the time base.

| | TIME BASE | | | | | |
|--------------------------------------|--|---|--|--|--|--|
| Time Base | | | | | | |
| Frequency (at calibration | 10 MHz ± 1 X 10-7 | | | | | |
| Adjustment Resolution | ± 5 X 10 ⁻⁸ | | | | | |
| Temperature Stability (0°C to +50°C) | ±5 X 10 ⁻⁶ (±5ppm) | | | | | |
| Aging | ≤ 1 X 10 ⁻⁶ /yr (≤ 1ppm/yr) | | | | | |
| External Timebase Input | 10 MHz | Must Drive one HC Logic family load plus 100 K pull-down resistor | | | | |
| | | $V_{IH} = 3.7 \text{ V}/40\mu\text{A minimum}$ | | | | |
| | | $V_{IL} = 0.95 \text{ V}/10\mu\text{A} \text{ maximum}$ | | | | |

Table 1-2 ENVIRONMENTAL*

| Characteristics | Description | | | |
|--|---|--|--|--|
| Temperature | | Meets MIL-T-28800B, class 5. | | |
| Operating | 0°C to +50°C | | | |
| Nonoperating | -55°C to +75°C | | | |
| Humidity | 95% RH, 0°C to 30°C 75% RH, to 40°C 45% RH, to 50°C | Meets MIL-T-28800B, class 5. | | |
| Altitude | | Meets MIL-T-28800B, class 5. | | |
| Operating | 4.6 km (15,000 ft) | • | | |
| Nonoperating | 15 km (50,000 ft) | | | |
| Vibration | 0.38 mm (0.015") peak to peak, 5 Hz to 55 Hz, 75 minutes. | Meets MIL-T-28800B, class 5, when installed in qualified power modules. ^b | | |
| Shock | 30 g's (1/2 sine), 11 ms duration, 3 shocks in each direction along 3 major axes, 18 total shocks. | Meets MIL-T-28800B, class 5, when installed in qualified power modules. | | |
| Bench Handling | 12 drops from 45°, 4" or equilibrium, which- ever occurs first. | Meets MIL-T-28800B, class 5 when installed in qualified power modules. ^b | | |
| Packaged Product Vibration and Shock ^c | Qualified under National Safe Transit Associ- ation Preshipment Test Procedures 1A-B-1 and 1A-B-2. | | | |
| Electrostatic Immunity | 20 kV maximum charge applied to instru- ment case. | | | |
| Electromagnetic Compatibility ^a | Within limits of F.C.C. Regulations, Part 15, Subpart J, Class A; VDE 0871; and MIL-461A tests RE01, CE01, CE03, RS01, RS03, CS01, and CS02.* | | | |
| | ENVIRONMENTAL EXCEPTION | ONS | | |
| Temperature During low temperature test 4.5.5.1.3 (b) for class 5, steps 4 and 5 shall be performed be step 2. Also, the instrument shall not be operating during step 6, paragraph 4.5.5.1.3 (e), class While operating, condensed moisture shall not be present on class 5 instruments. Drying or instrument for this class may be performed in a suitable chamber, if necessary. | | | | |

^{*}With power module.

^bRefer to TM 500/5000 power module specifications.

Without power module.

[&]quot;System performance subject to exceptions of power module or other individual plug-ins.

^{*} Within 4 dB of RE02 spec at 140 MHz and 150 MHz.

Table 1-3 PHYSICAL CHARACTERISTICS

| Characteristics | Description | | | |
|-------------------------------|-------------------------------------|--|--|--|
| Finish | | | | |
| Front Panel | Polycarbonate | | | |
| Chassis | Chromate conversion coated aluminum | | | |
| Net Weight (nominal) | 794 g (1 3/4 lbs.) | | | |
| Physical Dimensions (nominal) | | | | |
| Height | 126.0 mm (4.96 inches) | | | |
| Width | 65 mm (2.5 inches) | | | |
| Length | 278.8 mm (10.98 inches) | | | |

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OPERATING INSTRUCTIONS

Introduction

This section of the manual provides operating information required to obtain the most effective performance from the DC 504A. Included is a functional description of the front panel controls and connectors, operating considerations, and basic measurement techniques. Also included are installation instructions and repackaging information.

PREPARATION FOR USE

First Time Inspection

Inspect the instrument for visible damage (dents, scratches, etc.). Keep the original shipping container and packing material for future use. If the instrument is damaged, notify the carrier and the nearest Tektronix Service Center or representative.

Operating and Non-Operating Environments

The instrument can be operated, stored, or shipped within the environmental limits stated in the Specification section of this manual. However, the counter should be protected at all times from temperature extremes which can cause condensation within the instrument.

Rear Interface Considerations

A slot between pins 21 and 22 on the rear connector identifies this instrument as a member of the TM 500 counter family. If the counter is used to build a system, insert a family barrier key (Tektronix Part No. 214-1593-02) in the corresponding position of the selected power module jack to prevent plug-ins belonging to a different family from being used in that compartment of the power module.

WARNING

To avoid electric shock, disconnect the power module power cord before inserting the family barrier key in the power module jack. Refer the barrier key insertion to qualified service personnel.

NOTE

Rear interface information is found in the Maintenance section of this manual. Refer the interface connections to qualified service personnel.

INSTALLATION AND REMOVAL

NOTE

Refer to the Operator's Safety Summary in the front of this manual before installing this instrument in the power module.

Refer to the power module instruction manual and make sure that the line selector block is positioned correctly for the line voltage in use. Check the counter and the power module for the proper fuses. Be certain that the power plug for the power module has the proper grounding conductor.



To prevent damage to the instrument, turn the power module off before installation or removal from the power module. Do not use excessive force to install or remove the instrument from the power module.

Check to see that the plastic barrier keys on the interconnecting jack of the selected power module compartment match the cutouts in the rear interface connector for the counter. If they do not match, do not insert the counter until the reason is investigated.

If the cutouts and barrier keys match, align the chassis of the counter with the upper and lower guides of the selected compartment. See Fig. 2-1. Insert the counter into the compartment and press firmly to seat the rear interface connector. Apply power by operating the POWER switch on the power module.

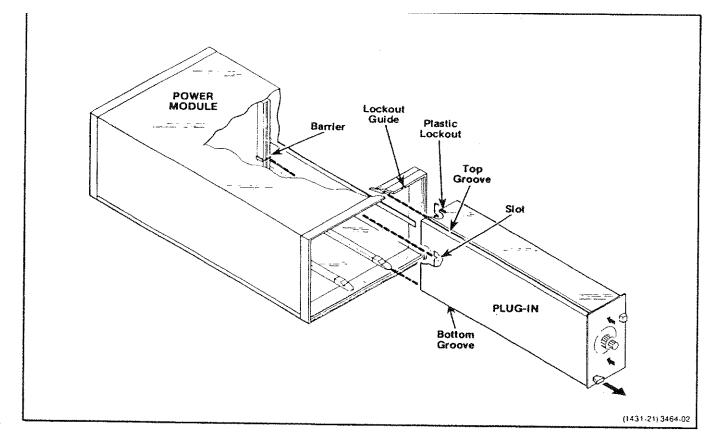


Fig. 2-1. Plug-in installation and removal.

To remove the counter from the power module, turn off the POWER switch, pull the release latch knob (located in the lower left front comer) until the interconnecting jack disengages. Pull the counter straight out of the power module compartment.

CONTROLS AND CONNECTORS

Although the DC 504A is fully calibrated and ready to use, the location and function of the controls and connectors should be reviewed before attempting to operate it. Following is a brief description of the front panel controls and connectors. Refer to Fig. 2-2.

- 1 READOUT DISPLAY—six digit LED readout with automatically positioned decimal point and leading zero suppression. Display reads in KILOHERTZ or MICROSECONDS.
- GATE—indicates the status of the main gate. When illuminated, the gate is open; the instrument is in the process of making a measurement. When extinguished, the gate is closed.

- OVERFLOW—when illuminated, indicates register overflow.
- MULTIPLIER LOCK—illuminated when the Multiplier (Phase Lock Loop) circuit is active. The Multiplier is automatically activated when measuring frequencies between 10 Hz and 25 kHz. This circuit multiplies the measured frequency by 100, providing two additional digits of display resolution.
- 5 FUNCTION—selects the following measurement or counting modes for the instrument.

FREQ TO 10 MHz—measures directly and displays the frequency of input signals up to 10 MHz.

FREQ TO 100 MHz—internally prescales and displays the frequency of input signals up to 100 MHz.

PERIOD—measures and displays the period of the input signal.

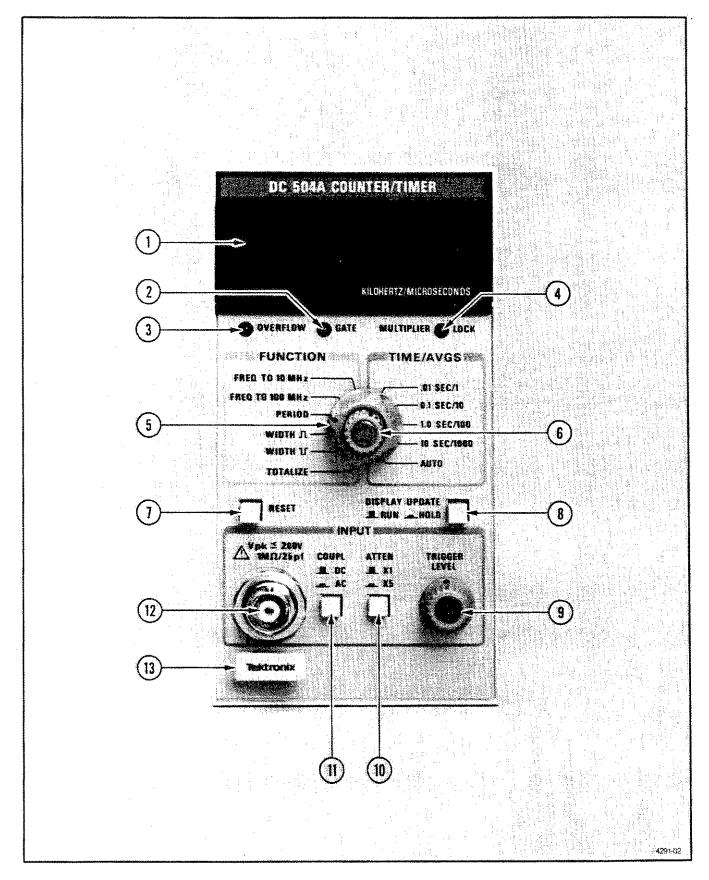


Fig. 2-2. Controls and Connectors.

WIDTH _____measures and displays the time interval between the triggering point on the positive leading edge to the corresponding point on the trailing edge of a pulse applied to the input.

WIDTH _ —measures and displays the time interval between the triggering point on the negative leading edge to the corresponding point on the trailing edge of a pulse applied to the input.

TOTALIZE—pulses applied to the input will be displayed in a running total until the counter is manually reset or register overflow occurs.

- TIME/AVGS—depending on the position of the FUNCTION switch, selects the gate time or the number of measurements to be averaged. In AUTO, a gate time that will display six digits is automatically selected.
- RESET—resets the count to zero when operating in the TOTALIZE mode. Acts as a master reset ensuring that the readout has been cleared before the next measurement. Also provides a check of all display LED's; when pressed and held, a row of 8's is displayed.
- 8 DISPLAY UPDATE—when the button is in the RUN (out) position, the DC 504A counts or makes measurements continuously.

When the button is in the HOLD (in) position and the instrument is in a measurement mode, the last measurement is displayed and no more made until the button is released.

When the instrument is counting (TOTALIZE), moving the button to the HOLD position stops the display only; the count continues to accumulate in the registers. When the button is released, the display is automatically updated to the current count accumulation and continues to run.

TRIGGER LEVEL—selects the amplitude point on the positive or negative slope of the input signal at which the triggering window is placed.

- ATTEN—selects the attenuation factor for the input signal. When the button is in the ×1 (out) position the input signal is not attenuated. The input signal is attenuated by a factor of five when the button is in the ×5 (in) position.
- COUPL—selects the method of coupling the input signal to the counter. When the button is in the DC (out) position, the signal is applied directly. The input signal is capacitively coupled to the input when the button is in the AC (in) position.
- Input Connector to the counter. Input impedance is 1 $M\Omega$ shunted by approximately 25 pF.

Maximum input amplitude is limited to 200 V peak.

Release Latch—disengages the instrument for removal from the power module.

Provisions have been incorporated in the DC 504A to modify the following operating conditions.

Multiplier (PLL)—the instrument is shipped with the multiplier circuit in the enabled condition. This circuit can be disabled if desired.

Time Base—the instrument is shipped with the internal time base connected. This can be disconnected to permit application of an external clock signal via the rear interface.

Signal Input—the instrument is shipped with the front panel input connected. Disconnecting this input allows signal measurements to be made via the rear interface.

WARNING

Refer qualified service personnel to the Maintenance Section to make changes to the above operating conditions.

OPERATING CONSIDERATIONS

INPUT CONNECTIONS

Maximum Safe Input Voltage Limits



CAUTION

To avoid instrument damage, make certain that the input voltages to the front panel connectors or rear interface inputs do not exceed their specified limits. See Specification section.

Be careful with high-frequency, high-amplitude signals. The front panel maximum safe input voltage ($\times 1$ attenuation) is derated linearily from 400 V p-p at 50 kHz to 15 V p-p at 1.33 MHz and higher. Refer to the Specification section.

Connecting External Signal Sources

If a high impedance signal probe is to be used between the front panel bnc connector and the measurement source, use a probe capable of compensating for the input capacitance of the counter (less than 30 pF). A high impedance probe such as the TEKTRONIX P6125, is recommended for all digital logic applications.

Input Coupling, Noise, and Attenuation

You can use either the ac coupling (AC COUPL) or dc coupling (DC COUPL) mode to couple the input signal to the input amplifier. If the signal to be measured is riding on a dc level, its amplitude limits may not fall within the triggering level range. The AC COUPL mode should be used for repetitive signals having a fixed frequency and a constant duty cycle when they are riding on a large dc level.

If the signal duty cycle changes during a measurement, the triggering point will shift, possibly causing erroneous results. Use the DC COUPL mode for low frequency ac signals without large dc offset, signals with a low duty cycle, and during width measurements.

Noise may be coupled to the input amplifier along with the signal to be measured. Noise may originate from the operating environment, the signal source, or be caused by improper connections. If the noise is of sufficient amplitude, it can result in inaccurate measurements due to false triggering. Using an external attenuator may solve the problem. See Fig. 2-3.

The input dynamic range specification describes the largest amplitude signal with a risetime or falltime less than about 5 ns that will not cause ringing and distortion internal to the counter. Ringing may cause mistriggering near the positive or negative peaks of the signal.

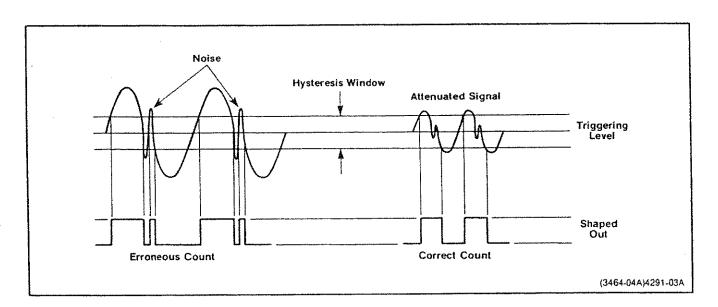


Fig. 2-3. Advantages in signal attenuation.

sensitivity requirements for the AC COUPL and DC COUPL modes (see Specification section). Proper use of the ATTEN (attenuation) control will ensure operation within the maximum limits; ± 2 V for $\times 1$ ATTEN, ± 10 V for $\times 5$ ATTEN.

Triggering

The TRIGGER LEVEL and COUPL controls affect the counter's ability to make a measurement. In general, the trigger controls are similar to oscilloscope controls, except that the end result is not a stable waveform graphic display, but a stable digital frequency display.

Input Coupling Switch. The Input Coupling switch selects ac (capacitive) or dc (direct) coupling for the input signal. Ac coupling is convenient for most frequency measurements to avoid readjusting the TRIGGER LEVEL control for changing dc levels. It does, however, reduce sensitivity to signals below 10 Hz. Thus, for period measurements longer than 0.1 sec, dc coupling should be used.

Trigger Level. The TRIGGER LEVEL control must be properly adjusted for a stable reading. It is not difficult to adjust unless the signal amplitude or frequency is close to (or beyond) the specified limits.

A signal that looks stable on an oscilloscope may still show jitter when measured with a digital counter. If the count varies from reading to reading, it is probably due to jitter in the signal source. If the count changes dramatically, the DC 504A is not being triggered properly, either because the controls are not set right or the signal is beyond the counter's capabilities (too small in amplitude or too high in frequency).

The TRIGGER LEVEL control allows the operator to move the hysteresis window of the trigger circuit to an optimum level on the input signal to ensure stable triggering. The TRIGGER LEVEL control adjusts over a nominal $\pm 2.0~V$ range of the input signal. If a wider range is desirable, use the $\times 5$ input attenuator for $\pm 10~V$ range.

Reducing Measurement Errors

As an aid in reducing measurement errors, keep in mind the following factors:

Use the proper ATTEN control and high impedance attenuator type probes when measuring signals from high impedance circuits.

- Consider trigger errors caused by input signals with slow rise or falltimes.
- Average the measurement over a larger number of cycles of the input signal (greater number of AVERAGES).
- Maintain the counter environment at a constant temperature.
- Apply a 10 MHz external time reference standard to the rear interface inputs.
- Perform internal adjustments, if necessary.

FREQUENCY MEASUREMENTS

Use ac coupling for most frequency measurements to avoid readjusting the LEVEL control because of changing dc levels. Signals less than 4 volts peak-to-peak need not be attenuated; larger signals should be attenuated to within the range of 85 mV to 4 volts peak-to-peak.

Set the FUNCTION switch to FREQ TO 10 MHz and, with the TIME/AVGS switch, select one of the shorter gate times. Connect the signal to be measured to the input and adjust the TRIGGER LEVEL control for a stable display. The level control setting is not critical unless the signal amplitude and frequency are close to specified limits. Fig. 2-4 shows waveform timing during frequency measurement.

Measurement Intervals

To adjust the trigger control, choose a short gate time such as 0.1 or .01 seconds. This gives rapid feedback via the display as to whether or not the counter is being triggered. Final selection of gate time depends upon the frequency being measured, desired resolution, and the time required to make a measurement. A 10 second gate time requires 10 seconds for a measurement to be made and displayed. This gives 0.1 Hz resolution. See Table 2-1.

Overflow

Through intentional use of overflow displays, it is possible to increase the resolution of the counter. Select a gate time that displays the most significant digit as far to the left as possible without overflow. Note the numbers displayed to the right of the decimal. Move the decimal to the left, by selecting longer gate times, until the desired resolution is

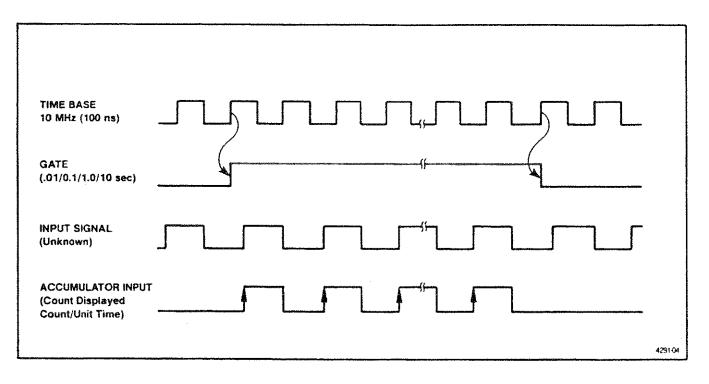


Fig. 2-4. Frequency Measurement.

achieved. The OVERFLOW indicator will light when the most significant digit has overflowed the last storage register. The relationship between gate time and resolution is shown in Table 2-1.

Table 2-1
GATE TIME VS. MEASUREMENT RESOLUTION

| Gate Time | FREQ TO 10 MHz | FREQ TO 10 MHz Multiplier Locked | FREQ TO 100 MHz |
|--------------|-------------------|-------------------------------------|--------------------|
| .01 sec | 100 Hz | 1 Hz | 1 kHz |
| 0.1 sec | 10 Hz | 0.1 Hz | 100 Hz |
| 1.0 sec | 1 Hz | .01 Hz | 10 Hz |
| 10 sec | 0.1 Hz | .001 Hz | 1 Hz |

the DC 504A, because it is multiplied by 100 (the counter is actually measuring 500 kHz), would display 5.00000 kHz with one second of gate time.

Since any frequency within the range of the multiplier will be multiplied, provision has been incorporated to lock out this feature if so desired. Refer qualified service personnel to the Maintenance Section. A front panel LED indicates when the multiplier is locked. The multiplier circuit is only active when the DC 504A is in this mode.

NOTE

When the multiplier is locked and a gate time of 10 Sec is selected, no decimal point appears. The decimal point is implied to the left of the sixth digit (MSD).

Frequencies Lower Than 10 MHz

Frequencies 10 MHz and below are measured with the FUNCTION switch in the FREQ TO 10 MHz position. Frequencies within the range 10 Hz to 25 kHz are automatically multiplied internally by 100 to increase display resolution. This is accomplished by routing the incoming signal through a phase-locked loop multiplier circuit before it is counted. If, for example, a 5 kHz signal is to be measured with a conventional counter, the display would read 5.000 kHz with one second of gate time. The same signal measured with

Frequencies Higher Than 10 MHz

Frequencies between 10 MHz and 100 MHz are measured with the FUNCTION switch in the FREQ TO 100 MHz position. Input frequencies in this range are internally prescaled (divided) by a factor of 10. If, for example, a frequency of 95 MHz is to be measured, the prescaler divides it down so the counter is actually measuring only 9.5 MHz. This, however, also reduces the display resolution by a factor of 10. Resolution can be increased, if desired, by selecting a longer gate time.

PERIOD MEASUREMENTS

The PERIOD mode reverses the functions of signal and clock as compared to the frequency mode. In frequency mode, signal events are counted for some number of clock pulses, then displayed. In PERIOD, clock pulses are counted for some number of signal events then displayed. Refer to Fig. 2-5.

Low Frequencies

Period measurements of signals below 10 Hz, and particularly in the lowest decade from 0.1 Hz to 1.0 Hz, are sensitive to wave shape and amplitude. Since it is desirable for the signal to pass through the trigger hysteresis abruptly, square-wave inputs are preferred. Sine and triangle waves can be measured accurately at the very low end if the input amplitude is kept somewhat above minimum specification so that the trigger input is driven hard.

Period Averaging

The best single shot resolution attainable in a period measurement is a direct function of the speed (frequency) of the time base clock being counted. The DC 504A has a 10 MHz time base; a single period of this time base is 100 ns (period = 1/frequency). Therefore, the resolution of a single period measurement is 100 ns.

Resolution can be increased by utilizing the capability of the DC 504A to average period measurements. Period averag-

ing up to 1000 is attainable, which results in a directly proportional increase in resolution. If, for example, the resolution of a single period measurement is 100 ns, averaging 1000 events results in a 1000 times increase in resolution, or 100 ps.

To illustrate the display readout, assume an input signal with a $1.0032~\mu s$ period. A single period measurement would display $1.0~\mu s$ (100 ns LSD). Averaging 10 periods of this same signal would display $1.00~\mu s$ (10 ns LSD) and 100 periods would display $1.003~\mu s$ (1 μs LSD). With a 1000 period average the display will read $1.0032~\mu s$ (100 ps LSD).

In the AUTO mode, the counter always attempts to fill the display (6 digits) while averaging up to 100 events. Note that periods longer than 100 ms will overflow the display.

WIDTH MEASUREMENTS

The width modes measure the time between two points on a waveform. These two points are selected with the TRIG-GER LEVEL control such that the main gate turns on at the selected level and turns off at the same level but the opposite slope. Refer to Fig. 2-6.

Width Averaging

Averaging can be used to increase the accuracy and resolution of repetitive signal measurements. The basic reason for

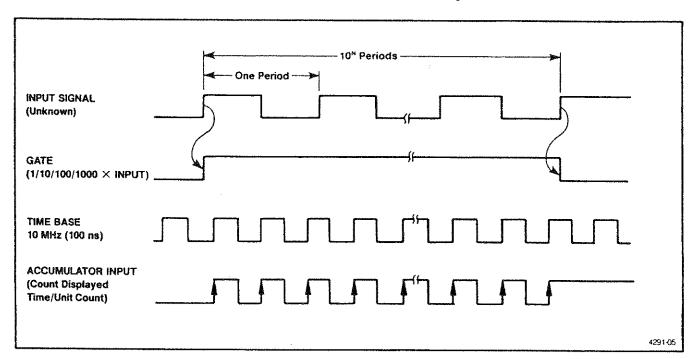


Fig. 2-5. Period Measurement.

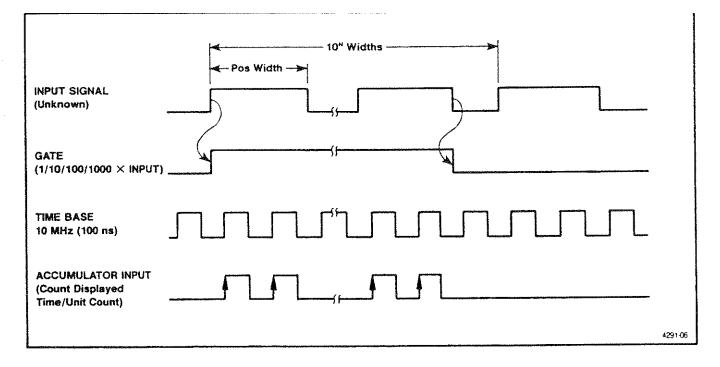


Fig. 2-6. Width Measurement.

averaging is the statistical reduction of the ± 1 count error. If the ± 1 count error is truly random, then as more intervals are averaged, the measurement will tend to approach the true value of the time interval. For time interval averaging to work, the time interval being measured must be repetitive and have a repetition frequency that is nonsynchronous to the counter clock rate.

The DC 504A has the capability of width averaging up to 1000 events. This single input measurement is much easier than typically associated with Universal Time Interval Counters.

NOTE

Width \tag{\textsup} and Width \tag{\textsup} require an arming pulse before a measurement begins. In the case where a stream of pulses is being measured, this presents no problem as the first pulse will arm the measurement, and the next "N" pulses will be measured. If a single pulse is to be measured, the counter can be put into the armed mode by rotating the trigger level completely clockwise, then counter-clockwise until the GATE indicator just turns on (it may require two rotations). The counter is then armed and will measure the next pulse it sees.

TOTALIZING

In the Totalize mode, signal events applied to the INPUT are counted and the accumulated total is displayed until the reset button is pushed or the FUNCTION switch is changed to another position. This mode is a manual analog of the frequency mode. Its main application is to accumulate a count of relatively slow and irregular events.

Starting the Count

Apply the signal to the input connector and set the trigger controls the same as for frequency measurement. Adjust the TRIGGER LEVEL control until the displayed total begins to increment. The accumulated count is displayed in whole numbers. In the Totalize mode, only the TRIGGER LEVEL control, the RESET button and the DISPLAY UPDATE button affect the display.

NOTE

In the TOTALIZE mode, moving the DISPLAY UP-DATE button to the HOLD position stops the display only; the count continues to accumulate in the registers. Releasing the button to the RUN position updates the display to the current register accumulation and the count display continues from there.

REPACKAGING FOR SHIPMENT

Should it become necessary to return the instrument to a Tektronix Service Center for service or repair, attach a tag to the instrument showing the owner (with address) and the name of the individual to be contacted, complete instrument serial number, option number, and a description of the service required.

If the original container and packaging material is unfit for use or not available, repackage the instrument as follows:

- Obtain a carton of corrugated cardboard having inside dimensions no less than six inches more than the instrument dimensions; this will allow for cushioning. The shipping carton test strength for the DC 504A is 200 pounds.
- 2. Surround the instrument with polyethylene sheeting to protect the finish.
- Cushion the instrument on all sides by tightly packing dunnage or urethane foam between carton and instrument, allowing three inches on all sides.
- 4. Seal the carton with shipping tape or industrial staples.
- Mark the shipping carton "FRAGILE INSTRUMENT" to indicate special handling.

THEORY OF OPERATION

Introduction

This section of the manual contains a description of the electrical circuits of the DC 504A. Refer to the block diagram and schematic diagrams on the foldout pages in the rear of the manual to aid in understanding this description. Diamond enclosed numbers appearing throughout this section refer to the schematic diagram on which the circuit being discussed is located. The schematic diagrams are divided with gray-tint blocks according to circuit function. The titles correspond to those shown on the block diagram.

Block Diagram

The block diagram shows the stages and basic interconnections of each major circuit in the instrument. Each circuit is described in detail. Use the block diagram and detailed circuit diagrams for reference.

Input Conditioning (1)



Input signals are applied to front panel connector J4015, or through connections at the rear interface. The position of Input selector jumper P4014 selects either front panel or rear interface input. Input to the rear interface is terminated in 50 Ω (R4015) to allow connections using standard 50 Ω coaxial cable. Input signals pass through DC/AC coupling switch S4024 into a frequency compensated attenuator network. Attenuator switch S4025 is normally in the ×1 position, which allows the signal to pass directly through. Five times attenuation is provided by R4023 and R4024, C4021 and C4025 provide frequency compensation. R4028 is the 1 $\mbox{M}\Omega$ input termination. R4032, R4036, and C4036 serve to limit current to and compensate for capacitance around the gate of Q4022. Overvoltage protection is provided by CR4032 and CR4037. These diodes clamp the signal at approximately ±5.5 V.

A matched pair of FET's, Q4022 and Q4023, form a high impedance differential comparator. Constant current to this amplifier is supplied by Q4021 with associated circuitry. The voltage at the gate of Q4023 is set by the TRIGGER LEVEL control (R4037). This voltage is divided across R4033 and R4034 to approximately $\pm 2.2 \text{ V}$.

The output of the comparator drives a three stage line receiver, the inputs of which are pins 9 and 10 of U3022B. The

first stage matches the impedance of the comparator to the second stage amplifier. U3022A is a voltage amplifier with a gain of approximately three. The third stage, U3022C, is configured as a Schmitt trigger circuit. High frequency peaking is accomplished by C3021. This stage serves to shape the inputs into fast edge outputs which feed to the counter.

Signal Routing (2)



Output from the Schmitt trigger is routed through one of three paths to the counter circuit. Depending on the function or frequency range selected, signals pass directly, through a +10 prescaler, or through a ×100 resolution multiplier (phase-locked loop) to the counter.

DIRECT. This routing to the counter is through a switching circuit composed of U1063A, Q1066, and Q1068. For all signals, except frequencies to be multiplied or divided, or negative pulse measurements, Q1068 turns off and the signal path is through Q1066. When the instrument is set to measure negative pulse width, Q1066 turns off and the signal path is through Q1068. When measuring frequencies higher than 10 MHz, Q1066 and Q1068 are both turned off and the path is through the ÷10 Prescaler, U2067.

The output of the switching circuit is fed to pin 9 of U1063B. The differential outputs of U1063B drive an ECL to TTL converter, Q1062 and Q1064. The converter outputs are inverted through U1048A and U1048B and applied directly to the A and B inputs of the counter, U2047 (Diagram 3).

PRESCALER. Inputs at frequencies from 10 MHz to 100 MHz are routed through a ÷10 prescaler. In this mode, both transistor switches (Q1066 and Q1068) are off and the signal is applied to the input (pin 7) of U2067. This integrated circuit is a ÷10 counter; the output frequency is one-tenth the input frequency. The prescaler output (pin 15) connects to pin 10 of U1063B. The signal then routes through the ECL to TTL converter to the counter circuits. The prescaler is enabled when pin 9 is pulled low through S2061A in the FREQ TO 100 MHz position.

×100 MULTIPLIER. With the FUNCTION switch in the FREQUENCY TO 10 MHz position, inputs ranging between 10 Hz and 25 kHz route to a ×100 Resolution Multiplier (phase-locked loop) circuit. This is an automatic function unless the loop is disabled by moving jumper P1040 (PLL Defeat) to the ground position.

Transistor Q1056 serves as an ECL to TTL converter. The input signal is buffered and inverted by U1052D and fed to pin 14 of U2054. (The output signal from U1052D is +5 V to -5 V). This integrated circuit consists of a phase comparator and voltage controlled oscillator. Only the phase comparator is utilized. The phase of the signal at pin 14 is compared to the phase of the signal at pin 3. The output at pin 13 determines the oscillator frequency. The voltage controlled oscillator (VCO) consists of U1044A, B, C, Q1053 and Q1054.

To understand the operation of the oscillator circuitry, assume that the emitter of Q1054 is at about +5 V. Current flows through U1044A and R1046 charging capacitor C1052. Pin 10 of U1044C is at about +5 V and pin 12 at about -5 V. Q1054 is turned off, with its base at about +5V. The drain of U1044A goes negative at a rate determined by the current flow through it. When the voltage at the drain of U1044A drops to about 0 V, pin 12 of U1044C switches to about +5 V and pin 8 of U1044B goes low turning Q1054 on. As current flows through Q1054, the voltage drop across R1046 increases turning on Q1053. Current flow through Q1053 is much greater than through U1044A and pin 10 of U1044C rises rapidly until U1044C and U1044B change state. This turns off Q1054 and repeats the cycle. The output waveform at the collector of Q1054 is a fast spike from about -5 V to about 0 V. The frequency of the circuit varies from about 500 Hz to about 3.5 MHz. This is accomplished by varying the current through U1044A and consequently the charge time of C1052.

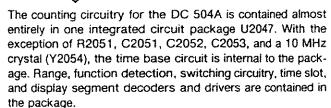
The positive going (-5 V to 0 V) spike, at varying frequencies, feeds to U1052A, is buffered, inverted and applied to the input of U1032 (pin 4). This integrated circuit (U1032A and B) divides the output frequency by 100. The output of U1032 (pin 13) feeds through Q1043, a TTL to MOS converter, to the second input of the phase comparator (U2054 pin 3).

If the frequency of the waveform at the collector of Q1054 goes higher than exactly 100 times the input (pin 14 U2054), the output voltage at pin 13 of U2054 goes more negative, reducing the oscillator frequency until both frequencies are in lock. The oscillator output at pin 3 U1052A feeds through U1052B and U1063C, is converted to ECL levels and applied to the third input, pin 11, of U1063B.

When the circuit is out of lock, pin 1 of U2054 goes low turning Q1057 on and Q1052 off. This results in a high at the output (pin 8) of U1052C. This high is applied to pin 9 of U1031B (Diagram 5) causing its output to go low. This low

at pin 13 of U1048E causes its output to go high extinguishing the MULTIPLIER LOCK indicator (Diagram 4). When the loop is locked, the output of U1052C goes low and the indicator is on.

Counter 3



The external oscillator input to the counter at pin 33 is connected to the buffered internal time base output, pin 38. Counter timing can also be from a clock signal external to the instrument by moving P2042 to the Ext position. This signal is taken from pin 14A on the rear interface and buffered by U2027C.

Variable capacitor C2051 serves to compensate for variations in the 10 MHz crystal and will vary the oscillator frequency several hundred Hertz.

The counter has two inputs for measured events; input A (pin 40) and input B (pin 2). All signals to these inputs come through the ECL to TTL converter circuit (Diagram 2). All events to be counted, except width, are applied to input A. In the width mode, the counter measures the time interval between an event on A input and an event on B input. For example: in the width positive mode, the rising edge of the pulse triggers input A starting the count, and the falling edge triggers input B stopping the count. There are four other inputs that set the counter to measure and display signals applied to inputs A and B. These inputs are: Range (pin 21), Function (pin 4), Control (pin 1), and Ext Decimal Point (pin 20). The counter digit drive (time slot) outputs, through the range and function select circuitry, provide the control signals. This is discussed in more detail under the heading Range and Function Selection.

The Run/Hold function is controlled by front panel pushbutton switch S3032. When the switch is in the RUN (out) position, pin 39 of U2047 is low through Q3031. When the switch is moved to the HOLD (in) position, pin 39 is at +5 V stopping the counter. The last complete measurement made is displayed. When operating in the TOTALIZE mode, activating HOLD stops only the display; the counter continues to accumulate information. Returning to RUN updates the display to the data in the accumulator and the count continues.

The Reset Input, pin 19, is high when the counter is running. Moving S3012A (RESET) to the reset position resets the counter to zero and clears the display. With S3012A in this position, pin 12 of U1031C (Diagram 5) is also pulled low enabling the gate and allowing TS8 to pass through the gate. TS8 is inverted through U1031A and applied to the counter Control Input, pin 1. During TS8, the counter Display Test function is activated and all segments and decimal points in the display are illuminated.

The BCD outputs, pins 6, 7, 17, and 18 are used to detect display zeros. The BCD information is applied to U1037A which triggers the autorange circuitry. Additional details are contained in the discussion on Autoranging.

The Measurement In Progress output at pin 3 is used to drive the front panel GATE indicator. The level at this pin is

low when the gate is open and the counter is making a measurement. This output is buffered and inverted through U1048D. The high output from U1048D turns the pulse stretcher circuit on, Q2023 and Q2027 (Diagram 4), which illuminates the GATE indicator. This circuit lengthens short gate pulses (to approximately 50 ms) so that the GATE indicator is on long enough to be visible.

The STORE (pin 5) and RESET (pin 32) outputs latch and reset the autorange circuit. See Autorange. Refer to Fig. 3-1 for the Gate, Store, and Reset relationship.

The digit select and segment drive outputs drive the display elements directly. However, because these outputs are neither TTL nor CMOS compatible, they are routed through level shift circuitry to drive the Range and Function Select components. The level shift circuit consists of a pair of

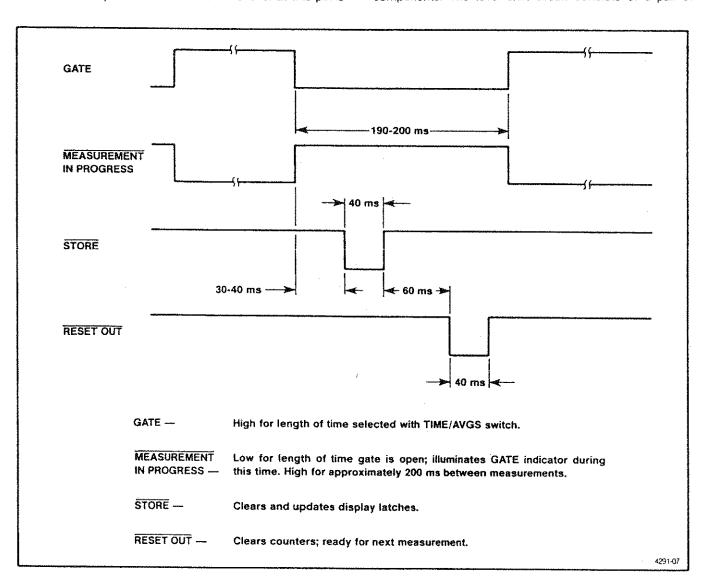


Fig. 3-1. Relationship of display update and counter reset signals.

guad-comparators U2043 and U2045. The reference voltage (minus input) of each unit is set at +2.5 V through divider R2034 and R2035. The open collector output of each device is pulled up to +5 V through 10 k Ω resistors, R1043B through I. The outputs of these comparators drive Multiplexer U1012 and the Function Select circuitry (Diagram 5).

Function, Range, & Decimal Point Select (5)



Function and range selection in the DC 504A is accomplished through a combination of switch closures and counter time slot routing. Table 3-1 shows the relationship between function, range, time slot output, and counter input.

Function Select. Time slot switching logic for function selection is provided by U1036. One input of each of the gates is controlled by front panel FUNCTION switch S2061A. The other input of each gate is controlled by time slot output from the counter, U2047. FUNCTION switch closures are grounded through Q2031 and the time slot signals are active low.

To understand the switching action of the function select circuit, assume the FUNCTION switch is in the PERIOD position. In this position, pin 2 of U1036A is pulled low. This allows TS8 (Time Slot 8) to pass through the gate to pin 10 of U1037B. The output of U1037B drives pin 4 of the counter, U2047 (Diagram 3), setting it to the Period mode.

In like manner each of the other functions is selected and routed to the counter Function Input.

Range Select. Range selection is accomplished by routing the time slots through multiplexer U1012. Manual range selection is via the front panel TIME/AVGS switch, S2061B, which controls the A and B select line inputs to the multiplexer. All time slot switching is internal to U1012. The x output, pin 13, goes directly to the counter Range input, pin 21, U2047.

Decimal Point Logic. The display decimal point is placed automatically by the counter (U2047) for all measurement functions applied directly to the counter inputs. For those functions that are multiplied or divided prior to measurement, decimal point positioning is accomplished through selected time slot application to the counter Ext D.P. Input, pin 20. This input is enabled during TS3 at the counter Control Input, pin 1. TS3 is controlled and gated through U1034C and D. During TOTALIZE and measurement of PERIOD, WIDTH, and FREQ TO 10 MHz (with the multiplier off), pin 8 of U1034C is held low preventing TS3 from enabling the counter Control Input. During these measurements, circuitry internal to the counter sets the decimal point.

When measuring frequencies within the range of the Multiplier circuit, the display decimal point must be shifted left two digits. Pins 8 and 9 of U1031B are pulled low setting the output, pin 10, high. Pin 8 of U1025C is driven high, disabling the gate. The high output of U1031B is also inverted

Table 3-1 COUNTER INPUT, FUNCTION/RANGE SELECT, AND TIME SLOT RELATIONSHIPS

| COUNTER INPUT PIN # | FUNCTION/RANGE | TIME SLOT (DIGIT) | | |
|---|-------------------------------------|--------------------------------------|--|--|
| FUNCTION INPUT | FREQUENCY | TS1 (D0) | | |
| PIN 4 | PERIOD | TS8 (D7) | | |
| | WIDTH | TS5 (D4) | | |
| | TOTALIZE | TS4 (D3) | | |
| RANGE INPUT | (TIME/AVGS) | | | |
| PIN 21 | .01 SEC/1 | TS1 (D0) | | |
| • | 0.1 SEC/10 | TS2 (D1) | | |
| | 1 SEC/100 | TS3 (D2) | | |
| | 10 SEC/1000 | TS4 (D3) | | |
| CONTROL INPUT | EXT OSC ENABLE | TS1 (D0) | | |
| PIN 1 | EXT D.P. ENABLE | TS3 (D2) | | |
| | DISPLAY TEST | TS8 (D7) | | |
| EXTERNAL DECIMAL POINT INPUT PIN 20 | Decimal point is output for same ti | me slot (digit) that is connected to | | |

through U1048E driving pin 5 of U1025B low to enable the gate. The low output of U1048E also drives pin 4 of U1026A low switching its output high. The high now at pin 8 of U1034C enables the gate and TS3 passes to pin 1 of the counter. This enables the Ext D.P. Input. Depending on the range (gate time) selected, TS4, 5, 6, or 7 gates through U1025B to U1025D. The time slot now at U1025D (pin 11) is applied to the Ext D.P. Input (pin 20) of the counter.

Since frequencies above 10 MHz are divided by ten prior to counting, the display decimal point must be shifted one digit to the right. During this condition, pin 5 of U2026A is pulled low through S2061A forcing the output high. This sets pin 8 of U1034C high to gate TS3 through to the counter Control Input, pin 1. This enables the Ext D.P. Input. Pin 8 of U1031B is high during these measurements, and the output remains low. The low output from U1031B sets pin 8 of U1025C low enabling this gate. The low output from U1031B is inverted through U1048E and applied to pin 5 of U1025B disabling this gate. The low output from U1025B enables U1025D and, depending on the range (gate time) selected, gates TS1, 2, 3, or 4 through to the Ext D.P. Input (pin 20) of the counter. Refer to Table 3-2 for Time Slot (TS) to decimal point relationships.

Autorange (5)

In the Auto mode, the front panel TIME/AVGS switch (S2061B) is disconnected from the multiplexer (U1012) control inputs. In this mode, the output of the autorange circuit controls the inputs to the multiplexer. Setting S2061B to the AUTO position pulls pin 2 of U2027A low through Q2032. This switches the output high enabling the autorange circuit.

Output from pin 1 of U2027A drives pin 2 of U1034A high switching the output low, removing the resets on U1011A and U1011B. The reset caused the Q outputs, pin 2 and pin 14, to be high. With pin 10 of U2026B and pin 12 of U2026C high (enabled) by U2027A, the high levels at pins 9 and 13 switch the output of these gates low. The low outputs from U2026B and U2026C drive the control inputs of U1012 low. This causes time slot one (TS1) to appear at the x output, pin 13. With TS1 applied to the Range Input, pin 21 of U2047, the counter selects the shortest range, .01 sec. A measurement is made and the result displayed. If the displayed result does not fill digit six (MSD), U1037A (Diagram 3) detects all lows on its inputs, during TS6, causing the output to go high (display zero). The high at pin 1 of U1037A is applied to the Data input, pin 9, of U1024B. The leading edge of TS6 triggers the input of a one shot multivibrator, pin 5 of U1023A. About halfway through TS6 (approximately 125 μ s) the \overline{Q} output, pin 7, of U1023A goes high. This high is applied to the Clock input, pin 11 of U1024B, which latches the high present on the Data input. Since U1024B is in a set state, latching a high on the Data causes no change in state and the Q output, pin 12, remains low. This low is inverted through U2027B driving the J and K inputs of U1011A high and putting the flip-flop in the toggle state. The Store pulse from pin 5 of the counter, U2047, is applied to the CLOCK input, pin 3, causing U1011A to change state. U1011A Q, pin 2, switches from high to low driving pin 13 of U2026C low. The output of U2026C switches from low to high driving the A input, pin 10, of the multiplexer high. This change in the control input causes TS2 to appear at the output, pin 13, which is applied to the Range input of the counter. The counter selects the next longer gate time, 0.1 sec, and another measurement is made and displayed. If the second gate time selected is still too short to fill the sixth digit (MSD), the events are repeated and TS3 selects the next longer gate time, 1 sec.

Table 3-2
TIME SLOT TO DECIMAL POINT RELATIONSHIP

| TIME/AVGS | | FUNCTION | | | | | | | |
|-----------------|-----------------------------------|--------------------|--------------|--------------------|-----------------------------------|--------------------|--------------|---------|--|
| | FREQ TO 10 MHz PERIOD WIDTH | | 1 | | FREQ TO 100 MHz (+10 PRESCALE) | | TOTALIZE | | |
| | TIME SLOT | DISPLAY DECIMAL | TIME SLOT | DISPLAY DECIMAL | TIME SLOT | DISPLAY DECIMAL | TIME SLOT | DISPLAY | |
| .01 SEC/1 | TS2 | 0.0 | TS4 | 0.000 | TS1 | , 0 . | TS1 | 0. | |
| 0.1 SEC/10 | TS3 | 0.00 | TS5 | 0.0000 | TS2 | 0.0 | TS1 | 0. | |
| 1.0 SEC/100 | TS4 | 0.000 | TS6 | 0.00000 | TS3 | 0.00 | TS1 | 0. | |
| 10 SEC/1000 | TS5 | 0.0000 | TS7 | °000000 | TS4 | 0.000 | TS1 | 0. | |
| EXT D.P. ACTIVE | | NO | | YES | | YES | | NO | |

^{*}Decimal point implied to left of digit six.

When the counter selects a gate time that results in the display of digit six at least one of the BCD lines driving U1037A (Diagram 3) will be high and the output, pin 1, is low driving the Data input, pin 9, of U1024B low. TS6 triggers the input of U1023A causing the \overline{Q} output to go high. This high is applied to the Clock input of U1024B. The high Clock input latches the low on the Data input causing a change in state. The \overline{Q} output switches from low to high. This high at pin 5 of U2027B causes the output to go low driving the J and K inputs of U1011A low. With the J and K inputs held low, the \overline{S} tore pulse from the counter cannot toggle the device. No change at the input of U1012 results in no change in time slot output. Measurements will continue using the last gate time selected.

The Autorange circuit prevents the counter advancing to the 10 sec gate time. If the 1 sec gate time is too short to fill digit six, measurements continue in this gate time, displaying as many digits as time allows. Conditions at the output of U1011B when the 1 sec gate time was selected, prevent advancement to the 10 sec time. When the 1 sec gate time is selected, the Q output, pin 15, of U1011B switches high. This high is inverted through U2027B, driving the J and K inputs of U1011A low, disabling the device. With the J and K inputs low, the Store pulse from the counter does not cause a change in state. The $\overline{\rm Q}$ output remains high, U2026C output remains low, no new time slot information is sent from U1012, and the counter continues measuring in the 1 sec range.

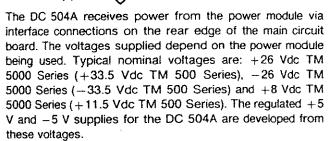
Overflow conditions (when the counter tries to display digit seven) are detected during TS7. When an overflow condition occurs, the Data input, pin 5, of U1024A goes low through Q1025 (Diagram 3). TS7 triggers the input to U1023B causing the Q output to go low for approximately 125 µs, then returns to the high state. This high at the Clock input, pin 3 of U1024A, latches the low on the Data line and toggles the device causing the Q1 output to go low. This low at pin 1 of U1034A causes the output to go high. This high resets U1011A and U1011B, causing their Q outputs to go high. These highs are inverted through U2026B and U2026C. The output from these gates drives the multiplexers (U1012) control inputs low causing TS1 to appear at the output, pin 13. TS1 at the Range input, pin 21, sets the counter to the shortest (.01 sec) gate time. The counter progresses through the succeeding longer ranges as previously described.

Display 4

The display consists of six common cathode seven segment LED's. Digit select time slot pulses (TS1 through TS8) are

generated within counter U2047 (Diagram 3). Individual segment drive (a through f and dp) is also generated within the counter. The OVERFLOW indicator, DS2011, connects to the seventh digit position. Whenever time slot 7 (TS7) and either segment line b or f are active this LED illuminates indicating a display overflow condition. Capacitor C2031, one section of which is connected to each time slot line, serves to suppress any noise spikes that might result in . erroneous displays.

Power Supplies 3



The +5 V supply, except for a series pass transistor located in the power module, is contained almost entirely within regulator package U2013. This regulator package contains a reference, operational amplifier, and current limiting elements. The regulator is powered by the fused +26 V/+33.5 V supply from the power module. The regulated +5 V is developed from fused +8 V/+11.5 V furnished by the power module.

The output of U2013 drives the series pass transistor. The regulator reference voltage, +7.15 V (nominal), is divided to +5.00 V by R3012 and R3015 and connected to pin 5 (V $_{\rm ref}$ In). Frequency compensation for the regulator is provided by R3014 and C3013. The 0.3 Ω resistor, R2016 in the emitter circuit of the series pass transistor, is the external current sensing element. Should the current flow through R2016 reach approximately 2 A, the sensing and drive circuitry within the regulator reduce base drive to the series pass transistor. This results in reduced supply output and shutdown if current demand rises sufficiently.

The entire -5 V supply, except filter capacitors C2014 and C3014, is contained within regulator package U2014. This regulator receives supply voltage from the fused power module -26 V/-33.5 V supply and is completely self contained.

PERFORMANCE CHECK PROCEDURE

Introduction

This procedure checks the electrical performance requirements as listed in the Specification section in this manual. Perform the Adjustment procedure if the instrument fails to meet these checks. In some cases, readjustment may not correct the discrepancy; circuit troubleshooting is then indicated. Also, use this procedure to determine acceptability of performance in an incoming inspection facility.

Adjustment Interval

To ensure instrument accuracy, check the performance every 2000 hours of operation or at a minimum of every 12 months if used infrequently. Allow 30 minutes warm up time prior to performing any checks.

Services Available

Tektronix, Inc. provides complete instrument repair, adjustment, and performance verification at local field service centers and at the factory service center. Contact your local Tektronix field office or representative for further information.

Test Equipment Required

The test equipment (or equivalent) listed in Table 4-1 is suggested to perform the Performance Check and Adjustment Procedures.

Table 4-1
LIST OF TEST EQUIPMENT REQUIREMENTS

| Description | Performance Requirements | Perf. Check | Adj. Proc. | Example | | |
|--|--|-------------------------------|--------------------------|--------------------------------|--|--|
| Power Module | | X | X | TEKTRONIX TM 506 or TM 5006 | | |
| Oscilloscope Mainframe | Dc to 250 MHz bandwidth | x | | TEKTRONIX 7704A | | |
| Vertical Plug-In | Bandwidth, dc to 200 MHz | X | | TEKTRONIX 7A16A | | |
| Horizontal Plug-In | Fastest sweep rate 10 ns | x | allow Waret damples than | TEKTRONIX 7B80 | | |
| Leveled Sinewave Generator | Calibrated amplitude > 135 MHz | X | | TEKTRONIX SG 503 | | |
| Pulse Generator | Risetime < 1 ns | Х | | TEKTRONIX PG 502 | | |
| Function Generator | Range, Sinewave 10 Hz to 1 MHz; Offset +7.5 V level | X | | TEKTRONIX FG 501A | | |
| Digital Multimeter | 4½ digits, 0.5% | × | | TEKTRONIX DM 501A | | |
| WWVB (60 kHz) Receiver/Frequency Standard | 1 MHz ±1×10 ⁻⁹ output | X | × | SPECTRACOM CORP Type 8161 | | |
| 50 Ω Feedthrough Termination | Bnc connectors | X | X | Tektronix Part No. 011-0049-01 | | |
| Coaxial cable, 50 Ω Precision 36 inch | Bnc connectors | Х | X | Tektronix Part No. 012-0482-00 | | |
| Adapter, Bnc Female to Dual Banana | | x | | Tektronix Part No. 103-0090-00 | | |
| 50 Ω, 10× Attenuator | Bnc connectors | x | | Tektronix Part No. 011-0059-02 | | |
| 50 Ω, 5× Attenuator | Bnc connectors | X Tektronix Part No. 011-0060 | | Tektronix Part No. 011-0060-02 | | |
| Flexible Extender | | | X | Tektronix Part No. 067-0645-01 | | |

1. Check Display

Test Equipment Required:

Function Generator 50 Ω Termination ×10 Attenuator

a. Set the DC 504A controls as follows:

FUNCTION TOTALIZE
TIME/AVGS AUTO
COUPL DC
ATTEN X1

- b. Set the function generator to produce a 2 Hz sine wave with an amplitude of approximately 5 yolts and zero offset (into 50 $\Omega).$
- c. Connect the function generator output, through a $\times 10$ attenuator and 50 Ω termination, to the DC 504A input.

- d. Reset the DC 504A by pushing the RESET button.
- e. CHECK—that the least significant digit (far right) in the DC 504A display counts from 0 to 9 and carries to the next digit.
- f. Set the function generator to 20 Hz.
- g. CHECK—that the second digit in the DC 504A display counts from 0 to 9 and carries to the third digit.
- h. Increase the function generator frequency in decade steps until all six digits in the display have been checked.
- i. CHECK—that the OVERFLOW light on the DC 504A comes on after the most significant digit (far left) has counted to 9.

- j. Set the DC 504A DISPLAY UPDATE switch to the HOLD position.
- k. CHECK—that the DC 504A display remains stable.
- I. Set the DC 504A DISPLAY UPDATE switch to the RUN position.
- m. CHECK-that the DC 504A display indicates a new number and continues counting from there.
- n. Set the function generator frequency to 200 kHz.
- o. Set the DC 504A FUNCTION switch to FREQ TO 10 MHz and the TIME/AVGS switch to the .01 SEC/1 position.
- p. CHECK—that the DC 504A display reads approximately 200.0 kHz.
- q. Rotate the DC 504A TIME/AVGS switch clockwise through each position.
- r. CHECK-that the DC 504A display indicates one additional digit of resolution for each succeeding switch position. In the 10 SEC/1000 position the OVERFLOW light will be On.
- s. CHECK—that the DC 504A display reads approximately 200.000 kHz with the TIME/AVGS switch in the AUTO position.

NOTE

Stability of the display will depend on stability of the signal source used.

- t. Push the RESET button and check that the display shows all 8's with all decimal points illuminated.
- u. Remove all connections for the next step.

2. Check Time Base Oscillator Frequency

Test Equipment Required:

1 MHz Frequency Standard 50 Ω Termination

a. Set the DC 504A controls as follows:

TRIGGER LEVEL

FUNCTION FREQ TO 10 MHz TIME/AVGS 1.0 SEC/100 COUPL DC ATTEN $\times 1$

b. Connect a coaxial cable and 50 Ω termination from the 1 MHz frequency standard to the DC 504A input connector.

midrange

- c. Adjust the DC 504A TRIGGER LEVEL control for a stable display.
- d. CHECK-that the DC 504A display reads between 999.994 and 000.006 (± 5 ppm ± 1 count). The OVER-FLOW light will be on if the count is greater than 999,999.
- e. Remove this connection for the next step.

3. Check Input Impedance

Test Equipment Required:

Digital Multimeter 50 Ω Termination

a. Set the DC 504A controls as follows:

FUNCTION TIME/AVGS FREQ TO 10 MHz

0.1 SEC/10

COUPL

DC

ATTEN $\times 1$

- b. Connect the BNC Female to Dual Banana adaptor to the Digital Multimeter with the adaptors GND connected to the HI input of the meter. Connect the DC 504A to the meter. Set the Digital Multimeter to read 1 M Ω .
- c. CHECK-that the digital multimeter display reads between .990 M Ω and 1.010 M $\Omega.$
- d. Set the DC 504A ATTEN switch to the $\times 5$ position.
- e. CHECK-that the digital multimeter display reads between .990 M Ω and 1.010 M Ω .
- f. Return the DC 504A ATTEN switch to the ×1 position.
- g. Remove all connections for the next step.

4. Check Attenuator

Test Equipment Required:

Pulse Generator Digital Multimeter ×5 Attenuator 50 Ω Termination

a. Set the DC 504A controls as follows:

FUNCTION TIME/AVGS

PERIOD AUTO

COUPL

DC ×1

TRIGGER LEVEL

fully clockwise

- b. Set the pulse generator for manually triggered output.
- c. Connect the pulse generator, through a 50 Ω termination and $5\times$ attenuator, to the digital multimeter.
- d. Adjust the pulse generator output for approximately 1 volt reading on the multimeter. Note the reading. (The Pulse Generator is used as a voltage source in this case.)
- e. Move the connection from the multimeter to the DC 504A input.
- f. Press the DC 504A RESET button.
- g. Adjust the DC 504A TRIGGER LEVEL control counterclockwise until the GATE light just comes on.
- h. Repeat steps 4f and 4g several times to arrive as close as possible to the point where the GATE light just turns on.
- i. Set the DC 504A ATTEN switch to the $\times 5$ position.
- j. Remove the $\times 5$ attenuator from the test set up and reconnect the cable.
- k. Press the DC 504A RESET button.
- Adjust the pulse generator output control clockwise until the DC 504A GATE light just comes on.

- m. Repeat steps 4k and 4l several times to arrive as close as possible to the point where the GATE light just comes on.
- n. Move the connection from the DC 504A to the multimeter.
- o. Note the multimeter reading.
- p. Divide the reading obtained in step 4o by the reading obtained in step 4d.
- q. CHECK—that the result obtained in step 4p is between 4.90 and 5.10.
- r. Remove these connections for the next step.

5. Check Low Frequency Stability

Test Equipment Required:

Function Generator 50 Ω Termination

a. Set the DC 504A controls as follows:

FUNCTION

FREQ TO 10 MHz

TIME/AVGS COUPL AUTO

ATTEN

DC X1

TRIGGER LEVEL

midrange

- b. Set the function generator controls to produce a 25 kHz sine wave with an amplitude of 60 mV centered around 0 volts. Attenuate the output if necessary.
- c. Connect the function generator output, through a 50 Ω coaxial cable and 50 Ω termination, to the DC 504A INPUT connector.
- d. Adjust the DC 504A TRIGGER LEVEL control for a stable display.
- e. CHECK—that the DC 504A display reads approximately 25.0000 kHz and the MULTIPLIER LOCK light is on. The display must be stable within 100 counts.

- f. Readjust the function generator controls to produce a 10 Hz sine wave.
- g. Adjust the DC 504A TRIGGER LEVEL control for a stable display.
- h. CHECK—that the DC 504A display reads approximately .01000 kHz and the MULTIPLIER LOCK light is on. The display must be stable within 10 counts.
- i. Set the function generator dc offset to a level at least 0.5 volts negative.
- j. CHECK-that the DC 504A display reads .000 kHz and the MULTIPLIER LOCK light is off.
- k. Set the DC 504A COUPL switch to AC.
- I. CHECK—that the DC 504A display is stable at approximately .01000 kHz and the MULTIPLIER LOCK light is on.
- m. Remove these connections for the next step.
- 6. Check High Frequency Stability

Test Equipment Required:

Sine Wave Generator 50 Ω Termination

a. Set the DC 504A controls as follows:

FUNCTION

FREQ TO 100 MHz

TIME/AVGS

AUTO

COUPL

ATTEN

DC $\times 1$

- b. Set the sine wave generator to produce a 100 MHz signal with a peak-to-peak amplitude of 70 mV centered around 0 Volts.
- c. Adjust the DC 504A TRIGGER LEVEL for a stable display.
- d. CHECK—that the DC 504A display reads approximately 100000, kHz and is stable within one count.

- e. Set the sine wave generator amplitude to 4.0 V.
- f. CHECK-that the DC 504A display reads approximately 100000, kHz and is stable within one count.
- g. Set the sine wave generator frequency to 10 MHz and the DC 504A FUNCTION switch to FREQUENCY TO 10 MHz.
- h. CHECK—that the DC 504A display reads approximately 10000.0 kHz and is stable within one count.
- i. Set the sine wave generator amplitude to 70 mV.
- CHECK—that the DC 504A display reads approximately 10000.0 kHz and is stable within one count.
- k. Set the DC 504A FUNCTION switch to TOTALIZE.
- I. CHECK-that the DC 504A display is advancing (digits will appear blurred and dim).
- m. Leave these connections for the next step.

7. Check Period and Width

Test Equipment Required:

Pulse Generator

50 Ω Termination

X10 Attenuator

a. Set the DC 504A controls as follows:

FUNCTION

PERIOD

TIME/AVGS

AUTO

COUPL

DC

ATTEN

 $\times 1$

- b. Set the pulse generator to produce a 2.55 MHz square wave with an amplitude of 60 mV p-p.
- c. CHECK—that the DC 504A display reads approximately .392 μ s and is stable within one count. Note the reading.

- d. Set the DC 504A FUNCTION switch to WIDTH ____ .
- e. CHECK—that the DC 504A display reads approximately .200 μs and is stable within $\pm\,15$ counts. Note the reading.
- f. Set the DC 504A FUNCTION switch to WIDTH __.
- g. CHECK—that the DC 504A display reads approximately .200 μs and is stable within $\pm\,15$ counts. Note the reading.

h. The sum of the readings obtained in steps 8e and 8g should be equal to the reading obtained in step 8c $\pm .040~\mu s.$

This completes the performance check procedure for the DC 504A; remove all connections.

ADJUSTMENT PROCEDURE

Introduction

Use this Adjustment Procedure to restore the DC 504A to original performance requirements. This Adjustment Procedure need not be performed unless the instrument fails to meet the Performance Requirements of the electrical characteristics listed in the Specification section, or if the Performance Check procedure cannot be completed satisfactorily. If the instrument has undergone repairs, the Adjustment Procedure is recommended. Allow thirty minutes warmup time for operation to specified accuracy (sixty minutes after storage in a high humidity environment).

Satisfactory completion of all adjustment steps in this procedure assures that instrument performance will meet the Performance Requirements.

Test Equipment Required

The test equipment (or equivalent) listed in Table 4-1 is required for adjustment of the DC 504A. Specifications given for the test equipment are the minimum necessary for accurate adjustment. All test equipment is assumed to be correctly calibrated and operating within specifications.

If other test equipment is substituted, the adjustment setup may need to be altered to meet the requirements of the equipment used.

Preparation

Access to the internal adjustments is achieved most easily when the DC 504A is connected to the power module with a flexible plug-in extender. Remove the left side cover of the DC 504A to reach the adjustments on the main board. Refer to the Adjustment Locations in the pullout pages at the rear of this manual.

NOTE

Make adjustments at an ambient temperature between +20°C and +30°C.

1. Adjust Time Base Frequency—C2051

Test Equipment Required:

1 MHz Frequency Standard 50 Ω Termination

a. Set the DC 504A controls as follows:

FUNCTION TIME/AVGS FREQ TO 10 MHz 10 SEC/1000

COUPL ATTEN

DC ×1

TRIGGER LEVEL

midrange

- b. Connect a coaxial cable and 50 Ω termination from the 1 MHz frequency standard to the DC 504A input connector.
- c. Adjust the DC 504A TRIGGER LEVEL control for a stable display.
- d. ADJUST—C2051 (located on the main board) until the DC 504A display reads between 99.9998 and 00.0002 (±0.1 ppm ±1 count). The OVERFLOW light will be on.

This completes the adjustment procedure; remove all connections.

MAINTENANCE

Static-Sensitive Components



Static discharge may damage semiconductor components in this instrument.

This instrument contains electrical components that are susceptible to damage from static discharge. See Table 5-1 for relative susceptibility of various classes of semiconductors. Static voltages of 1 kV to 30 kV are common in unprotected environments.

Observe the following precautions to avoid damage:

- 1. Minimize handling of static-sensitive components.
- Transport and store static-sensitive components or assemblies in their original containers, on a metal rail, or on conductive foam. Label any package that contains staticsensitive assemblies or components.
- 3. Discharge the static voltage from your body by wearing a grounded wrist strap while handling these components. Servicing static-sensitive assemblies or components should be performed only at a static-free work station by qualified service personnel.
- 4. Nothing capable of generating or holding a static charge should be allowed on the work station surface.
- 5. Keep the component leads shorted together whenever possible.
- 6. Pick up components by the body, never by the leads.
- 7. Do not slide the components over any surface.

- 8. Avoid handling components in areas that have a floor or work surface covering capable of generating a static charge.
- 9. Use a soldering iron that is connected to earth ground.
- Use only special antistatic suction type or wick type desoldering tools.

Test Equipment

Before using any test equipment to make measurements on static-sensitive components or assemblies, be certain that any voltage or current supplied by the test equipment does not exceed the limits of the component to be tested.

Table 5-1
RELATIVE SUSCEPTIBILITY
TO STATIC DISCHARGE DAMAGE

| Semiconductor Classes | | Relative Susceptibility Levels* | | |
|-----------------------|--------------------|---------------------------------|--|--|
| MOS or CMOS m | 1 | | | |
| discretes, or linear | microcircuits with | | | |
| MOS inputs. | (Most Sensitive) | | | |
| ECL | 2 | | | |
| Schottky signal die | 3 | | | |
| Schottky TTL | | 4 | | |
| High-frequency bip | oolar transistors | 5 | | |
| JFETs | | 6 | | |
| Linear microcircuit | s | 7 | | |
| Low-power Schot | tky TTL | 8 | | |
| TTL | (Least Sensitive) | 9 | | |
| *Voltage equivalent | for levels: | | | |
| 1 = 100 to 500 V | 4 = 500 V | 7 = 400 to 1000 V | | |
| | | (est.) | | |
| 2 = 200 to 500 Y | 5 = 400 to 600 V | 8 = 900 V | | |
| 3 = 250 V | 6 = 600 to 800 V | 9 = 1200 V | | |

(Voltage discharged from a 100 pF capacitor through a resistance of 100 $\Omega_{\rm c}$)

Cleaning Instructions

This instrument should be cleaned as often as operating conditions require. Accumulation of dirt on components acts as an insulating blanket and prevents efficient heat dissipation that can cause overheating and component breakdown.



Avoid the use of chemical cleaning agents that might leave a film or damage the plastic material used in this instrument. Use a nonresidue type of cleaner, preferably, isopropyl alcohol or totally denatured ethyl alcohol. Before using any other type of cleaner, consult your Tektronix Service Center or representative.

Exterior. Loose dust accumulated on the front panel can be removed with a soft cloth or a small brush. Dirt that remains can be removed with a soft cloth dampened with a mild detergent and water solution. Abrasive cleaners should not be used.

Interior. Dust in the interior of the instrument should be removed occasionally, due to its electrical conductivity under high humidity conditions. The best way to clean the interior is to blow off the accumulated dust with dry, low pressure air, then use a soft brush. If further cleaning is required, use a mild detergent and water solution, flushing well with clean water.

CAUTION

Do not clean the circuit board with any solvent, unless the pushbutton switches and FUNCTION and TIME/AVGS switch are removed first. Any solvent forced or carried under the switches can remove the lubricants and cause intermittent operation. Circuit boards and components must be dry before applying power to prevent damage from electrical arcing.

Drying can be accomplished with dry, low-pressure air or by placing in an oven at 40°C to 60°C for approximately four hours.

After making minor board repairs, cleaning is best accomplished by carefully flaking or chipping the solder flux from the repaired area.

Isopropyl alcohol can be used to clean major repairs to the circuit board; however, flush the board well with clean, isopropyl alcohol. Make certain that resin or dirt is carefully

removed from the board. Avoid contact with switches (see CAUTION above).

Obtaining Replacement Parts

Electrical and mechanical parts can be obtained through your local Tektronix Field Office or representative. However, many of the standard electronic components can be obtained from a local commercial source. Before purchasing or ordering parts from a source other than Tektronix, Inc., check the Replaceable Electrical Parts list for the proper value, rating, tolerance, and description.

Ordering Parts

When ordering replacement parts from Tektronix, Inc., it is important to include all of the following information.

- 1. Instrument type (include modification or option numbers).
- 2. Instrument serial number.
- A description of the part (if electrical, include the component number).
- 4. Tektronix part number.

Soldering Techniques

WARNING

To avoid electric shock hazard, disconnect the instrument from the power source before soldering.

The reliability and accuracy of this instrument can be maintained only if proper soldering techniques are used when repairing or replacing parts. General soldering techniques which apply to maintenance of any precision electronic equipment should be used when working on this instrument. Use only 60/40 rosin-core, electronic grade solder. The choice of soldering iron is determined by the repair to be made.

When soldering on circuit boards or small wiring, use only a 15 watt, pencil type soldering iron. A higher wattage soldering iron can cause the etched circuit wiring to separate from the board base material and melt the insulation from small wiring. Always keep the soldering iron tip properly tinned to ensure the best heat transfer to the solder joint. Apply only enough heat to remove the component or to make a good solder joint. To protect heat sensitive components, hold the component lead with a pair of long-nose pliers between the component body and the solder joint. Use a solder removing wick to remove excess solder from connections or to clean circuit board pads.

Interconnecting Pins

Several methods of interconnection are used to electrically connect the circuit boards with the other boards and components.

Several types of mating connectors are used for these interconnecting pins. If the mating connector is mounted on a plug-on circuit board, special sockets are soldered into the board. If the mating connector is on the end of a lead, an end-lead pin connector is used. This connector mates with the interconnecting pin. The following information provides the removal and replacement procedure for the various interconnecting methods.

Square Pin Assemblies

See Fig. 5-1. These pins are of various lengths. They are attached to each other with a plastic strip. To remove them simply unsolder from the circuit board.

Multipin Connectors

The pin connectors used to connect the wires to the interconnecting pins are clamped to the ends of the wires. To replace damaged multipin connectors, remove the old pin connector from the holder. Do this by inserting a scribe between the connector and the holder and prying the connector from the holder. Clamp the replacement connector to the wire. Reinstall the connector in the holder.

If the individual end lead pin connectors are removed from the plastic holder, note the order of the individual wires for correct replacement in the holder. For proper replacement see Fig. 5-2.

Semiconductors

To remove the in-line integrated circuits installed in sockets, use an extracting tool. This tool is available from Tektronix, Inc.; order Tektronix Part Number 003-0619-00. If an extracting tool is not available, use care to avoid damaging the pins. Pull slowly and evenly on both ends of the integrated

circuit. Try to avoid disengaging one end before the other. IC's that are soldered in should be carefully unsoldered, using commercially available de-soldering tools, and gently removed. Care should be taken not to lift runs or pads from the etched circuit board. If de-soldering tools are not available, the pins of the IC may be clipped with diagonal cutters, and the pins then individually removed from the board.

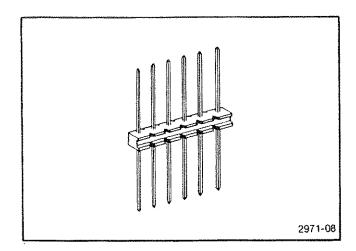


Fig. 5-1. Typical square pin assembly.

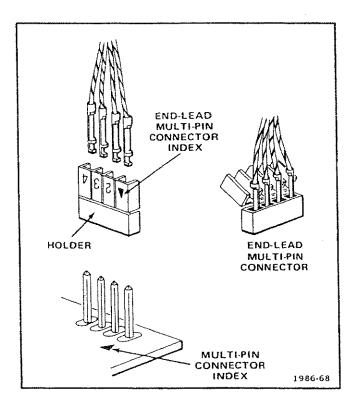


Fig. 5-2. Orientation and disassembly of multipin connectors.

Release Latch Removal

All plastic parts of the latch assembly and the return spring are individually replaceable. However, should the latch tension spring become damaged, the entire bottom frame rail assembly must be replaced.

- 1. Pull the latch pull bar out approximately 1/8 inch and hold the latch out.
- 2. Push the pull bar inward and downward until the retaining pins clear the slot in the latch.
- Release the latch and remove the pull bar.
- 4. Remove the screw securing the lower edge of the main circuit board to the bottom frame rail.
- 5. Remove the two screws from the bottom of the front frame assembly and the two guide pins at the lower edge of the rear frame.
- 6. The bottom frame rail can now be removed and the latch disassembled.
- 7. Re-assemble in the reverse order.
- 8. Push the pull bar through the front panel as far as it will go and hold it. Push the latch forward until the pull bar retaining pins engage the slot in the latch.

Main Circuit Board (A12) Removal

- Remove the side covers. A tab on the front frame assembly and a quarter-turn fastener at the rear secure the covers.
- 2. Remove the TIME/AVGS and FUNCTION switch knobs.
- 3. Disconnect the input cable at J4012.
- Remove the screw securing U2014 (heat sink) to the rear frame.
- Remove the two screws and two guide pins that secure the rear frame to the top and bottom frame rails and remove the rear frame.

- 6. Remove the three screws that secure the circuit board to the top (2) and bottom (1) frame rails.
- Pull the circuit board straight toward the rear of the instrument to disengage the connection to the display circuit board.
- Re-assemble in the reverse order. Take care that the pins on the display board are properly aligned with the mating connector on the main board.

Display Circuit Board (A10) Removal

- 1. Remove the side covers. A tab on the front frame assembly and a quarter-turn fastener at the rear secure the covers.
- 2. Remove the release latch pull bar as previously outlined under Release Latch Removal.
- 3. Remove the TIME/AVGS and FUNCTION switch and TRIGGER LEVEL knobs.
- 4. Remove the nut from the INPUT connector. A special wrench to remove this nut is available from Tektronix, Inc.; order Tektronix Part Number 003-0306-00. If this tool is not available, exercise care to prevent damage to the front panel.
- 5. Disconnect the input cable from the display circuit board at J4012.
- 6. Remove four screws that secure the top (2) and bottom (2) frame rails to the front frame assembly.
- 7. Pull the front frame assembly carefully straight out to avoid damaging the interconnecting pins to the main circuit board.
- 8. Remove the two screws on the back of the circuit board and separate the assembly.
- 9. Re-assemble in the reverse order taking care that interconnecting pins, LEDs, etc. are properly aligned.

NOTE

Display and indicator LED lead length is critical. If the leads of the replacement part are cut shorter than the original, that digit or indicator may not be clearly visible when viewed from an angle.

Internal Jumpers

Refer to the Adjustments and Test Points illustrations in the pull out pages for the locations of the following internal jumpers.

PLL DISABLE (P1040) located on the main board (A12)—disables the Phase Lock Loop circuitry.

INT/EXT CLOCK (P2042) located on the main board (A12)—selects the internal (10 MHz) time base, or permits application of an external time base via the rear interface.

INT/EXT INPUT (P4014) located on the display board (A10)—permits signal measurements via the front panel INPUT connector (EXT) or the rear interface (INT), P4012 at the rear edge of the Main board (A12) must also be moved to pins 1 and 2 of J4012 for INT.

Test Fixture Connectors

The two connectors identified on the schematic diagrams as J1032 and J2032 are test points used during the manufacturing process.

REAR INTERFACE CONNECTOR

Refer to Fig. 5-3 for the following.

A slot between pins 21 and 22 on the rear connector identifies this instrument as a member of the TM 500 counter family. Insert a barrier in the corresponding position of the power module jack to prevent noncompatible plug-ins being used in that compartment. Consult the power module manual for further information.

Functions Available

Pin 14A External Clock Input—This connection allows an external 10 MHz frequency standard to be used in

place of the internal time base. The input is one LSTTL load.

Pin 15A External Clock Ground—This is the common connection for the clock input and output signals.

Pin 16A Input—This is the signal input when the INT/EXT jumper is in the INT position. This connection is terminated into 50 Ω with a maximum input of 4 volts peak.

Pin 17A Input Ground—This is the common connection for the rear interface signal input.

| INPUT OR OUTPUT | PIN B | *************************************** | PIN A | INPUT OR OUTPUT |
|---------------------------|----------|---|----------|-------------------------|
| | 28 | FAMILY | 28 | |
| | | BARRIER | | |
| | 22 | SLOT | 22 | |
| | 21 | | 21 | , , |
| | | - | | |
| | | | | |
| | | | | |
| | | | 17 | INPUT CNO |
| | | | 16 | INPUT |
| | | , | 15 | EXT CLOCK GND |
| | | | 14 | EXT CLOCK IN |
| | | | | |
| * +26 Vdc | 12 | | 12 | * +26 Vdc |
| | | | | |
| CROUND | 9 | TH500 | 9 | GROUND |
| * -26 Vdc | 8 | BARRIER | 8 | * -26 Vdc |
| NPN SERIES PASS COLLECTOR | 7 | SLOT | 7 | NPN SERIES PASS EMITTER |
| | 6 | | 6 | NPN SERIES PASS BASE |
| | | | | |
| | | | | |
| | | | | |
| CROUND | 4 | | 4 | CROUND |
| CROUND | 3 | REAR VIEV | 3 | GROUND |
| * +8 Vdc | 2 | OF . | 2 | * +8 Vdc |
| | 1 | PLUC-IN | 1 | |
| | 1 | | | |

* Nominal Voltage - May be higher depending on power module type.

4291-09

Fig. 5-3. Rear interface connector assignments.

OPTIONS

There are no options for the DC 504A.

| | | grande statement came |
|--|--|-----------------------|
| | | - |
| | | |
| | | |

REPLACEABLE ELECTRICAL PARTS

PARTS ORDERING INFORMATION

Replacement parts are available from or through your local Tektronix, Inc. Field Office or representative

Changes to Tektronix instruments are sometimes made to accommodate improved components as they become available, and to give you the benefit of the latest circuit improvements developed in our engineering department. It is therefore important, when ordering parts, to include the following information in your order: Part number, instrument type or number, serial number, and modification number if applicable.

If a part you have ordered has been replaced with a new or improved part, your local Tektronix, Inc. Field Office or representative will contact you concerning any change in part number.

Change information, if any, is located at the rear of this manual.

LIST OF ASSEMBLIES

A list of assemblies can be found at the beginning of the Electrical Parts List. The assemblies are listed in numerical order. When the complete component number of a part is known, this list will identify the assembly in which the part is located.

CROSS INDEX-MFR. CODE NUMBER TO MANUFACTURER

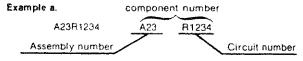
The Mfr. Code Number to Manufacturer index for the Electrical Parts List is located immediately after this page. The Cross Index provides codes, names and addresses of manufacturers of components listed in the Electrical Parts List.

ABBREVIATIONS

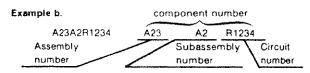
Abbreviations conform to American National Standard Y1.1.

COMPONENT NUMBER (column one of the Electrical Parts List)

A numbering method has been used to identify assemblies, subassemblies and parts. Examples of this numbering method and typical expansions are illustrated by the following:



Read: Resistor 1234 of Assembly 23



Read: Resistor 1234 of Subassembly 2 of Assembly 23

Only the circuit number will appear on the diagrams and circuit board illustrations. Each diagram and circuit board illustration is clearly marked with the assembly number. Assembly numbers are also marked on the mechanical exploded views located in the Mechanical Parts List. The component number is obtained by adding the assembly number prefix to the circuit number.

The Electrical Parts List is divided and arranged by assemblies in numerical sequence (e.g., assembly A1 with its subassemblies and parts, precedes assembly A2 with its subassemblies and parts).

Chassis-mounted parts have no assembly number prefix and are located at the end of the Electrical Parts List.

TEKTRONIX PART NO. (column two of the Electrical Parts List)

Indicates part number to be used when ordering replacement part from Tektronix.

SERIAL/MODEL NO. (columns three and four of the Electrical Parts List)

Column three (3) indicates the serial number at which the part was first used. Column four (4) indicates the serial number at which the part was removed. No serial number entered indicates part is good for all serial numbers.

NAME & DESCRIPTION (column five of the Electrical Parts List)

In the Parts List, an Item Name is separated from the description by a colon (:). Because of space limitations, an Item Name may sometimes appear as incomplete. For further Item Name identification, the U.S. Federal Cataloging Handbook H6-1 can be utilized where possible.

MFR. CODE (column six of the Electrical Parts List)

Indicates the code number of the actual manufacturer of the part. (Code to name and address cross reference can be found immediately after this page.)

MFR. PART NUMBER (column seven of the Electrical Parts List)

Indicates actual manufacturers part number

CROSS INDEX - MFR. CODE NUMBER TO MANUFACTURER

| lfr. Jode | Manufacturer | Address | City, State, Zip Code |
|----------------|---|--|---|
| 00136 | MCCOY ELECTRONICS CO | 100 WATTS ST | MT HOLLY SPRINGS PA 17065-1821 |
| 00213 | NYTRONICS COMPONENTS GROUP INC SUBSIDIARY OF NYTRONICS INC | PO BOX B ORANGE ST | DARLINGTON SC 29532 |
| 00853 | SANGAMO WESTON INC COMPONENTS DIV | SANGAMO RD PO BOX 128 | PICKENS SC 29671-9716 |
| 01121 01295 | ALLEN-BRADLEY CO TEXAS INSTRUMENTS INC | 1201 SOUTH 2ND ST 13500 N CENTRAL EXP | MILWAUKEE WI 53204-2410 DALLAS TX 75265 |
| 02735 | SEMICONDUCTOR GROUP RCA CORP | PO BOX 655012 ROUTE 202 | SOMERVILLE NJ 08876 |
| 03508 | SOLID STATE DIVISION GENERAL ELECTRIC CO | W GENESEE ST | AUBURN NY 13021 |
| 04222 | SEMI-CONDUCTOR PRODUCTS DEPT AVX CERAMICS DIV OF AVX CORP | 19TH AVE SOUTH P O BOX 867 | MYRTLE BEACH SC 29577 |
| 04713 | MOTOROLA INC SEMICONDUCTOR PRODUCTS SECTOR | 5005 E MCDOWELL RD | PHOENIX AZ 85008-4229 |
| 05828 | GENERAL INSTRUMENT CORP GOVERNMENT SYSTEMS DIV | 600 W JOHN ST | HICKSVILLE NY 11802 |
| 07263 | FAIRCHILD SEMICONDUCTOR CORP NORTH AMERICAN SALES | 10400 RIDGEVIEW CT | CUPERTINO CAW CA 95014 |
| 07716 | SUB OF SCHLUMBERGER LTD MS 118 TRW INC TRW IRC FIXED RESISTORS/BURLINGTON | 2850 MT PLEASANT AVE | BURLINGTON [A 5260] |
| 11236 | CTS CORP BERNE DIV | 406 PARR ROAD | BERNE IN 46711-9506 |
| 8324 | THICK FILM PRODUCTS GROUP SIGNETICS CORP | 4130 S MARKET COURT | SACRAMENTO CA 95834-1222 |
| 9701 | MILITARY PRODUCTS DIV MEPCO/CENTRALAB A NORTH AMERICAN PHILIPS CO | P O BOX 760 | MINERAL WELLS TX 76067-0760 |
| 2526 | DU PONT E I DE NEMOURS AND CO INC DU PONT CONNECTOR SYSTEMS DIV MILITARY PRODUCTS GROUP | 515 FISHING CREEK RD | NEW CUMBERLAND PA 17070-3007 |
| 4931 | SPECIALTY CONNECTOR CO INC | 2100 EARLYWOOD DR PO BOX 547 | FRANKLIN IN 46131 |
| 7014 9604 | NATIONAL SEMICONDUCTOR CORP STACKPOLE COMPONENTS CO SUB OF THE STACKPOLE CORP | 2900 SEMICONDUCTOR DR PO BOX 14466 | SANTA CLARA CA 95051-0606 RALEIGH NC 27610 |
| 2293 | INTERSIL INC SUB OF GENERAL ELECTRIC CO | 10600 RIDGEVIEW COURT | CUPERTINO CA 95014-0704 |
| 2997 | BOURNS INC TRIMPOT DIV | 1200 COLUMBIA AVE | RIVERSIDE CA 92507-2114 |
| 4473 | MATSUSHITA ELECTRIC CORP OF AMERICA | ONE PANASONIC WAY PO BOX 1501 | SECAUCUS NJ 07094-2917 |
| 5680 6289 | NICHICON /AMERICA/ CORP SPRAGUE ELECTRIC CO WORLD HEADOUARTERS | 927 E STATE PKY 92 HAYDEN AVE | SCHAUMBURG IL 60195-4526 LEXINGTON MA 02173-7929 |
| 7668 8361 | R-OHM CORP GENERAL INSTRUMENT CORP OPTOELECTRONICS DIV | 16931 MILLIKEN AVE 3400 HILLVIEW AVE | IRVINE CA 92713 PALO ALTO CA 94304-1319 |
| 9660 | TUSONIX INC | 7741 N BUSINESS PARK DR PO BOX 37144 | TUCSON AZ 85740-7144 |
| 1400 | BUSSMANN DIV OF COOPER INDUSTRIES INC | 114 OLD STATE RD PO BOX 14460 | ST LOUIS MO 63178 |
| 1590 | MEPCO/CENTRALAB INC A NORTH AMERICAN PHILIPS CO | HWY 20 W P O BOX 858 | FORT DODGE IA 50501 |
| 6493 | BELL INDUSTRIES INC JW MILLER DIV | 19070 REYES AVE PO BOX 5825 | COMPTON CA 90224-5825 |
| 000 9 | TEKTRONIX INC | 14150 SW KARL BRAUM DR PO BOX 500 MS 53-111 | BEAVERTON OR 97077 |
| 0031 6733 | MEPCO/ELECTRA INC SFE TECHNOLOGIES | 22 COLUMBIA RD 1501 FIRST ST | MORRISTOWN NJ 07960 SAN FERNANDO CA 91340-2707 |

| Component No. | Tektronix Part No. | Serial/Ass Effective | • | Name & Description | Mfr. Code | Mfr. Part No. |
|--|--|--|--|--|--|---|
| A10 A10 A12 A12 A12 A12 | 670-7597-00 670-7597-01 670-7598-00 670-7598-01 670-7598-02 670-7598-03 | B011130 B010100 B011130 B011470 | B011129 B011129 B011469 B012375 | CIRCUIT BD ASSY:DISPLAY CIRCUIT BD ASSY:DISPLAY CIRCUIT BD ASSY:MAIN CIRCUIT BD ASSY:MAIN CIRCUIT BD ASSY:MAIN CIRCUIT BD ASSY:MAIN | 80009 80009 80009 80009 80009 80009 | 670-7597-00 670-7597-01 670-7598-00 670-7598-01 670-7598-02 670-7598-03 |
| A10 A10 A10C2011 A10C2012 A10C2014 A10C2031 | 670-7597-00 670-7597-01 281-0775-00 290-0920-00 281-0775-00 283-0487-00 | | 8011129 | CIRCUIT BD ASSY:DISPLAY CIRCUIT BD ASSY:DISPLAY CAP,FXD,CER DI:0.1UF,20%,50V CAP,FXD,ELCTLT:33UF,+50-20%,35WVDC CAP,FXD,CER DI:0.1UF,20%,50V CAP NTWK,CER,DI:(7)330PF,20%,50V | 80009 80009 04222 55680 04222 56289 | 670-7597-00 670-7597-01 MA205E104MAA UVX1H330MPA MA205E104MAA 470C7C0G331M5DG |
| A10C2033 A10C3021 A10C3034 A10C4013 A10C4014 A10C4014 | 290-0920-00 281-0785-00 281-0775-00 281-0775-00 283-0057-00 281-0907-00 | B010100 B011130 | 8011129 | CAP, FXD, ELCTLT: 33UF, +50-20%, 35WVDC CAP, FXD, CER DI: 68PF, 10%, 100V CAP, FXD, CER DI: 0.1UF, 20%, 50V CAP, FXD, CER DI: 0.1UF, 20%, 50V CAP, FXD, CER DI: 0.1UF, +80-20%, 200V CAP, FXD, CER DI: 0.068UF, 10%, 200V | 55680 04222 04222 04222 04222 96733 | UVX1H330MPA MA101A680KAA MA205E104MAA MA205E104MAA SR306E104ZAA RH06BX683K |
| A10C4021 A10C4025 A10C4035 A10C4036 A10C4038 A10CR2012 | 281-0797-00 281-0798-00 281-0775-00 283-0067-00 281-0775-00 152-0141-02 | | | CAP, FXD, CER DI:15PF, 10%, 100V CAP, FXD, CER DI:51PF, 1%, 100V CAP, FXD, CER DI:0.1UF, 20%, 50V CAP, FXD, CER DI:0.001UF, 10%, 200V CAP, FXD, CER DI:0.1UF, 20%, 50V SEMICOND DVC, DI:SW, SI, 30V, 150MA, 30V, D0-35 | 04222 04222 04222 59660 04222 03508 | MA106A150KAA MA101A510GAA MA205E104MAA 835-515-YSE0102K MA205E104MAA DA2527 (1N4152) |
| A10CR2013 A10CR2023 A10CR3034 A10CR4032 A10CR4037 A10DS1011 | 152-0141-02 152-0141-02 152-0141-02 152-0141-02 152-0141-02 150-1048-00 | | | SEMICOND DVC,DI:SW,SI,30V,150MA,30V,DO-35 SEMICOND DVC,DI:SW,SI,30V,150MA,30V,DO-35 SEMICOND DVC,DI:SW,SI,30V,150MA,30V,DO-35 SEMICOND DVC,DI:SW,SI,30V,150MA,30V,DO-35 SEMICOND DVC,DI:SW,SI,30V,150MA,30V,DO-35 LAMP,LED RDOUT:ORANGE,7 SEG,1 DIGIT | 03508 03508 03508 03508 03508 58361 | DA2527 (1N4152) DA2527 (1N4152) DA2527 (1N4152) DA2527 (1N4152) DA2527 (1N4152) Q3383/MAN4640A |
| A10DS1012 A10DS1023 A10DS1024 A10DS1035 A10DS1036 A10DS2011 | 150-1048-00 150-1048-00 150-1048-00 150-1048-00 150-1048-00 150-1036-00 | | | LAMP, LED RDOUT: ORANGE, 7 SEG, 1 DIGIT LAMP, LED RDOUT: ORANGE, 7 SEG, 1 DIGIT LT EMITTING DIO: RED, 650NM, 40MA MAX | 58361 58361 58361 58361 58361 58361 | Q3383/MAN4640A Q3383/MAN4640A Q3383/MAN4640A Q3383/MAN4640A Q6878/MV5074C |
| A10DS2022 A10DS2034 A10J2062 | 150-1036-00 150-1036-00 131-2651-01 | | | LT EMITTING DIO:RED,650NM,40MA MAX LT EMITTING DIO:RED,650NM,40MA MAX CONN,RCPT,ELEC:HEADER,1 X 36,0.1 CTR,0.025 PIN | 58361 58361 TK1483 | Q6878/MV5074C Q6878/MV5074C 082~3643~SS06 |
| A10J4012 A10J4014 | 131-1857-00 131-1857-00 | | | TERM SET, PIN:36/0.025 SQ PIN, ON 0.1 CTRS TERM SET, PIN:36/0.025 SQ PIN, ON 0.1 CTRS | TK1483 TK1483 | 082-3643-SS10 082-3643-SS10 |
| A10J4015 A10L2013 A10Q2023 A10Q2027 A10Q3011 A10Q3031 | 131-2833-00 108-0245-00 151-0341-00 151-0342-00 151-0190-00 151-0190-00 | | | CONN, RCPT, ELEC: BNC, FEMALE CHOKE, RF: FIXED, 3.9UH TRANSISTOR: NPN, SI, TO-106 TRANSISTOR: PNP, SI, TO-92 TRANSISTOR: NPN, SI, TO-92 TRANSISTOR: NPN, SI, TO-92 | 24931 76493 04713 07263 80009 80009 | 28JR175-4 B6310-1 SP56919 S035928 151-0190-00 151-0190-00 |
| A1004021 A1004022 A1004023 A10R2011 A10R2012 A10R2022 | 151-0427-00 151-1042-00 151-1042-00 315-0103-00 315-0512-00 315-0561-00 | | | TRANSISTOR:NPN,SI,TO-92 SEMICOND DVC SE:FET,SI,TO-92 SEMICOND DVC SE:FET,SI,TO-92 RES,FXD,FILM:10K OHM,5%,0.25W RES,FXD,FILM:5.1K OHM,5%,0.25W RES,FXD,FILM:560 OHM,5%,0.25W | 07263 04713 04713 19701 57668 19701 | \$39287 \$PF627M2 \$PF627M2 5043CX10K00J NTR25J-E05K1 5043CX560R0J |
| A10R2023 A10R2025 A10R2026 | 315-0103-00 315-0472-00 315-0472-00 | | | RES.FXD.FILM:10K OHM.5%.0.25W RES.FXD.FILM:4.7K OHM.5%.0.25W RES.FXD.FILM:4.7K OHM.5%.0.25W | 19701 57668 57668 | 5043CX10K00J NTR25J-E04K7 NTR25J-E04K7 |

| Component No. | Tektronix Part No. | Serial/Asse Effective | | Name & Description | Mfr. Code | Mfr. Part No. | (|
|---|--|--------------------------|--------------------|---|--|---|---|
| A12R1052 A12R1053 A12R1054 A12R1055 A12R1056 A12R1057 | 315-0331-00 315-0162-00 315-0561-00 315-0102-00 315-0201-00 315-0270-00 | | | RES, FXD, FILM: 330 OHM, 5%, 0.25W RES, FXD, FILM: 1.6K OHM, 5%, 0.25W RES, FXD, FILM: 560 OHM, 5%, 0.25W RES, FXD, FILM: 1K OHM, 5%, 0.25W RES, FXD, FILM: 200 OHM, 5%, 0.25W RES, FXD, FILM: 27 OHM, 5%, 0.25W | 57668 19701 19701 57668 57668 19701 | NTR25J-E330E 5043CX1K600J 5043CX560R0J NTR25JE01K0 NTR25J-E200E 5043CX27R00J | |
| A12R1058 A12R1059 A12R1060 A12R1062 A12R1063 A12R1064 | 315-0473-00 315-0103-00 315-0103-00 315-0511-00 315-0270-00 315-0101-00 | | | RES,FXD,FILM:47K OHM,5%,0.25W RES,FXD,FILM:10K OHM,5%,0.25W RES,FXD,FILM:10K OHM,5%,0.25W RES,FXD,FILM:510 OHM,5%,0.25W RES,FXD,FILM:27 OHM,5%,0.25W RES,FXD,FILM:100 OHM,5%,0.25W | 57668 19701 19701 19701 19701 57668 | NTR25J-E47K0 5043CX10K00J 5043CX10K00J 5043CX510R0J 5043CX27R00J NTR25J-E 100E | |
| A12R1065 A12R1066 A12R1067 A12R1068 A12R1069 A12R2014 | 315-0101-00 315-0182-00 315-0182-00 315-0181-00 315-0751-00 315-0104-00 | B011470 | | RES,FXD,FILM:100 OHM,5%,0.25W RES,FXD,FILM:1.8K OHM,5%,0.25W RES,FXD,FILM:1.8K OHM,5%,0.25W RES,FXD,FILM:180 OHM,5%,0.25W RES,FXD,FILM:750 OHM,5%,0.25W RES,FXD,FILM:100K OHM,5%,0.25W | 57668 57668 57668 57668 57668 57668 | NTR25J-E 100E NTR25J-E1K8 NTR25J-E1K8 NTR25J-E180E NTR25J-E750E NTR25J-E100K | |
| A12R2015 A12R2016 A12R2031 A12R2032 A12R2034 A12R2035 | 315-0102-00 308-0244-00 307-0445-00 307-0445-00 315-0472-00 315-0472-00 | | | RES,FXD,FILM:1K OHM,5%,0.25W RES,FXD,WW:0.3 OHM,10%,2W RES NTWK,FXD,FI:4.7K OHM,20%,(9)RES RES NTWK,FXD,FI:4.7K OHM,20%,(9)RES RES,FXD,FILM:4.7K OHM,5%,0.25W RES,FXD,FILM:4.7K OHM,5%,0.25W | 57668 00213 32997 32997 57668 57668 | NTR25JE01K0 310S 0.3-10 4310R-101-472 4310R-101-472 NTR25J-E04K7 NTR25J-E04K7 | |
| A12R2038 A12R2039 A12R2046 A12R2047 A12R2048 A12R2051 | 315-0103-00 315-0103-00 315-0472-00 315-0561-00 315-0561-00 315-0106-00 | B010100 B010100 | B011129 B011129 | RES,FXD,FILM:10K 0HM,5%,0.25W RES,FXD,FILM:10K 0HM,5%,0.25W RES,FXD,FILM:4.7K 0HM,5%,0.25W RES,FXD,FILM:560 0HM,5%,0.25W RES,FXD,FILM:560 0HM,5%,0.25W RES,FXD,FILM:10M 0HM,5%,0.25W | 19701 19701 57668 19701 19701 01121 | 5043CX10K00J 5043CX10K00J NTR25J-E04K7 5043CX560R0J 5043CX560R0J CB1065 | (|
| A12R2052 A12R2053 A12R2063 A12R3012 A12R3014 A12R3015 | 315-0682-00 315-0154-00 307-0598-00 321-0260-00 315-0162-00 321-0225-00 | | | RES,FXD,FILM:6.8K OHM,5%,0.25W RES,FXD,FILM:150K OHM,5%,0.25W RES NTWK,FXD,F1:7,330 OHM,2%,1.0W RES,FXD,FILM:4.99K OHM,1%,0.125W,TC=T0 RES,FXD,FILM:1.6K OHM,5%,0.25W RES,FXD,FILM:2.15K OHM,1%,0.125W,TC=T0 | 57668 57668 11236 19701 19701 | NTR25J-E06K8 NTR25J-E150K 750-81-R330 5033ED4K990F 5043CX1K600J 5033ED2K15F | |
| A12R3016 A12R3017 A12S2061 A12TP1063 A12TP2012 A12TP2014 | 321-0105-00 321-0151-00 260-2123-00 214-0579-00 214-0579-00 214-0579-00 | | | RES.FXD.FILM:121 OHM 1%.0.125W.TC=\0 RES.FXD.FILM:365 OHM.1%.0.125W.TC=TO SWITCH.ROTARY:DUAL CONCENTRIC TERM.TEST POINT:BRS CD PL TERM.TEST POINT:BRS CD PL TERM.TEST POINT:BRS CD PL TERM.TEST POINT:BRS CD PL | 07716 07716 29604 80009 80009 | CEAD121R0F CEAD365R0F 73-8501 214-0579-00 214-0579-00 214-0579-00 | |
| A12TP3012 A12U1011 A12U1012 A12U1023 A12U1024 A12U1025 | 214-0579-00 156-0525-03 156-0514-01 156-1152-01 156-0366-02 156-0349-06 | | | TERM,TEST POINT:BRS CD PL MICROCKT.DGTL:DUAL J-K MASTER SLAVE FF,SEL MICROCKT.DGTL:DIFF 4-CHANNEL MUX,SEL MICROCKT.DGTL:PRCN RETRIGGERABLE,SCRN MICROCKT.DGTL:DUAL D FLIP-FLOP,SCREENED MICROCKT.DGTL:QUAD 2 INP NOR GATE | 80009 04713 80009 04713 02735 02735 | 214-0579-00 MC14027BCLD 156-0514-01 MC14538BCLDS CD4013BFX CD4001BFX | |
| A12U1031 A12U1032 A12U1034 A12U1036 A12U1037 A12U1044 | 156-0383-02 156-0910-02 156-0350-05 156-0349-06 156-0754-02 156-0352-06 | 5 | | MICROCKT,DGTL:QUAD 2-INP NOR GATE,SCRN, MICROCKT,DGTL:DUAL DECADE COUNTER,SCRN MICROCKT,DGTL:QUAD 2 INPUT NAND GATE MICROCKT,DGTL:QUAD 2 INP NOR GATE MICROCKT,DGTL:DUAL 4-INPUT NOR GATE,SCRN MICROCKT,DGTL:CMOS,DUAL CMPLM PAIR + INVT | 18324 01295 02735 02735 02735 02735 | N74LS02NB SN74LS390N3 CD4011BFX CD4001BFX CD4002BFX-98 CD4007A(E OR F) | |
| A12U1048 A12U1048 A12U1052 A12U1063 | 156-0385-02 156-2027-00 156-0970-00 156-0182-00 | 0 B011130 3 | B011129 | MICROCKT,DGTL:HEX INVERTER,SCRN MICROCKT,DGTL:CMOS,HEX INVERTER MICROCKT,DGTL:QUAD HV NAND GATE W/OC OUT MICROCKT,DGTL:TRIPLE 2-3-2 INP GATE,SCRN | 07263 27014 01295 04713 | | |

| Campanent No. | Tektronix Part No. | Serial/Asse Effective | | Name & Description | Mfr. Code | Mfr. Part No. | |
|--|--|--------------------------|---------|---|--|---|--|
| A12U2013 A12U2014 A12U2026 A12U2027 A12U2027 A12U2043 | 156-0071-02 156-1451-00 156-0384-02 156-0383-02 156-2026-00 156-0411-02 | B010100 B011130 | B011129 | MICROCKT, LINEAR: VOLTAGE REGULATOR, CHECKED MICROCKT, LINEAR: 3-TERM NEG VOLTAGE RGLTR MICROCKT, DGTL: QUAD 2-INP NAND GATE, SCRN MICROCKT, DGTL: QUAD 2-INP NOR GATE, SCRN, MICROCKT, DGTL: CMOS, QUAD 2 INPUT NOR GATE MICROCKT, LINEAR: QUAD COMPARATOR, SCREENED | 04713 27014 07263 18324 04713 04713 | MC1723CLDS LM337T 74LS03PCQR N74LS02NB MC74HC02(N OR J) LM339JDS | |
| A12U2O45 A12U2O47 A12U2O54 A12U2O67 A12Y2O54 | 156-0411-02 156-1655-00 156-0704-00 156-0642-01 158-0129-00 | | | MICROCKT, LINEAR: QUAD COMPARATOR, SCREENED MICROCKT, DGTL: IDL, 10MHZ UNIVERSAL COUNTER MICROCKT, LINEAR: CMOS, PHASE LOCK LOOP MICROCKT, DGTL: BI QUINARY CNTR, SCREENED XTAL UNIT, QTZ: 10MHZ 0.001%, PARALLEL | 04713 32293 04713 04713 00136 | LM339JDS ICM7226BIPL MC14046CP MC10138PD/LD 20-9~1 | |



DIAGRAMS AND CIRCUIT BOARD ILLUSTRATIONS

Symbols

Graphic symbols and class designation letters are based on ANSI Standard Y32.2-1975.

Logic symbology is based on ANSI Y32.14-1973 in terms of positive logic. Logic symbols depict the logic function performed and may differ from the manufacturer's data.

The overline on a signal name indicates that the signal performs its intended function when it is in the low state.

Abbreviations are based on ANSI Y1.1-1972.

Other ANSI standards that are used in the preparation of diagrams by Tektronix, Inc. are:

Y14.15, 1966 Drafting Practices.

Y14.2, 1973 Line Conventions and Lettering.

Y10.5, 1968 Letter Symbols for Quantities Used in Electrical Science and Electrical

Engineering.

American National Standard Institute 1430 Broadway New York, New York 10018

Component Values

Electrical components shown on the diagrams are in the following units unless noted otherwise:

Capacitors = Values one or greater are in picofarads (pF). Values less than one are in microfarads (μF) .

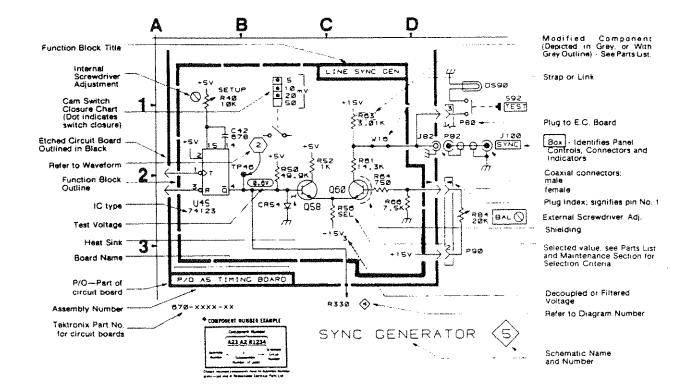
Resistors = Ohms (Ω) .

The information and special symbols below may appear in this manual.

Assembly Numbers and Grid Coordinates

Each assembly in the instrument is assigned an assembly number (e.g., A20). The assembly number appears on the circuit board outline on the diagram, in the title for the circuit board component location illustration, and in the lookup table for the schematic diagram and corresponding component locator illustration. The Replaceable Electrical Parts list is arranged by assemblies in numerical sequence; the components are listed by component number *(see following illustration for constructing a component number).

The schematic diagram and circuit board component location illustration have grids. A lookup table with the grid coordinates is provided for ease of locating the component. Only the components illustrated on the facing diagram are listed in the lookup table. When more than one schematic diagram is used to illustrate the circuitry on a circuit board, the circuit board illustration may only appear opposite the first diagram on which it was illustrated; the lookup table will list the diagram number of other diagrams that the circuitry of the circuit board appears on.



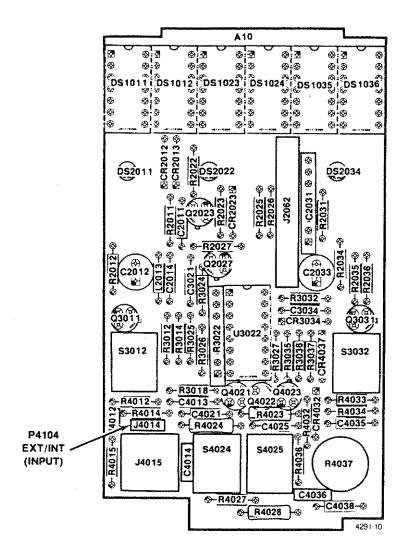
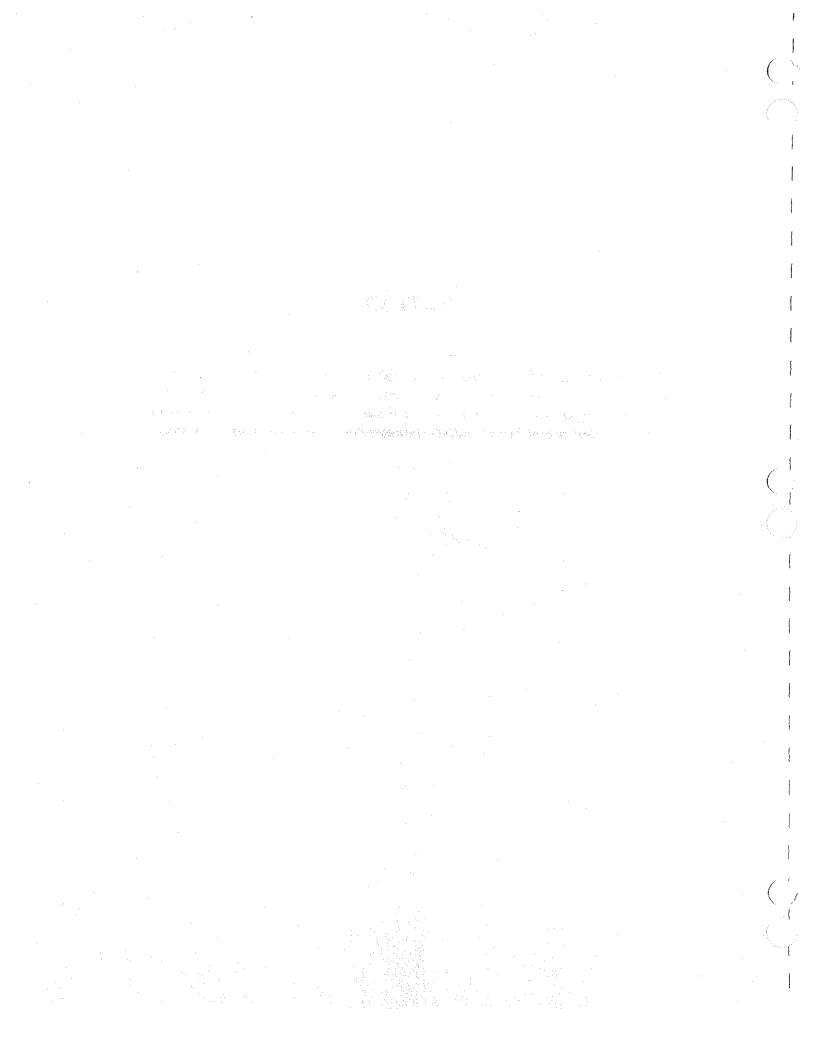


Fig. 8-1. Display Board.

Warning

The following servicing instructions are for use only by qualified personnel. To avoid personnel injury, do not perform any servicing other than that contained in the operating instructions unless you are qualified to do so. Refer to General Safety Summary and Service Safety Summary prior to performing any service.



REV MAY 1983

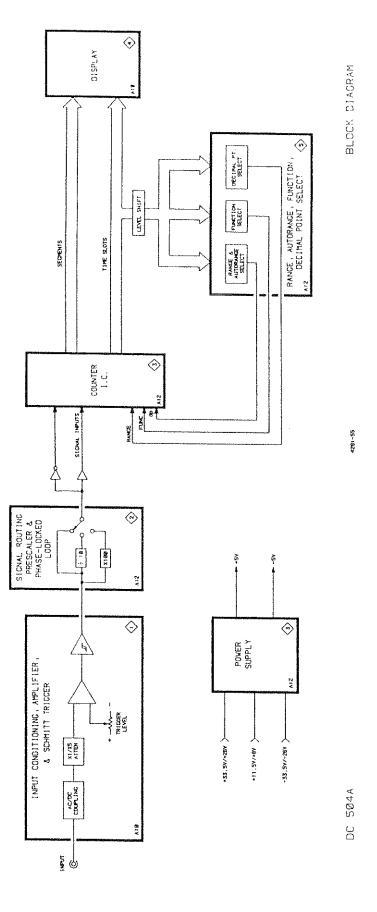
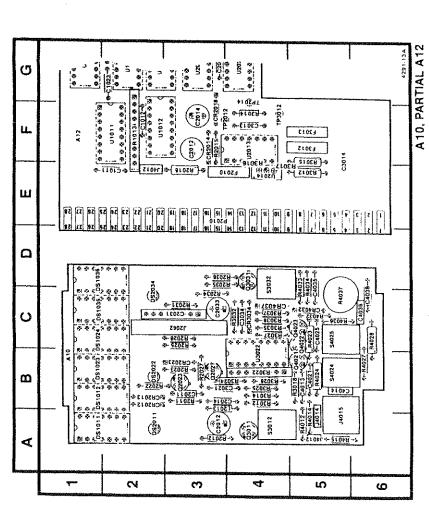


Fig. 8-3, Block Diagram.

PARTS LOCATION GRID

Table 8-1



COMPONENT NUMBER EXAMPLE A23 A2 71234

Static Sensitive Devices Section

Fig. B-4. Display Board (A10 Assy), and partial of Main Board (A12 Assy).

 \odot FRONT PANEL BOARD COMPONENT REFERENCE CHART SCHEMATIC ◈ \odot A10 ASSY aiso shown BOARD ENTONOUS SERVICES SER SCHEMATIC 0/4 2227755555676 545 655 2 82 654 CO012 C0003 CIRCUIT

MAIN BOARD

ឌដ

P2010 P4012 0

52

J4012

PIO A12 ASSY

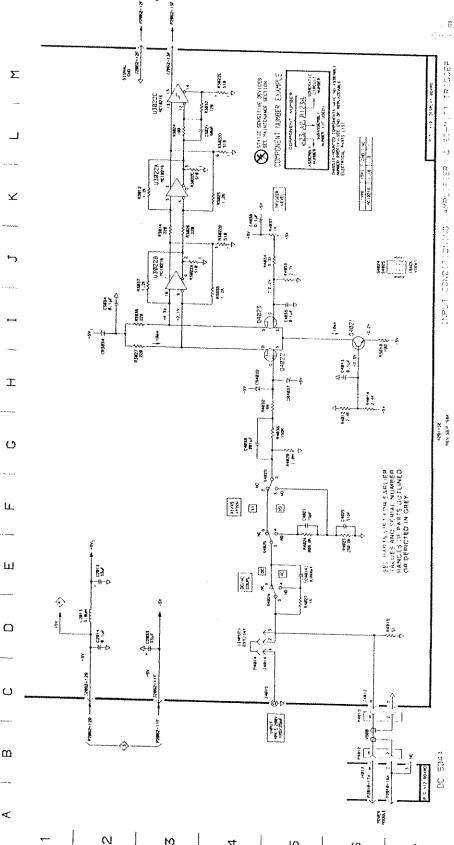
 \odot 86 86

 \odot

A12 ASSY also shown on

õ 8

REV MAY 1983



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ω

A12

Fig. 8-5. Main Board (A12 Assy).

| | | | , - |
|--|--|--|---------|
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| | | | |
| | | | e a a e |

Table 8-2 COMPONENT REFERENCE CHART

| P/O A12 AS | SSY | | | MAIN BO | DARD 2 |
|-------------------|-----------------------|-------------------|-------------------|-----------------------|-------------------|
| CIRCUIT NUMBER | SCHEMATIC LOCATION | BOARD LOCATION | CIRCUIT NUMBER | SCHEMATIC LOCATION | BOARD LOCATION |
| 04054 | | | | | |
| C1051 | L7 | J1 | R1046 | J5 | H1 |
| C1052 C1057 | G6 | J2 | R1047 | G <u>e</u> | H1 |
| | H5 | J2 | R1050 | C5 | K1 |
| C2055 | <u>G</u> 7 | J3 | R1052 | J4 | J2 |
| C2067 | E5 | К3 | R1053 | 16 | J2 |
| C2068 | C3 | L3 | R1054 | 16 | J2 |
| 00.555 | | | R1055 | C5 | K1 |
| CR1020 | Ļ5 | D1 | R1056 | l <u>6</u> | K1 |
| CR1021 | L5 | D1 | R1057 | G5 | K2 |
| CR1062 | Je | L1 | R1058 | G4 | K2 |
| CR1063 | C4 | L1 | R1059 | D5 | K2 |
| | | | R1060 | D5 | K2 |
| J1040 | 19 | H1 | R1062 | B4 | K2 |
| | | | R1063 | G2 | L1 |
| P1040 | 19 | H1 | R1064 | H4 | L1 |
| | | | R1065 | G4 | L2 |
| Q1042 | H7 | H1 | R1066 | D1 | M1 |
| Q1043 | F8 | H1 | R1067 | D2 | M1 |
| Q1052 | J4 | J1 | R1068 | L6 | M1 |
| Q1053 | G5 | J2 | R1069 | L6 | M1 |
| Q1054 | J6 | K2 | R2046 | F7 | H2 |
| Q1056 | C5 | K1 | R2047 * | 13 | H3 |
| Q1057 | J4 | K2 | R2048* | J3 | H3 |
| Q1062 | G2 | K1 | R2052 | F6 | J3 |
| Q1064 | H2 | L1 | R2053 | F6 | J3 |
| Q1066 | D2 | M2 | R2063 | Ē3 | L2 |
| Q1068 | D 1 | M2 | | | |
| | | | TP1063 | B2 | L2 |
| R1031 | K5 | F1 | | | ~ - |
| R1032 | L5 | Fi | U1032 | 18 | F1 |
| R1039 | H7 | G1 | U1044 | Ğ6 | H2 |
| R1040 | G7 | Ği | U1048 | H3 | H2 |
| R1041 | G8 | G1 | U1052 | J6 | J1 |
| R1042 | F8 | Ğ2 | U1063 | C1 | Ľ2 |
| R1044 | K6 | Hī | U2054 | F5 | K3 |
| R1045 | J5 | Hi | U2067 | D4 | L3 |
| | B/O 812 | ASSY also shown | | ^ | |

*See Parts List for serial number ranges.

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PARTS LOCATION GRIDS

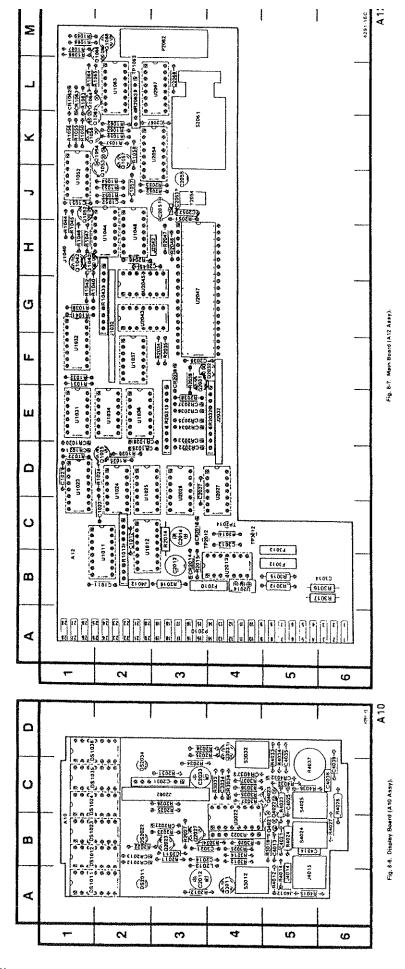
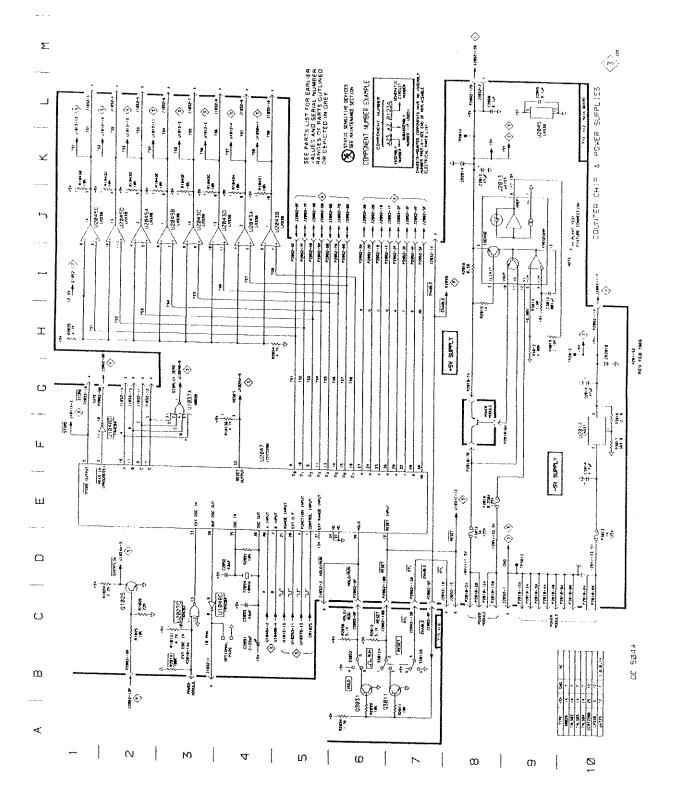


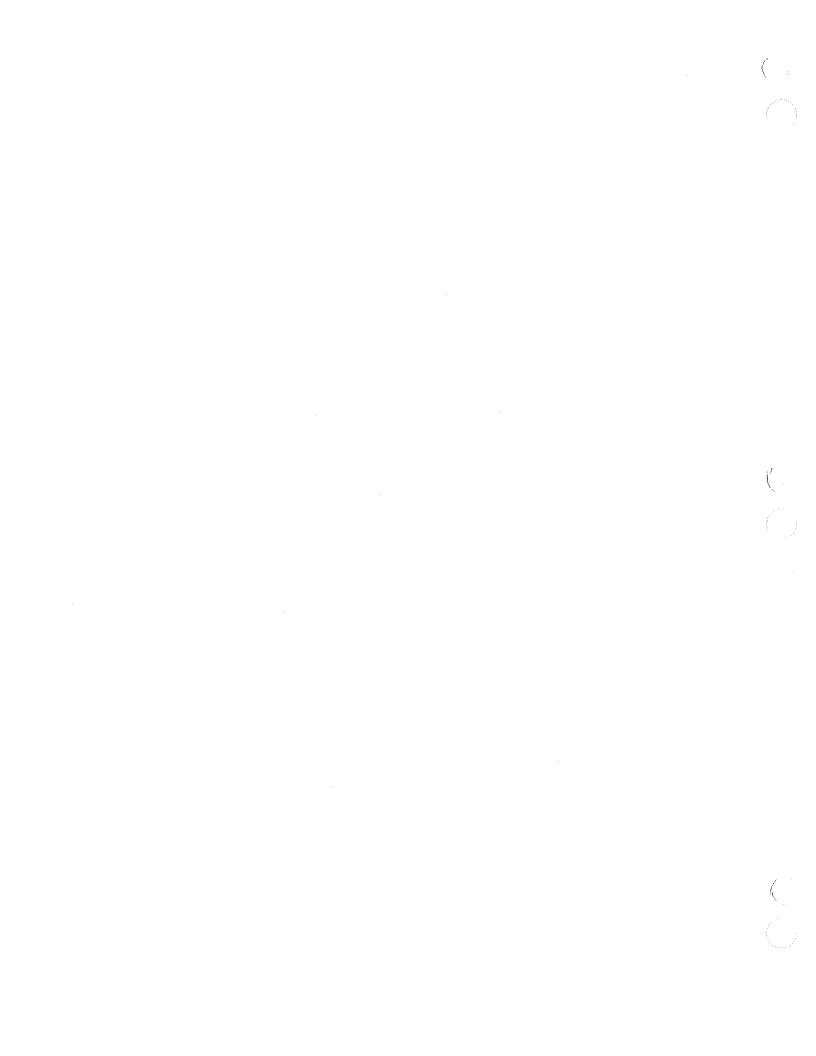
Table 8-3
COMPONENT REFERENCE CHART

| B3 C3 B4 B5 C5 G2 E4 | R1013 R1024 R1025 R1026 R1026 R1043 R2014* R2015 R2016 R2035 R2035 R2035 R2051 R3012 R3014 R3015 R3016 R3017† TP2012 TP2014 TP3012 U1037 | MAIN BO SCHEMATIC LOCATION F4 C2 C2 C2 K1 B3 I8 I8 A6 H1 D4 H9 I9 H9 G10 F10 H10 L8 D9 | BOARD LOCATION B2 D2 D2 D2 C3 B3 B3 B3 F3 F3 F3 F3 C4 B5 B6 B6 C3 C4 C4 C4 |
|--|---|--|--|
| B3 C3 F3 A2 J3 J3 J3 C4 B5 C3 B4 B5 C5 | R1013 R1025 R1025 R1026 R1043 R2014* R2015 R2016 R2034 R2035 R2051 R3012 R3014 R3015 R3016† R3017† TP2012 TP2014 | F4 C2 C2 C2 K1 B3 I8 I8 A6 H1 D4 H9 I9 H9 G10 F10 H10 L8 D9 | B2 D2 D2 D2 G2 C3 B3 B3 F3 F3 F3 F3 C4 B5 C4 |
| C3 F3 A2 J3 J3 J3 C4 B5 C3 B4 B5 C5 G2 E4 | R1024 R1025 R1025 R1026 R1043 R2014* R2015 R2016 R2035 R2035 R3012 R3012 R3017 R3017† TP2012 TP2014 TP3012 | C2 C2 C2 K1 B3 I8 I8 A6 H1 H9 H9 H9 H9 F10 H10 L8 D9 | D2 D2 D2 C3 B3 F3 F3 J3 B5 C4 B5 B6 C3 C4 |
| C3 F3 A2 J3 J3 J3 C4 B5 C3 B4 B5 C5 G2 E4 | R1025 R1026 R1026 R1043 R2014* R2015 R2016 R2034 R2035 R2051 R3012 R3014 R3015 R3016† R3017† TP2012 | C2 C2 K1 B3 I8 I8 A6 H1 D4 H9 I9 H9 G10 F10 H10 L8 | D2 D2 D2 C3 B3 F3 F3 J3 B5 C4 B5 B6 C3 C4 |
| F3 A2 J3 J3 J3 C4 B5 B3 C3 B4 B5 C5 G2 E4 | R1026 R1043 R2014* R2015 R2016 R2034 R2035 R2051 R3012 R3014 R3015 R3016† R3017† TP2012 TP2012 | C2 C2 K1 B3 I8 I8 A6 H1 D4 H9 I9 H9 G10 F10 H10 L8 | D2 D2 G2 C3 B3 F3 F3 J3 B5 C4 B5 B6 C3 C4 |
| A2 J3 J3 C4 B5 B3 C3 B4 B5 C5 | R1043 R2014* R2015 R2016 R2034 R2035 R2051 R3012 R3014 R3015 R3016† R3017† TP2012 TP2014 TP3012 | K1 B3 I8 A6 H1 D4 H9 I9 G10 F10 H10 L8 | D2 G2 C3 B3 F3 F3 J3 B5 C4 B5 B6 C3 C4 |
| J3 J3 J3 C4 B5 B3 C3 B4 B5 C5 | R2014* R2015 R2016 R2034 R2035 R2051 R3012 R3014 R3015 R3016† R3017† TP2012 TP2014 TP3012 | B3 I8 A6 H1 D4 H9 I9 H9 G10 F10 H10 L8 D9 | G2 C3 B3 F3 F3 J3 B5 C4 B5 B6 B6 C3 C4 |
| J3 J3 C4 B5 B3 C3 B4 B5 C5 | R2015 R2016 R2034 R2035 R2051 R3012 R3014 R3015 R3016† R3017 TP2012 TP2014 TP3012 | 18 18 A6 H1 D4 H9 H9 G10 F10 F10 L8 | C3 B3 B3 F3 J3 B5 C4 B5 B6 C3 C4 |
| J3 C4 B5 B3 C3 B4 B5 C5 | R2016 R2034 R2035 R2051 R3012 R3014 R3015 R3016† R3017† TP2012 TP2014 TP3012 | 18 A6 H1 D4 H9 19 H9 G10 F10 H10 L8 | 83 83 F3 J3 85 C4 85 86 86 C3 |
| C4 B5 B3 C3 B4 B5 C5 | R2034 R2035 R2051 R3012 R3014 R3015 R3016† R3017† TP2012 TP2014 TP3012 | 18 A6 H1 D4 H9 19 H9 G10 F10 H10 L8 | B3 F3 F3 J3 B5 C4 B5 B6 C3 C4 |
| 83 C3 B4 B5 C5 G2 E4 | R2035 R2051 R3012 R3014 R3015 R3016† R3017† TP2012 TP2014 TP3012 | H1 D4 H9 H9 H9 G10 F10 H10 L8 | F3 F3 J3 B5 C4 B5 B6 B6 C3 C4 |
| 83 C3 B4 B5 C5 G2 E4 | R2051 R3012 R3014 R3015 R3016† R3017† TP2012 TP2014 TP3012 | H1 D4 H9 H9 H9 G10 F10 H10 L8 | F3 J3 B5 C4 B5 B6 B6 C3 C4 |
| C3 B4 B5 C5 G2 E4 | R3012 R3014 R3015 R3016† R3017† TP2012 TP2014 TP3012 | D4 H9 I9 H9 G10 F10 H10 L8 D9 | J3 B5 C4 B5 B6 B6 C3 C4 |
| C3 B4 B5 C5 G2 E4 | R3014 R3015 R30161 R30171 TP2012 TP2014 TP3012 | H9 19 H9 G10 F10 H10 L8 D9 | 85 C4 85 86 86 C3 C4 |
| B4 B5 C5 G2 E4 | R3015 R3016† R3017† TP2012 TP2014 TP3012 | H9 G10 F10 H10 L8 D9 | C4 B5 B6 B6 C3 C4 |
| B5 C5 G2 E4 | R3016† R3017† TP2012 TP2014 TP3012 | G10 F10 H10 L8 D9 | 85 86 86 C3 C4 |
| C5 G2 E4 | R3017† TP2012 TP2014 TP3012 | F10 H10 L8 D9 | 86 86 C3 C4 |
| G2 E4 | TP2012 TP2014 TP3012 | H10 L8 D9 | C3 C4 |
| E4 | TP2014 TP3012 | L8 D9 | C4 |
| E4 | TP3012 | D9 | |
| | | | C4 |
| | U1037 | | |
| H3 | | G3 | F2 |
| *** | U1048 | C4 | H2 |
| A3 | U2013 | K8 | B 4 |
| H3 | U2014 | F10 | 84 |
| M3 | U2027 | Ċ3 | D4 |
| - | U2043 | J4 | G2 |
| D2 | U2045 | J2 | U2 |
| | U2047 | F4 | G3 |
| | Y2054 | D4 | J3 |
| ASSY also shown or | 1 🗘 🔇 | \$ \$ | |
| | | DISPL | AY BOARD |
| A4 | Bouse | DC DC | |
| | R2036 | C6 | D3 D3 |
| D4 | S3012 | 86 | A.4 |
| | | | A4 D4 |
| D4 B3 A3 | | 50 | |
| | | D4 R2036 B3 S3012 | A4 R2035 B6 C6 B3 S3012 B6 |

[†]May be located on back of board.

^{*}See Parts List for serial number ranges.





PARTS LOCATION GRID

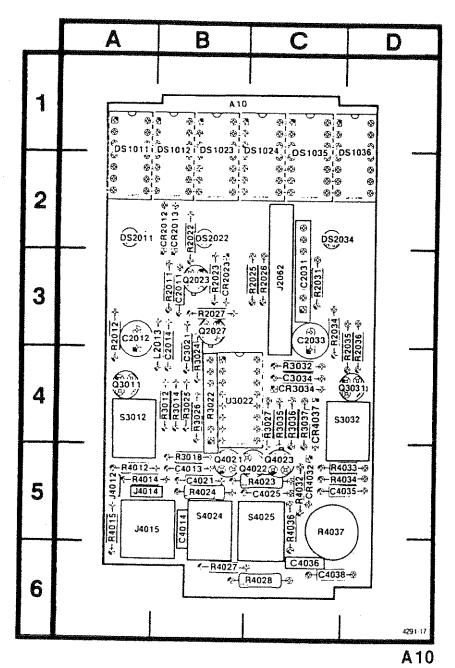


Fig. 8-8. Display Board (A10 Assy).





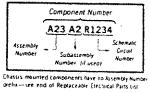




Table 8-4
COMPONENT REFERENCE CHART

| CIRCUIT NUMBER | SCHEMATIC LOCATION | BOARD LOCATION | CIRCUIT NUMBER | SCHEMATIC LOCATION | BOARD LOCATION |
|-------------------|-----------------------|-------------------|-------------------|-----------------------|-------------------|
| C2011 C2031 | D6 C3 | ВЗ СЗ | J2062 | B2 | СЗ |
| | | | P2062 | A 1 | C3 |
| CR2012 | C4 | 82 | | | |
| CR2013 | B4 | B2 | Q2023 | D7 | B3 |
| CR2023 | C6 | 83 | Q2027 | C6 | 83 |
| DS1011 | D3 | A1 | R2022 | D6 | 82 |
| DS1012 | E3 | 81 | R2023 | C7 | B3 |
| DS1023 | F3 | B1 | R2025 | 07 | C3 |
| DS1024 | G3 | Č1 | R2026 | C7 | C3 |
| DS1035 | 13 | Ĉ1 | R2027 | D6 | 83 |
| DS1036 | J3 | D1 | R2031 | F6 | C3 |
| DS2011 | C3 | A2 | 1 | . • | 50 |
| DS2022 | D6 | 82 | | | |
| DS2034 | F6 | C2 | - | | |

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PARTS LOCATION GRID

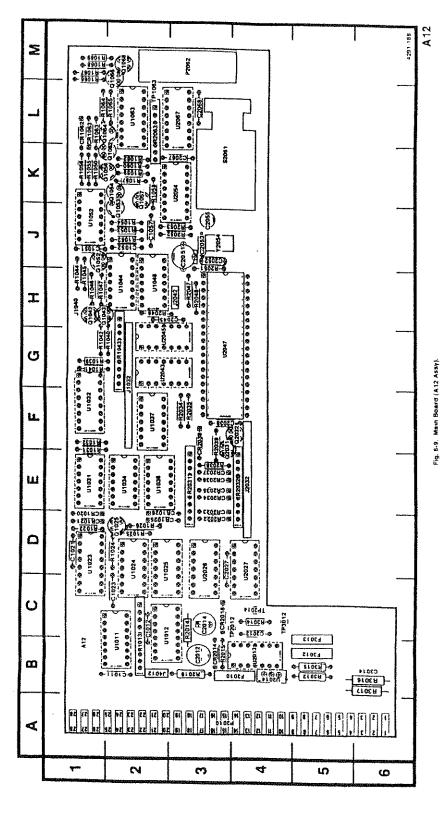


Table 8-5
COMPONENT REFERENCE CHART

| CIRCUIT | SCHEMATIC | BOARD | CIRCUIT | SCHEMATIC | BOARD |
|---------|------------|----------|----------------|-----------|----------|
| NUMBER | LOCATION | LOCATION | NUMBER | LOCATION | LOCATION |
| C1011 | J7 | B2 | R1013 | E10 | 82 |
| C1012 | K7 | C2 . | R1022 | 18 | D1 |
| C1021 | G10 | D1 | R1043A* | J6 | G2 |
| C1023 | D9 | Č2 | R2031 | C7 | E3 |
| C2027 | K8 | D3 | R2032 | D1 | E4 |
| | | | R2038 | B4 | E3 |
| CR1025 | 15 | D2 | R2039 | B4 | F3 |
| CR1026 | 16 | D2 | | | |
| CR2022 | B7 | D3 | S2061 | C3 | K3 |
| CR2023 | B 7 | E3 | | ato a | |
| CR2034 | E3 | E3 | U1011 | 17 | 82 |
| CR2035 | E3 | E3 | U1012 | E7 | C2 |
| CR2036 | E3 | E3 | U1023 | H10 | D1 |
| CR2037 | E2 | E3 | U1024 | F9 | D2 |
| CR2038 | G5 | F3 | U1025 | 15 | D2 |
| | | | U1031 | G5 | E1 |
| J2032 | A1 | E4 | U1034 | H11 | E2 E2 |
| | | _ | U1036 | G3 | F2 |
| Q2031 | C3 | F3 | U1037 U1048 | H4 G6 | H2 |
| Q2032 | B4 | F4 | U2026 | 45 | D3 |
| | | | U2026 U2027 | пэ D8 | D3 D4 |

^{*}See Parts List for serial number ranges.

REPLACEABLE MECHANICAL PARTS

PARTS ORDERING INFORMATION

Replacement parts are available from or through your local Tektronix, Inc. Field Office or representative.

Changes to Tektronix instruments are sometimes made to accommodate improved components as they become available, and to give you the benefit of the latest circuit improvements developed in our engineering department. It is therefore important, when ordering parts, to include the following information in your order: Part number, instrument type or number, serial number, and modification number if applicable.

If a part you have ordered has been replaced with a new or improved part, your local Textronix, Inc. Field Office or representative will contact you concerning any change in part number.

Change information, if any, is located at the rear of this manual.

SPECIAL NOTES AND SYMBOLS

X000 Part first added at this serial number

00X Part removed after this serial number

FIGURE AND INDEX NUMBERS

Items in this section are referenced by figure and index numbers to the illustrations.

INDENTATION SYSTEM

This mechanical parts list is indented to indicate item relationships. Following is an example of the indentation system used in the description column.

1 2 3 4 5

Name & Description

Assembly and/or Component Attaching parts for Assembly and/or Component

Detail Part of Assembly and/or Component Attaching parts for Detail Part

Parts of Detail Part
Attaching parts for Parts of Detail Part

Attaching Parts always appear in the same indentation as the item it mounts, while the detail parts are indented to the right. Indented items are part of, and included with, the next higher indentation. The separation symbol - - - * - - - indicates the end of attaching parts.

Attaching parts must be purchased separately, unless otherwise specified.

ITEM NAME

In the Parts List, an Item Name is separated from the description by a colon (:). Because of space limitations, an Item Name may sometimes appear as incomplete. For further Item Name identification, the U.S. Federal Cataloging Handbook H6-1 can be utilized where possible.

ABBREVIATIONS

| •• | INCH | ELCTRN | ELECTRON | #N | INCH | SE | SINGLE END |
|------------|--------------------|---------|-----------------------|----------|----------------------|--------|-----------------|
| | NUMBER SIZE | ELEC | ELECTRICAL | INCAND | INCANDESCENT | SECT | SECTION |
| ACTR | ACTUATOR | ELCTLT | ELECTROLYTIC | INSUL | INSULATOR | | SEMICONDUCTOR |
| ADPTR | ADAPTER | | ELEMENT | INTL | INTERNAL | | SHIELD |
| ALIGN | ALIGNMENT | ELEM | | ••• | - | SHLD | |
| | | EPL | ELECTRICAL PARTS LIST | LPHLDR | LAMPHOLDER | SHLDR | SHOULDERED |
| AL | ALUMINUM | EQPT | EQUIPMENT | MACH | MACHINE | SKT | SOCKET |
| ASSEM | ASSEMBLED | EXT | EXTERNAL | MECH | MECHANICAL | SL | SLIDE |
| ASSY | ASSEMBLY | FIL | FILLISTER HEAD | MTG | MOUNTING | SLFLKG | SELF-LOCKING |
| ATTEN | ATTENUATOR | FLEX | FLEXIBLE | NIP | NIPPLE | SLVG | SLEEVING |
| AWG | AMERICAN WIRE GAGE | FLH | FLAT HEAD | NON WIRE | NOT WIRE WOUND | SPR | SPRING |
| 8 0 | BOARD | FLTR | FILTER | OBD | ORDER BY DESCRIPTION | \$O | SOUARE |
| BRKT | BRACKET | FR | FRAME or FRONT | OD | OUTSIDE DIAMETER | SST | STAINLESS STEEL |
| BRS | BRASS | FSTNR | FASTENER | OVH | OVAL HEAD | STL | STEEL |
| BRZ | BRONZE | FT | FOOT | PH BRZ | PHOSPHOR BRONZE | SW | SWITCH |
| BSHG | BUSHING | FXD | FIXED | PL | PLAIN or PLATE | T | TUBE |
| CAB | CABINET | GSKT | GASKET | PLSTC | PLASTIC | TERM | TERMINAL |
| CAP | CAPACITOR | HDL | HANDLE | PN | PART NUMBER | THD | THREAD |
| CER | CERAMIC | HEX | HEXAGON | PNH | PAN HEAD | THK | THICK |
| CHAS | CHASSIS | HEX HD | HEXAGONAL HEAD | PWR | POWER | TNSN | TENSION |
| CKT | CIRCUIT | HEX SOC | HEXAGONAL SOCKET | RCPT | RECEPTACLE | TPG | TAPPING |
| COMP | COMPOSITION | HLCPS | HELICAL COMPRESSION | RES | RESISTOR | TRH | TRUSS HEAD |
| CONN | CONNECTOR | HLEXT | HELICAL EXTENSION | RGD | RIGID | v | VOLTAGE |
| COV | COVER | HV | HIGH VOLTAGE | RLF | RELIEF | VAR | VARIABLE |
| CPLG | COUPLING | | | RTNR | RETAINER | | WITH |
| | | ŧC | INTEGRATED CIRCUIT | | | W/ | |
| CRT | CATHODE RAY TUBE | 10 | INSIDE DIAMETER | SCH | SOCKET HEAD | WSHR | WASHER |
| DEG | DEGREE | IDENT | IDENTIFICATION | SCOPE | OSCILLOSCOPE | XFMR | TRANSFORMER |
| DWR | DRAWER | IMPLR | IMPELLER | SCR | SCREW | XSTR | TRANSISTOR |

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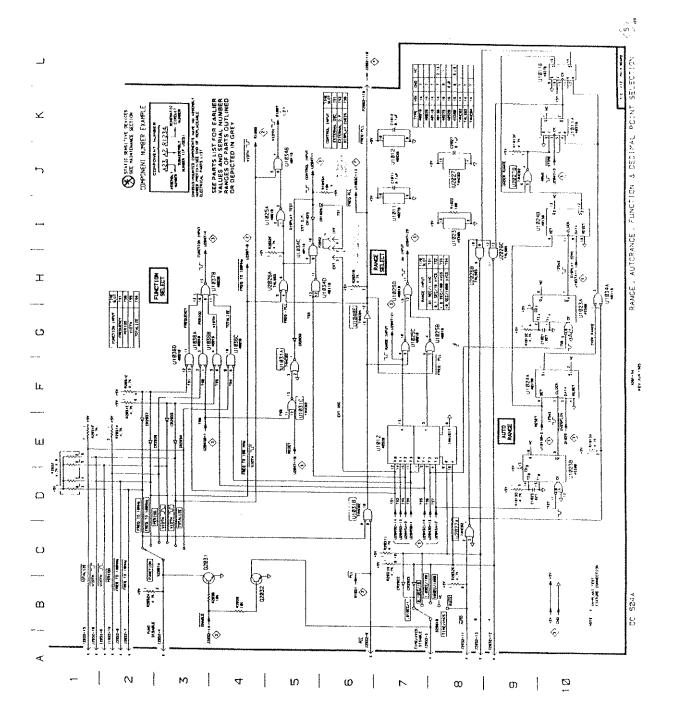
CROSS INDEX - MFR. CODE NUMBER TO MANUFACTURER

| Mfr. | | | |
|--------|---|--|------------------------------|
| Code | Manufacturer | Address | City, State, Zip Code |
| 00261 | GENERAL ELECTRIC CO FOOD SERVICE EQUIPMENT BUSINESS DEPT | 14TH AND ARNOLD STS | CHICAGO HEIGHTS IL 60411 |
| 09772 | WEST COAST LOCKWASHER CO INC | 16730 E JOHNSON DRIVE P O BOX 3588 | CITY OF INDUSTRY CA 91744 |
| 09922 | BURNDY CORP | RICHARDS AVE | NORWALK CT 06852 |
| 22526 | DU PONT E I DE NEMOURS AND CO INC DU PONT CONNECTOR SYSTEMS DIV MILITARY PRODUCTS GROUP | 515 FISHING CREEK RD | NEW CUMBERLAND PA 17070-3007 |
| 55285 | BERGOUIST CO INC THE | 5300 EDINA INDUSTRIAL BLVD | MINNEAPOLIS MN 55435-3707 |
| 71159 | BRISTOL SOCKET SCREW CO | | WATERBURY CT |
| 73743 | FISCHER SPECIAL MFG CO | III INDUSTRIAL RD | COLD SPRING KY 41076-9749 |
| 78189 | ILLINOIS TOOL WORKS INC SHAKEPROOF DIV | ST CHARLES ROAD | ELGIN IL 60120 |
| 80009 | TEKTRONIX INC | 14150 SW KARL BRAUM DR PO BOX 500 MS 53-111 | BEAVERTON OR 97077 |
| 83385 | MICRODOT MFG INC GREER-CENTRAL DIV | 3221 W BIG BEAVER RD | TROY MI 48098 |
| 93907 | TEXTRON INC CAMCAR DIV | 600 18TH AVE | ROCKFORD IL 61101 |
| TK0392 | NORTHWEST FASTENER SALES INC | 7923 SW CIRRUS DRIVE | BEAVERTON OR 97005-6448 |
| TK0435 | LEWIS SCREW CO | 4300 S RACINE AVE | CHICAGO IL 60609-3320 |
| TK0772 | RADAR ELECTRIC | 168 WESTERN AVE W | SEATTLE WA 98119-4212 |
| TK0858 | STAUFFER SUPPLY CO | 105 SE TAYLOR | PORTLAND OR 97214 |
| TK1326 | NORTHWEST FOURSLIDE INC | 18224 SW 100TH CT | TUALATIN OR 97062 |

| Fig. & Index No. | Tektronix Part No. | Serial/Assembly No. Effective Dscont | Qty | 12345 Name & Description | Mfr. Code Mfr. Part No. |
|------------------------|-----------------------|---|-----|--|---|
| | | LITERING BACKLE | | | 80009 337-3039-00 |
| 1-1 | 337-3039-00 | | 2 | SHIELD, ELEC: SIDE | 80009 105-0932-00 |
| -2 | 105-0932-00 | | 2 | LATCH, PANEL: SIDE FASTENER, LATCH: ACETAL, SIL GRAY | 80009 214-3364-00 |
| -3 | 214-3364-00 | | 2 | KNOB:GY,0.127 ID X 0.392 OD X 0.531 H | 80009 366-1023-13 |
| -4 | 366-1023-13 | | 1 | | 71159 ORDER BY DESCR |
| _ | 213-0246-00 | | 1 | .SETSCREW:5-40 X 0.094,STL KNOB:DOVE GRAY,0.421 ID X 0.706 0D X 0.6 H | 80009 366-2156-00 |
| -5 | 366-2156-00 | | 1 | | TK0392 ORDER BY DESCR |
| | 213-0153-00 | | 2 | .SETSCREW:5-40 X 0.125,STL BUSHING,SLEEVE:0.197 ID X 0.438 00 X 0.375 | 80009 358-0686-00 |
| -6 | 358-0686-00 | | 1 | (ATTACHING PARTS) | |
| -7 | 220-0495-00 | | 1 | NUT, PLAIN, HEX: 0.375-32 X 0.438 HEX, BRS | 73743 ORDER BY DESCR 80009 344-0195-01 |
| -8 | 344-0195-01 | | 1 | CLIP, ELECTRICAL: GROUNDING, PH BRZ ALBALOY PL | 09772 ORDER BY DESCR |
| -9 | 210-0012-00 | | 1 | WASHER, LOCK: 0.384 ID, INTL, 0.022 THK, STL (END ATTACHING PARTS) | |
| -10 | 378-2030-05 | | 1 | LENS, LED DSPL:RED W/MARKINGS | 80009 378-2030-05 |
| | 334-4827-00 | | 1 | MARKER, IDENT: MKD DC504A | 80009 334-4827-00 |
| -11 | 366-1851-01 | | 1 | KNOB, LATCH: IVORY GY, 0.625 X 0.25 X 1.09 | 80009 365-1851-01 |
| -12 | 105-0865-00 | | 1 | BAR, LATCH RLSE: | 80009 105-0865-00 |
| -13 | 105-0866-00 | | 1 | LATCH, RETAINING: SAFETY | 80009 105-0866-00 |
| -14 | 214-3143-00 | | 1 | SPRING, HLEXT: 0.125 OD X 0.545 L.XLOOP | 80009 214-3143-00 |
| -15 | 366-0494-08 | | 1 | KNOB:GY, NEW GEN. 0.1271D X 0.5300 X 0.5H | 80009 366-0494-08 |
| | 213-0246-00 | | 1 | .SETSCREW:5-40 X 0.094,STL | 71159 ORDER BY DESCR |
| -16 | 333-3009-00 | | 1 | FRONT PNL ASSY: | 80009 333-3009-00 |
| -17 | 337-3044-00 | | 1 | SHIELD, ELEC: FRONT SUBPANEL | 80009 337-3044-00 |
| -18 | 426-0725-24 | | 1 | FR SECT, PLUG-IN: TOP | 80009 426-0725-24 |
| | | | | (ATTACHING PARTS) | THREE DONED BY DECCO |
| -19 | 211-0101-00 | | 2 | SCREW, MACHINE:4-40 X 0.25, FLH, 100 DEG, STL (END ATTACHING PARTS) | |
| -20 | 214-3406-00 | | 1 | SPRING, FLAT: 1.48 L X 0.125 W.CU BE | TK1326 ORDER BY DESCR |
| -21 | 214 5400 00 | | i | CKT BOARD ASSY:DISPLAY(SEE A10 REPL) | • |
| 21 | | | - | (ATTACHING PARTS) | |
| 22 | 211-0244-00 | | 2 | SCR. ASSEM WSHR: 4-40 X 0.312, PNH STL | TK0858 211-0244-00 |
| ** L C | Z11054400 | | _ | (END ATTACHING PARTS) | |
| | | | | CUT DOADO ACCU INCLINES | |
| -23 | 136-0494-00 | | 6 | .SKT.PL-IN ELEK:MICROCIRCUIT,14 DIP | 80009 136-0494-00 |
| 24 | 136-0252-07 | | 6 | SOCKET.PIN CONN:W/O DIMPLE | 22526 75060-012 |
| -25 | 130-0232-07 | - | ĩ | CONN.RCPT.ELEC:(SEE A10J2062 REPL) | |
| -26 | | | 1 | TERM SET.PIN:(SEE ALOJ4012,4014 REPL) | |
| -27 | 131-0993-00 | 4 | ī | .BUS.CONDUCTOR:SHUNT ASSEMBLY,BLACK | 22526 65474-005 |
| -28 | 101 0000 00 | | 1 | .RESVAR.NONWIR:(SEE AIOR4037 REPL) | |
| -29 | | | 1 | .CONN.RCPT.ELEC:(SEE A10J4015 REPL) | |
| | | | | (ATTACISTAC DADTC) | ODOED DV DECOR |
| -30 | 210-0473-00 | | 1 | .NUT.PLAIN,DODEC:0.469-32 X 0.638,BRS NP | /3/43 DRUER BY DESCR |
| 21 | | | 3 | .SWITCH, PUSH: (SEE A10S3032, 4024, 425 REPL) | |
| -31 -32 | | | 1 | .SWITCH.PUSH: (SEE ALOS3012 REPL) | |
| -32 -33 | 366-1559-09 | | 4 | PUSH BUTTON: IVORY GRAY, 0.18 SQ X 0.43 H | 80009 366-1559-09 |
| -34 | 200 1300 00 | | 1 | CKT BOARD ASSY:MAIN(SEE A12 REPL) (ATTACHING PARTS) | |
| _ | | | | SCREW.TPG.TF:6-20 X 0.312, TYPE B, PNH, STL | 83385 ORDER BY DESCR |
| -35 | 213-0146-00 | • | 4 | (END ATTACHING PARTS) | |
| | | | | CKT BOARD ASSY INCLUDES: | |
| -36 | | | 1 | .CONN, RCPT, ELEC: (SEE A12P2062 REPL) | 00022 NI DICD 100T |
| -37 | 136-0729-00 | | 1 | SKT, PL-IN ELEK: MICROCKT, 16 CONTACT | 09922 DILB16P-108T 09922 DILB40P-108 |
| -38 | 136-0757-00 | | 1 | .SKT, PL-IN ELEK: MICROCIRCUIT, 40 DIP | 09955 DIFD401-100 |
| -39 | | | 1 | .SWITCH, ROTARY: (SEE A12S2061 REPL) | |
| -40 | | | 1 | .CONN.RCPT, ELEC: (SEE A12J1032, 2032 REPL) | |
| -41 | | | 9 | TERMINAL PIN: (SEE A12J1040, 2042, 4012 REPL) | ODEDE CEATA DOE |
| -42 | | | 2 | RUS_CONDUCTOR:SHUNT ASSEMBLY,BLACK | 22526 65474-005 |
| -43 | 101 0000 00 | | 4 | .TERM.TEST POINT: (SEE A12TP1063, TP2012, | • |
| -44 | سومد هو چه پند | | 1 | .TP2014,TP3012 REPL) .MICROCIRCUIT,LI:(SEE A12U2014 REPL) | |
| | | | 1 | .(ATTACHING PARTS) | 78189 51-040445-01 |
| -45 | | | | | 73743 12161-50 |
| -46 | | | 1 | | 00261 A7148516P2 |
| -47 | 210-1171-00 | • | 1 | (FND ATTACHING PARTS) | TK0772 10-18-2033 |
| -48 -49 | | | 1 | | 55285 7403-09FR-52 |

*

| Fig. & Index No. | Tektronix Part No. | Serial/Asser Effective | bly No. Decont | Qty | 12345 | Name & Description | Mfr. Code | Mfr. Part No. |
|------------------------|----------------------------|---------------------------|-------------------|-----|------------------|--|----------------|----------------------------------|
| 1-50 -51 | 351-0612-00 426-0724-25 | | | 1 | FR SEC | KT BOARD:NYLON,1.0 L ,PLUG-IN:BOTTOM | 80009 80009 | 351-0612-00 426-0724-25 |
| -52 | 211-0101-00 | | | 2 | SCREW, | IING PARTS) VACHINE:4-40 X 0.25.FLH,100 DEG,STL TACHING PARTS) | | ORDER BY DESCR |
| -53 | 386-4910-00 | | | 1 | | (,FRAME:REAR HING PARTS) | 80009 | 386-4910-00 |
| -54 -55 | 213-0868-00 386-3657-01 | | | 2 2 | SCREW, SUPPOR | THE FARTS, PG.TF:6-32 X 0.375 L,FILH,STL T,PLUG-IN: TTACHING PARTS) | 93907 93907 | ORDER BY DESCR ORDER BY DESCR |
| | 175-2985-00 | | | i | | SSEMBLIES ASSY,RF:50 OHM COAX,10.0 L,9-3 | 80009 | 175-2985-00 |
| | 070-4291-00 | | | 1 | STANDA MANUAL | RD ACCESSORIES ,TECH:INSTRUCTION,DC504A | 80009 | 070-4291-00 |



. ,

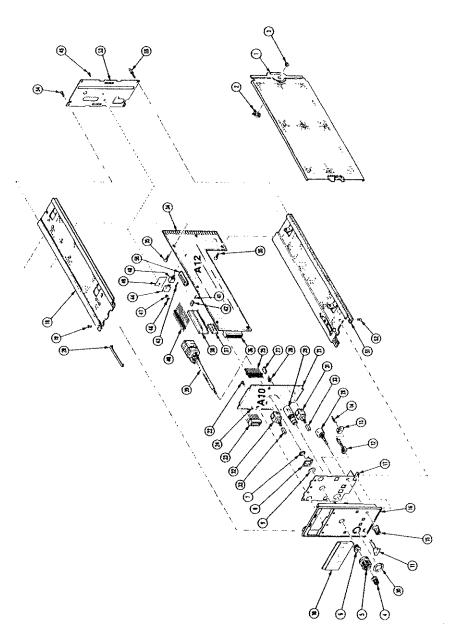


Table 8-2 COMPONENT REFERENCE CHART

| P/O A12 AS | SY | | | MAIN BO | DARD (2) | | | | | | |
|-------------------|----------------------------------|----|---------|-----------------------|-------------------|--|--|--|--|--|--|
| CIRCUIT NUMBER | | | | SCHEMATIC LOCATION | BOARD LOCATION | | | | | | |
| C1051 | L7 | J1 | R1046 | J5 | Н1 | | | | | | |
| C1052 | G6 | J2 | R1047 | G6 | H1 | | | | | | |
| C1057 | H5 | J2 | R1050 | C5 | K1 | | | | | | |
| C2055 | G 7 | Jä | R1052 | J4 | Ĵ2 | | | | | | |
| C2067 | E5 | K3 | R1053 | 16 | J2 J2 | | | | | | |
| C2068 | C3 | L3 | R1054 | 16 | J2 | | | | | | |
| 1 | | | R1055 | Č5 | K1 | | | | | | |
| CR1020 | L5 | D1 | R1056 | 16 | K1 | | | | | | |
| CR1021 | L5 | D1 | R1057 | Ğ5 | K2 | | | | | | |
| CR1062 | J6 | Ĭi | R1058 | Ğ4 | K2 | | | | | | |
| CR1063 | C4 | Ξi | R1059 | D5 | K2 | | | | | | |
| 1 | -, | _, | R1060 | D5 | K2 | | | | | | |
| J1040 | 19 | H1 | R1062 | B4 | K2 | | | | | | |
| | | | R1063 | G2 | Lī | | | | | | |
| P1040 | J9 | H1 | R1064 | H4 | Ĺi | | | | | | |
| | • • | | R1065 | G4 | L2 | | | | | | |
| Q1042 | H7 | H1 | R1066 | Ďi | M1 | | | | | | |
| Q1043 | F8 | H1 | R1067 | D2 | M1 | | | | | | |
| Q1052 | J4 | Ĵĵ | R1068 | L6 | M1 | | | | | | |
| Q1053 | G5 | J2 | R1069 | L6 | M1 | | | | | | |
| Q1054 | J6 | K2 | R2046 | F7 | H2 | | | | | | |
| Q1056 | C5 | K1 | R2047 * | 13 | H3 | | | | | | |
| Q1057 | J4 | K2 | R2048 * | J3 | Н3 | | | | | | |
| Q1062 | G2 | K1 | R2052 | F6 | J3 | | | | | | |
| Q1064 | H2 | LI | R2053 | F6 | J3 | | | | | | |
| Q1066 | D2 | M2 | R2063 | E 3 | L2 | | | | | | |
| Q1068 | D1 | M2 | | | | | | | | | |
| | | | TP1063 | B2 | L2 | | | | | | |
| R1031 | K5 | F1 | | | | | | | | | |
| R1032 | L5 | F1 | U1032 | 18 | F1 | | | | | | |
| R 1039 | H7 | G1 | U1044 | G6 | H2 | | | | | | |
| R1040 | G7 | G1 | U1048 | Н3 | H2 | | | | | | |
| R1041 | G8 | G1 | U1052 | J6 | J1 | | | | | | |
| R1042 | F8 | G2 | U1063 | C1 | L2 | | | | | | |
| R1044 | K6 | H1 | U2054 | F5 | K3 | | | | | | |
| R1045 | J5 | H1 | U2067 | D4 | L3 | | | | | | |
| | P/O A12 ASSY also shown on 1 3 5 | | | | | | | | | | |

^{*}See Parts List for serial number ranges.

Table 8-3
COMPONENT REFERENCE CHART

| | | | | | | |
|-------------------|-----------------------|-------------------|-------------------|-----------------------|-------------------|--|
| P/O A12 ASS | 3Y | | | MAIN BO | DARD 3 | |
| CIRCUIT NUMBER | SCHEMATIC LOCATION | BOARD LOCATION | CIRCUIT NUMBER | SCHEMATIC LOCATION | BOARD LOCATION | |
| C2012 | К8 | B3 | R1013 | F4 | B2 | |
| C2014 | G10 | C3 | R1024 | C2 | D2 | |
| C2038 | L8 | F3 | R1025 | C2 | D2 | |
| C2045 | Ĺ9 | A2 | R1026 | C2 | D2 | |
| C2051 | Č4 | J3 | R1043 | K1 | G2 | |
| C2052 * | D4 | J3 | R2014* | B 3 | C3 | |
| C2053 | C4 | J3 | R2015 | 18 | B3 | |
| C3013 | 19 | C4 | R2016 | 18 | B3 | |
| C3014 | F10 | B5 | R2034 | A6 | F3 | |
| | | | R2035 | H1 | F3 | |
| CR2014 | K8 | B 3 | R2051 | D4 | J3 | |
| CR2018 | H10 | C3 | R3012 | H9 | B5 | |
| | | | R3014 | 19 | C4 | |
| F2010 | E8 | B4 | R3015 | H9 | B 5 | |
| F3012 | E8 | B 5 | R3016† | G10 | B6 | |
| F3013 | E10 | C5 | R3017† | F10 | B6 | |
| | | | TP2012 | H10 | C3 | |
| J1032 | B 3 | G2 | TP2014 | L8 | C4 | |
| J2032 | D7 | E4 | TP3012 | D9 | C4 | |
| J2042 | D3 | H3 | U1037 | G3 | F2 | |
| | | | U1048 | C4 | H2 | |
| P2010 | D10 | A3 | U2013 | K8 | B4 | |
| P2042 | D3 | H3 | U2014 | F10 | B4 | |
| P2062 | 15 | M3 | U2027 | C3 | D4 | |
| | | | U2043 | J4 | G2 | |
| Q1025 | C2 | D2 | U2045 U2047 | J2 F4 | U2 | |
| | | | Y2054 | D4 | G3 J3 | |
| | 9/O A12 A6 | SSY also shown o | - 4 | <u> </u> | | |
| | 1/0 A12 A | os also shown (| " V V | 2> <5> | | |
| P/O A10 AS | SY | | | DISP | LAY BOARD | |
| Q3011 | B6 | A4 | R2035 | B6 | D3 | |
| Q3031 | B6 | D4 | R2036 | C6 | D3 | |
| R2011 | B7 | В3 | \$3012 | B6 | A4 | |
| R2012 | C6 | A3 | S3032 | 86 | D4 | |
| | P/O A10 | ASSY also show | vn on 🗘 | 4 | | |
| | | | | | | |

[†]May be located on back of board.

^{*}See Parts List for serial number ranges.

Table 8-5
COMPONENT REFERENCE CHART

| CIRCUIT NUMBER | SCHEMATIC LOCATION | BOARD LOCATION | CIRCUIT NUMBER | SCHEMATIC LOCATION | BOARD LOCATION |
|-------------------|-----------------------|-------------------|-------------------|-----------------------|-------------------|
| 04044 | 1-4 | D 0 | R1013 | E10 | B2 |
| C1011 C1012 | J7 K7 | B2 C2 | R1022 | 18 | D1 |
| C1012 | G10 | D1 | R1043A* | J6 | G2 |
| C1021 | D9 | C2 | R2031 | C7 | E3 |
| C2027 | K8 | D3 | R2032 | D1 | E4 |
| C2021 | NO. | <u>U</u> 3 | R2038 | 84 | E3 |
| CR1025 | 15 | D2 | R2039 | B4 | F3 |
| CR1026 | iš | D2 | | | |
| CR2022 | B7 | D3 | \$2061 | C3 | K3 |
| CR2023 | B7 | E3 | | _ | |
| CR2034 | E3 | E3 | U1011 | 17 | B2 |
| CR2035 | E3 | E3 | U1012 | E7 | C2 |
| CR2036 | E3 | E3 | U1023 | H10 | D1 |
| CR2037 | E2 | E3 | U1024 | F9 | D2 |
| CR2038 | G5 | F3 | U1025 | 15_ | D2 |
| | | | U1031 | G5 | E1 |
| J2032 | A1 | E4 | U1034 | H11 | E2 |
| | | | U1036 | G3 | E2 |
| Q2031 | C3 | F3 | U1037 | H4 | F2 |
| Q2032 | B4 | F4 | U1048 | G6 | H2 D3 |
| | | | U2026 U2027 | H5 D8 | D3 D4 |

^{*}See Parts List for serial number ranges.

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REPLACEABLE MECHANICAL PARTS

PARTS ORDERING INFORMATION

Replacement parts are available from or through your local Tektronix, Inc. Field Office or representative.

Changes to Tektronix instruments are sometimes made to accommodate improved components as they become available, and to give you the benefit of the latest circuit improvements developed in our engineering department. It is therefore important, when ordering parts, to include the following information in your order Part number, instrument type or number, serial number, and modification number if applicable.

If a part you have ordered has been replaced with a new or improved part, your local Tektronix, Inc. Field Office or representative will contact you concerning any change in part number.

Change information, if any, is located at the rear of this manual.

SPECIAL NOTES AND SYMBOLS

X000 Part first added at this serial number
00X Part removed after this serial number

FIGURE AND INDEX NUMBERS

Items in this section are referenced by figure and index numbers to the illustrations.

INDENTATION SYSTEM

This mechanical parts list is indented to indicate item relationships. Following is an example of the indentation system used in the description column.

1 2 3 4 5

Name & Description

Assembly and/or Component
Attaching parts for Assembly and/or Component

Detail Part of Assembly and/or Component Attaching parts for Detail Part

Parts of Detail Part Attaching parts for Parts of Detail Part

Attaching Parts always appear in the same indentation as the item it mounts, while the detail parts are indented to the right. Indented items are part of, and included with, the next higher indentation. The separation symbol - - - * - - - indicates the end of attaching parts.

Attaching parts must be purchased separately, unless otherwise specified.

ITEM NAME

In the Parts List, an Item Name is separated from the description by a colon (:). Because of space limitations, an Item Name may sometimes appear as incomplete. For further Item Name identification, the U.S. Federal Cataloging Handbook H6-1 can be utilized where possible.

ABBREVIATIONS

| ACTR ADPTR ALIGN ALIGN ASSEM ASSEM ASSEM ASSEM AWG BRKT BRS BRZ BSHG CAP CER CHAS CKT COMP CONN COV CPLG CPLG CHG | INCH NUMBER SIZE ACTUATOR ADAPTER ALIGNMENT ALUMINUM ASSEMBLED ASSEMBLY ATTENUATOR AMERICAN WIRE GAGE BOARD BRACKET BRASS BRONZE BUSHING CABINET CAPACITOR CERAMIC CHASSIS CIRCUIT COMPOSITION CONNECTOR COVER COUPLING CATHODE RAY TUBE DEGREE | ELCTRN ELEC ELCTLT ELEM EPL EOPT EXT FIL FLEX FLH FLTR FR FSTNR FT FXD GSKT HDL HEX | ELECTRON ELECTRICAL ELECTROLYTIC ELEMENT ELECTRICAL PARTS LIST EQUIPMENT EXTERNAL FILLISTER HEAD FILEXIBLE FLAT HEAD FILTER FRAME OF FRONT FASTENER FOOT FIXED GASKET HANDLE HEXAGONAL HEAD HEXAGONAL HELICAL COMPRESSION HELICAL LEXTENSION HIGH VOLTAGE INTEGRATED CIRCUIT INSIDE DIAMETER IDENTIFICATION | IN INCAND INSUL INTL LPHLDR MACH MTG NIP NON WIRE OBD OD OVH PH BRZ PL PLSTC PN PNH PWR RCPT RES RGD RLF RTNA SCH SCOPE | INCH INCANDESCENT INSULATOR INTERNAL LAMPHOLDER MACHINE MECHANICAL MOUNTING NIPPLE NOT WIRE WOUND ORDER BY DESCRIPTION OUTSIDE DIAMETER OVAL HEAD PHOSPHOR BRONZE PLAIN OF PLATE PLASTIC PART NUMBER PAN HEAD POWER RECEPTACLE RESISTOR RIGID RELIEF RETAINER SOCKET HEAD OSCILLOSCOPE | SE SECT SEMICOND SHLD SHLDA SKT SL SLFLKG SLVG SPR SO SST STL SW T TERM THD THK TNSN TPG TRH V VAR W/ WSHR KFMR | SINGLE END SECTION SEMICONDUCTOR SHIELD SHOULDERED SOCKET SLIDE SELF-LOCKING SLEEVING SPRING SOUARE STAINLESS STEEL STEEL SWITCH TUBE TERMINAL THREAD THICK TENSION TAPPING TRUSS HEAD VOLTAGE VARIABLE WITH WASHER TRANSFORMER |
|---|---|---|---|---|--|---|---|
| DEG DWR | DEGREE DRAWER | IDENT IMPLR | IDENTIFICATION IMPELLER | SCOPE SCR | SCREW | XEMH XSTR | TRANSISTOR |

CROSS INDEX - MFR. CODE NUMBER TO MANUFACTURER

| Mfr. | Manufacture | ****** | 014 04 1 77 C 4 |
|--------|---|--|------------------------------|
| Code | Manufacturer | Address | City, State, Zip Code |
| 00261 | GENERAL ELECTRIC CO FOOD SERVICE EQUIPMENT BUSINESS DEPT | 14TH AND ARNOLD STS | CHICAGO HEIGHTS IL 60411 |
| 09772 | WEST COAST LOCKWASHER CO INC | 16730 E JOHNSON DRIVE P O BOX 3588 | CITY OF INDUSTRY CA 91744 |
| 09922 | BURNDY CORP | RICHARDS AVE | NORWALK CT 06852 |
| 22526 | DU PONT E I DE NEMOURS AND CO INC DU PONT CONNECTOR SYSTEMS DIV MILITARY PRODUCTS GROUP | 515 FISHING CREEK RD | NEW CUMBERLAND PA 17070-3007 |
| 55285 | BERGQUIST CO INC THE | 5300 EDINA INDUSTRIAL BLVD | MINNEAPOLIS MN 55435-3707 |
| 71159 | BRISTOL SOCKET SCREW CO | | WATERBURY CT |
| 73743 | FISCHER SPECIAL MFG CO | 111 INDUSTRIAL RD | COLD SPRING KY 41076-9749 |
| 78189 | ILLINOIS TOOL WORKS INC SHAKEPROOF DIV | ST CHARLES ROAD | ELGIN IF 60150 |
| 80009 | TEKTRONIX INC | 14150 SW KARL BRAUM DR PO BOX 500 MS 53-111 | BEAVERTON OR 97077 |
| 83385 | MICRODOT MFG INC GREER-CENTRAL DIV | 3221 W BIG BEAVER RD | TROY MI 48098 |
| 93907 | TEXTRON INC CAMCAR DIV | 600 18TH AVE | ROCKFORD IL 61101 |
| TK0392 | NORTHWEST FASTENER SALES INC | 7923 SW CIRRUS DRIVE | BEAVERTON OR 97005-6448 |
| TK0435 | LEWIS SCREW CO | 4300 S RACINE AVE | CHICAGO IL 60609-3320 |
| TK0772 | RADAR ELECTRIC | 168 WESTERN AVE W | SEATTLE WA 98119-4212 |
| TK0858 | STAUFFER SUPPLY CO | 105 SE TAYLOR | PORTLAND OR 97214 |
| TK1326 | NORTHWEST FOURSLIDE INC | 18224 SW 100TH CT | TUALATIN OR 97062 |

| Fig. & Index No. | Tektronix Part No. | Serial/Assembly No. Effective Dscont | 0ty | 12345 Name & Description | Mfr. Code Mfr. Part No. |
|------------------------|----------------------------|---|--------|--|---|
| 1-1 | 337-3039-00 | | 2 | SHIELD, ELEC: SIDE | 80009 337-3039-00 |
| -2 | 105-0932-00 | | 2 | LATCH, PANEL: SIDE | 80009 105-0932-00 |
| -3 | 214-3364-00 | | 2 | FASTENER, LATCH: ACETAL, SIL GRAY | 80009 214-3364-00 |
| -4 | 366-1023-13 | | 1 | KNOB:GY,0.127 ID X 0.392 OD X 0.531 H | 80009 366-1023-13 |
| | 213-0246-00 | | 1 | .SETSCREW:5-40 X 0.094,STL | 71159 ORDER BY DESCR |
| -5 | 366~2156~00 | | 1 | KNOB: DOVE GRAY, 0.421 ID X 0.706 OD X 0.6 H | 80009 366-2156-00 |
| | 213-0153-00 | | 2 | .SETSCREW:5-40 X 0.125.STL | TK0392 ORDER BY DESCR |
| -6 | 358-0686-00 | | 1 | BUSHING, SLEEVE: 0.197 ID X 0.438 OD X 0.375 | 80009 358-0 686-0 0 |
| | | | | (ATTACHING PARTS) | TOTAL ACRED DU DECCO |
| -7 | 220-0495-00 | | 1 | NUT, PLAIN, HEX: 0.375-32 X 0.438 HEX, BRS | 73743 ORDER BY DESCR |
| -8 | 344-0195-01 | | 1 | CLIP, ELECTRICAL GROUNDING, PH BRZ ALBALOY PL | 80009 344-0195-01 |
| -9 | 210-0012-00 | | 1 | WASHER, LOCK: 0.384 ID, INTL, 0.022 THK, STL | 09772 ORDER BY DESCR |
| | | | | (END ATTACHING PARTS) | 80009 378-2030-05 |
| -10 | 378-2030-05 | | ì | LENS, LED DSPL:RED W/MARKINGS | 80009 334-4827-00 |
| | 334-4827-00 | | 1 | MARKER, IDENT: MKD DC504A | 80009 366-1851-01 |
| -11 | 366-1851-01 | | 1 | KNOB, LATCH: IVORY GY, 0.625 X 0.25 X 1.09 | 80009 105-0865-00 |
| -12 | 105-0865-00 | | 1 | BAR, LATCH RLSE: | 80009 105-0866-00 |
| -13 | 105-0866-00 | | 1 | LATCH, RETAINING: SAFETY | 80009 214-3143-00 |
| -14 | 214-3143-00 | | 1 | SPRING,HLEXT:0.125 OD X 0.545 L,XLOOP KNOB:GY.NEW GEN,0.127ID X 0.530D X 0.5H | 80009 366-0494-08 |
| -15 | 366-0494-08 | | 1 | .SETSCREW:5-40 X 0.094, STL | 71159 ORDER BY DESCR |
| | 213-0246-00 | | 1 | FRONT PNL ASSY: | 80009 333-3009-00 |
| -16 | 333-3009-00 | | 1 | SHIELD.ELEC:FRONT SUBPANEL | 80009 337-3044-00 |
| -17 | 337-3044-00 | | 1 | FR SECT, PLUG-IN: TOP | 80009 426-0725-24 |
| -18 | 426-0725-24 | | 1 | (ATTACHING PARTS) | |
| -19 | 211-0101-00 | | 2 | SCREW, MACHINE: 4-40 X 0.25, FLH, 100 DEG, STL | TK0435 ORDER BY DESCR |
| | | | | (END ATTACHING PARTS) | TK1326 ORDER BY DESCR |
| -20 | 214-3406-00 | | 1 | SPRING, FLAT: 1.48 L X 0.125 W,CU BE CKT BOARD ASSY:DISPLAY(SEE A10 REPL) | THEORY ONDER IS SESON |
| -21 | | | 1 | (ATTACHING PARTS) | |
| -22 | 211-0244-00 | | 2 | SCR, ASSEM WSHR:4-40 X 0.312, PNH STL (END ATTACHING PARTS) | TK0858 211-0244-00 |
| | | | | CKT BOARD ASSY INCLUDES: | 00000 100 0404 00 |
| -23 | 136-0494-00 | | 6 | | 80009 136-0494-00 |
| -24 | 136-0252-07 | | 5 | .SOCKET, PIN CONN:W/O DIMPLE | 22526 75060-012 |
| -25 | | | 1 | .CONN, RCPT, ELEC: (SEE A1QJ2062 REPL) | |
| -26 | | | 1 | TERM SET, PIN: (SEE A10J4012, 4014 REPL) | 22526 65474-005 |
| -27 | 131-0993-00 | | 1 | .BUS.CONDUCTOR:SHUNT ASSEMBLY, BLACK | 22320 03474-003 |
| -28 | | | 1 | .RES., VAR, NONVIR: (SEE A10R4037 REPL) | |
| -29 | | | 1 | .CONN,RCPT,ELEC:(SEE A10J4015 REPL) .(ATTACHING PARTS) | מממט מחשבה מע הבכבה |
| -30 | 210-0473-00 | | 1 | .NUT.PLAIN,DODEC: 0.469-32 X 0.638,BRS NP .(END ATTACHING PARTS) | 73743 UKUER DI DESCR |
| -31 -32 | | | 3 1 | SWITCH, PUSH: (SEE ALOS3032,4024,425 REPL) SWITCH, PUSH: (SEE ALOS3012 REPL) | |
| -33 | 366-1559-09 | | 4 | | 80009 366-1559-09 |
| -34 | 500 £350 W | | 1 | CKT BOARD ASSY: MAIN (SEE A12 REPL) | |
| ਪਾਰ | | | - | (ATTACHING PARTS) | |
| -35 | 213-0146-00 | | 4 | SCREW.TPG.TF:6-20 X 0.312, TYPE B, PNH, STL (END ATTACHING PARTS) | 83385 ORDER BY DESCR |
| | | | 1 | CKT BOARD ASSY INCLUDES: .CONN.RCPT.ELEC:(SEE A12P2062 REPL) | |
| -36 | | | 1 | CUNNICHI ELECTORE ALCEZOC RUFL) | 09922 DILB16P-108T |
| -37 | 136-0729-00 | | 1 | .SKT,PL-IN ELEK:MICROCKT,I6 CONTACT .SKT,PL-IN ELEK:MICROCIRCUIT,40 DIP | 09922 DILB40P-108 |
| -38 | 136-0757-00 | | 1 | SWITCH, ROTARY: (SEE A12S2061 REPL) | |
| -39 | | | 1 | .CONN.RCPT, ELEC: (SEE A12J1032, 2032 REPL) | |
| -40 | | | 9 | TERMINAL PIN: (SEE A12J1040, 2042, 4012 REPL) | |
| -41 | 131-0993-00 | | 2 | BUS, CONDUCTOR: SHUNT ASSEMBLY, BLACK | 22526 65474-005 |
| -42 | 131-0933-00 | | 4 | TERM TEST POINT: (SEE A12TP1063, TP2012, | |
| -43 | | | · | .TP2014.TP3012 REPL) | |
| -44 | | | 1 | .MICROCIRCUIT, LI: (SÉE A12U2014 REPL) .(ATTACHING PARTS) | 70100 E1 04044E 01 |
| -45 | | | 1 | SCR, ASSEM WSHR:4-40 X 0.29, PNH, BRS NI PL | 78189 51-040445-01 73743 12161-50 |
| -46 -47 | 210-0406-00 210-1171-00 | | 1 1 | .NUT, PLAIN, HEX: 4-40 X 0.188, BRS CD PL .WASHER, SHLDR: 0.12 ID X 0.143 OD X 0.07 D | 00261 A7148516P2 |
| ,, | | | | .(END ATTACHING PARTS) | TI/0770 40 40 0000 |
| -48 -49 | | | 1 | .SKT,PL-IN ELEK:TRANSISTOR,3 CONTACT INSULATOR,PLATE:TRANSISTOR | TK0772 10-18-2033 55285 7403-09FR-52 |

| Fig. & Index No. | Tektronix Part No. | Serial/Asser Effective | mbly No. Dscont | Qty | 12345 | Name | & Description | Mfr. Code | Mfr. Part | No. |
|------------------------|----------------------------|---------------------------|--------------------|--------|---------------------|-------------------------------|-------------------------------|----------------|--------------------------|--------|
| 1-50 -51 | 351-0612-00 426-0724-25 | | | 1 | | | ARD:NYLON,1.0 L ·IN:BOTTOM | 80009 80009 | 351-0612-0 426-0724-2 | • |
| -52 | 211-0101-00 | | | 2 | SCREW, | | E:4-40 X 0.25,FLH,100 DEG,STL | TK0435 | ORDER BY C | ESCR . |
| -53 | 386-4910-00 | | | 1 | Support | TIACHIN T.FRAME HING PA | | 80009 | 386-4910-0 | 0 |
| -54 -55 | 213-0868-00 386-3657-01 | | | 2 2 | SCREW, I SUPPORT | TPG,TF: T,PLUG- | 6-32 X 0.375 L,FILH,STL | 93907 93907 | ORDER BY D | |
| | 175-2985-00 | | | 1 | WIRE AS | | ES :50 OHM COAX,10.0 L,9-3 | 80009 | 175-2985-0 | 0 |
| | 070-4291-00 | | | 1 | _ | | SSORIES NSTRUCTION, DC504A | 80009 | 070-4291-0 | 0 |