#### SECTION III OPERATING INSTRUCTIONS

#### 3-1 OPERATING CONTROLS AND INDICATORS

3-2 The front panel controls and indicators, together with the normal turn-on sequence, are shown in Figure 3-1.



 REMOVE SHORT AND CONNECT LOAD TO OUTPUT TERMINALS(FRONT OR REAR).

Figure 3-1. Front Panel Controls and Indicators

#### 3-3 OPERATING MODES

The power supply is designed so that its mode 3-4 of operation can be selected by making strapping connections between particular terminals on the terminal strip at the rear of the power supply. The terminal designations are stenciled in white on the power supply above their respective terminals. Although the strapping patterns illustrated in this section show the positive terminal grounded, the operator can ground either terminal or operate the power supply up to 300Vdc off ground (floating). The following paragraphs describe the procedures for utilizing the various operational capabilities of the power supply. A more theoretical description concerning the operational features of this supply is contained in Application Note 90, DC Power Supply Handbook.which may be obtained from your local Hewlett-Packard field sales office.

#### 3-5 NORMAL OPERATING MODE

3-6 The power supply is normally shipped with its rear terminal strapping connections arranged for Constant Voltage/Constant Current, local sensing, local programming, single unit mode of operation. This strapping pattern is illustrated in Figure 3-2. The operator selects either a constant voltage or a constant current output using the front panel controls (local programming, no strapping changes are necessary).



Figure 3-2. Normal Strapping Pattern

## 3-7 CONSTANT VOLTAGE

3-8 To select a constant voltage output, proceed as follows:

a. Turn-on power supply and adjust VOLTAGE controls for desired output voltage (output terminals open).

b. Short output terminals and adjust CUR-RENT controls for maximum output current allowable (current limit), as determined by load conditions. If a load change causes the current limit to be exceeded, the power supply will automatically crossover to constant current output at the preset current limit and the output voltage will drop proportionately. In setting the current limit, allowance must be made for high peak current which can cause unwanted cross-over. (Refer to Paragraph 3-46.)

#### 3-9 CONSTANT CURRENT

3-10 To select a constant current output, proceed as follows:

a. Short output terminals and adjust CUR-RENT controls for desired output current.

b. Open output terminals and adjust VOLTAGE controls for maximum output voltage allowable (volt-age limit), as determined by load conditions. If a

load change causes the voltage limit to be exceeded, the power supply will automatically crossover to constant voltage output at the preset voltage limit and the output current will drop proportionately. In setting the voltage limit, allowance must be made for high peak voltages which can cause unwanted crossover. (Refer to Paragraph 3-46.)

# 3-11 CONNECTING LOAD

3-12 Each load should be connected to the power supply output terminals using separate pairs of connecting wires. This will minimize mutual coupling effects between loads and will retain full advantage of the low output impedance of the power supply. Each pair of connecting wires should be as short as possible and twisted or shielded to reduce noise pickup. (If shield is used, connect one end to power supply ground terminal and leave the other end unconnected.)

3-13 If load considerations require that the output power distribution terminals be remotely located from the power supply, then the power supply output terminals should be connected to the remote distribution terminals via a pair of twisted or shielded wires and each load separately connected to the remote distribution terminals. For this case, remote sensing should be used (Paragraph 3-20).

# 3-14 OPERATION OF SUPPLY BEYOND RATED OUTPUT

3-15 The shaded area on the front panel meter face indicates the amount of output voltage or current that is available in excess of the normal rated output. Although the supply can be operated in this shaded region without being damaged, it cannot be guaranteed to meet all of its performance specifications. However, if the line voltage is maintained above 115 Vac, the supply will probably operate within its specifications.

# 3-16 OPTIONAL OPERATING MODES

3-17 REMOTE PROGRAMMING, CONSTANT VOLTAGE

3-18 The constant voltage output of the power supply can be programmed (controlled) from a remote location if required. Either a resistance or voltage source can be used for the programming device. The wires connectin the programming terminals of the supply to the remote programming device should be twisted or shielded to reduce noise pick-up. The VOLTAGE controls on the front panel are disabled according to the following procedures.

3-19 <u>Resistance Programming (Figure 3-3)</u>. In this mode, the output voltage will vary at a rate determined by the programming coefficient (200 ohms per Volt for Models 6253A, 6255A, 6281A, 6284A, and 6289A or 300 ohms per Volt for Models 6294A and

6299A). The output voltage will increase 1 Volt for each 200 ohms (or 300 ohms) added in series with the programming terminals. The programming coefficient is determined by the programming current. This current is factory adjusted to within 2% of 5mA for Models 6253A, 6255A, 6281A, 6284A, and 6289A or 2% of 3.3mA for Models 6294A and 6299A. If greater programming accuracy is required, it may be achieved by changing resistor R13.



Figure 3-3. Remote Resistance Programming (Constant Voltage)

3-20 The output voltage of the power supply should be zero Volts  $\pm 20$  millivolts when zero ohms is connected across the programming terminals. If a zero ohm voltage closer than this is required, it may be achieved by changing resistor R6 or R8 as described in Paragraph 5-59.

3-21 To maintain the stability and temperature coefficient of the power supply, use programming resistors that have stable, low noise, and low temperature (less than 30 ppm per degree Centigrade) characteristics. A switch can be used in conjunction with various resistance values in order to obtain discrete output voltages. The switch should have make-before-break contacts to avoid momentarily opening the programming terminals during the switching interval.

3-22 Voltage Programming (Figure 3-4). Employ the strapping pattern shown on Figure 3-4 for



Figure 3-4. Remote Voltage Programming (Constant Voltage)

3-2

voltage programming. In this mode, the output voltage will vary in a 1 to 1 ratio with the programming voltage (reference voltage) and the load on the programming voltage source will not exceed 25mA.

3-23 The impedance matching resistor  $(R_X)$  for the programming voltage source should be approximately 500 ohms to maintain the temperature and stability specifications of the power supply.

#### 3-24 REMOTE PROGRAMMING, CONSTANT CURRENT

3-25 Either a resistance or a voltage source can be used to control the constant current output of the supply. The CURRENT controls on the front panel are disabled according to the following procedures.

3-26 <u>Resistance Programming (Figure 3-5).</u> In this mode, the output current varies at a rate determined by the programming coefficient — 200 ohms per Amp for Model 6281A, 500 ohms per Ampere for Models 6253A, 6255A, 6284A, and 6289A, and 1000 ohms per Ampere for Models 6294A and 6299A. The programming coefficient is determined by the Constant Current programming current (2mA for Models 6253A, 6255A, 6284A, and 6289A, 5mA for Model 6281A, 1mA for Model 6294A and 1.33mA for Model 6299A). This current is adjusted to within 10% at the factory. If greater programming accuracy is required, it may be achieved by changing resistor R19 as outlined in Section V.



Figure 3-5. Remote Resistance Programming (Constant Current)

3-27 Use stable, low noise, low temperature coefficient (less than 30ppm/°C) programming resistors to maintain the power supply temperature coefficient and stability specifications. A switch may be used to set discrete values of output current. A makebefore-break type of switch should be used since the output current will exceed the maximum rating of the power supply if the switch contacts open during the switching interval. CAUTION-

If the programming terminals (A1 and A5) should open at any time during this mode, the output current will rise to a value that may damage the power supply and/or the load. To avoid this possibility, connect a resistor across the programming terminals having the value listed below. Like the programming resistor, this resistor should be of the low noise, low temperature coefficient type.

Model	6253A,6284A	6255A,6289A,6299A
Resistance	1.5Kn	750n

Model	6281A,6294A
Resistance	1Kn

3-28 <u>Voltage Programming (Figure 3-6)</u>. In this mode, the output current will vary linearly with changes in the programming voltage. The programming voltage should not exceed 1.2 Volts. Voltage in excess of 1.2 Volts will result in excessive power dissipation in the instrument and possible damage.



Figure 3-6. Remote Voltage Programming (Constant Current)

3-29 The output current will be the programming voltage divided by 1 ohm. The current required from the voltage source will be less than 25 micro-amperes. The impedance matching resistor (R<sub>X</sub>) should be approximately 500 ohms if the temperature coefficient and stability specifications of the power supply are to be maintained.

### 3-30 REMOTE SENSING (See Figure 3-7)

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3-31 Remote sensing is used to maintain good regulation at the load and reduce the degradation of regulation which would occur due to the voltage drop in the leads between the power supply and the load. Remote sensing is accomplished by utilizing the strapping pattern shown in Figure 3-7. The power supply should be turned off before changing strapping patterns. The leads from the +S terminals to the load will carry less than 10mA of current, and it is not required that these leads be as heavy as the load leads. However, they must be twisted or shielded to minimize noise pick-up.

#### ----CAUTION----

Observe polarity when connecting the sensing leads to the load.



Figure 3-7. Remote Sensing

3-32 Note that it is desirable to minimize the drop in the load leads and it is recommended that the drop not exceed 1 Volt per lead if the power supply is to meet its dc specifications. If a larger drop must be tolerated, please consult a Hewlett-Packard field representative.

#### NOTE

Due to the voltage drop in the load leads, it may be necessary to readjust the current limit in the remote sensing mode.

3-33 The procedure just described will result in a low dc output impedance at the load. If a low ac impedance is required, it is recommended that the following precautions be taken:

a. Disconnect output capacitor C20 by disconnecting the strap between A9 and  $-\mathrm{S}$ 

b. Connect a capacitor having similar characteristics (approximately same capacitance, same voltage rating or greater, and having good high freguency characteristics) across the load using short leads.

3-34 Although the strapping patterns shown in Figures 3-3 through 3-6 employ local sensing, note that it is possible to operate a power supply simultaneously in the remote sensing and Constant Voltage/Constant Current remote programming modes.

#### 3-35 SERIES OPERATION

3-36 Normal Series Connections (Figure 3-8). Two

or more power supplies can be operated in series to obtain a higher voltage than that available from a single supply. When this connection is used, the output voltage is the sum of the voltages of the individual supplies. Each of the individual supplies must be adjusted in order to obtain the total output voltage. The power supply contains a protective diode connected internally across the output which protects the supply if one power supply is turned off while its series partner(s) is on.



Figure 3-8. Normal Series Connections

3-37 Auto-Series Connections (Figure 3-9). The Auto-Series configuration is used when it is desirable to have the output voltage of each of the series connected supplies vary in accordance with the setting of a control unit. The control unit is called the master; the controlled units are called slaves. At maximum output voltage, the voltage of the slaves is determined by the setting of the front panel VOLTAGE control on the master. The master supply must be the most positive supply of the series. The output CURRENT controls of all series units are operative and the current limit is equal to the lowest control setting. If any output CURRENT controls are set too low, automatic crossover to constant current operation will occur and the output voltage will drop. Remote sensing and programming can be used; however, the strapping arrangements shown in the applicable figures show local sensing and programming.

3-38 In order to maintain the temperature coefficient and stability specifications of the power supply, the external resistors (Rx) shown in Figure 3-9 should be stable, low noise, low temperature coefficient (less than 30 ppm per degree Centigrade) resistors. The value of each resistor is dependant on the maximum voltage rating of the "master" supply. The value of Rx is this voltage divided by the voltage programming current of the slave supply (1/Kp where Kp is the voltage programming coefficient). The voltage contribution of the slave is determined by its voltage control setting.

3-4



Figure 3-9. Auto-Series, Two and Three Units

#### 3-39 PARALLEL OPERATION

3-40 <u>Normal Parallel Connections (Figure 3-10)</u>. Two or more power supplies can be connected in parallel to obtain a total output current greater than that available from one power supply. The total output current is the sum of the output currents of the individual power supplies. The output CURRENT controls of each power supply can be separately set. The output voltage controls of one power supply should be set to the desired output voltage; the other power supply should be set for a slightly larger output voltage. The supply set to the lower output voltage will act as a constant voltage source; the supply set to the higher output will act as a constant current source, dropping its output



Figure 3-10. Normal Parallel Connections

voltage until it equals that of the other supply. The constant voltage source will deliver only that fraction of its total rated output current which is necessary to fulfill the total current demand.



Figure 3-11. Auto-Parallel, Two and Three Units

3-41 <u>Auto-Parallel</u>. The strapping patterns for Auto-Parallel operation of two power supplies are shown in Figure 3-11. Auto-Parallel operation permits equal current sharing under all load con-

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ditions, and allows complete control of output current from one master power supply. The output current of each slave will be approximately equal to the master's regardless of the load conditions. Because the output current controls of each slave are operative, they should be set to maximum to avoid having the slave revert to constant current operation; this would occur if the master output current setting exceeded the slave's.



Figure 3-12. Auto-Tracking, Two and Three Units

3-42 AUTO-TRACKING OPERATION (See Figure 3-12)

3-43 The Auto-Tracking configuration is used when it is necessary that several different voltages referred to a common bus, vary in proportion to the setting of a particular instrument (the control or

master). A fraction of the master's output voltage is fed to the comparison amplifier of the slave supply, thus controlling the slave's output. The master must have the largest output voltage of any power supply in the group (must be the most positive supply in the example shown on Figure 3-12).

3-44 The output voltage of the slave is a percentage of the master's output voltage, and is determined by the voltage divider consisting of  $R_X$  (or  $R_X$ and  $R_Y$ ) and the voltage control of the slave supply,  $R_p$ , where:  $E_S = E_M R_P / R_X + R_P$ . Turn-on and turn-off of the power supplies is controlled by the master. Remote sensing and programming can be used; although the strapping patterns for these modes show only local sensing and programming. In order to maintain the temperature coefficient and stability specifications of the power supply, the external resistors should be stable, low noise, low temperature (less than 30ppm per <sup>o</sup>C) resistors.

# 3-45 SPECIAL OPERATING CONSIDERATIONS

### 3-46 PULSE LOADING

3-47 The power supply will automatically crossover from constant voltage to constant current operation, or the reverse, in response to an increase (over the preset limit) in the output current or voltage, respectively. Although the preset limit may be set higher than the average output current or voltage, high peak currents or voltages (as occur in pulse loading) may exceed the preset limit and cause crossover to occur. If this crossover limiting is not desired, set the preset limit for the peak requirement and not the average.

## 3-48 OUTPUT CAPACITANCE

3-49 An internal capacitor, connected across the output terminals of the power supply, helps to supply high-current pulses of short duration during constant voltage operation. Any capacitance added externally will improve the pulse current capability, but will decrease the safety provided by the constant current circuit. A high-current pulse may damage load components before the average output current is large enough to cause the constant current circuit to operate.

3-50 The effects of the output capacitor during constant <u>current</u> operation are as follows:

a. The output impedance of the power supply decreases with increasing frequency.

b. The recovery time of the output voltage is longer for load resistance changes.

c. A large surge current causing a high power dissipation in the load occurs when the load resistance is reduced rapidly.

## 3-51 REVERSE VOLTAGE LOADING

3-52 A diode is connected across the output terminals. Under normal operating conditions, the diode is reverse biased (anode connected to negative terminal). If a reverse voltage is applied to the output terminals (positive voltage applied to negative terminal), the diode will conduct, shunting current across the output terminals and limiting the voltage to the forward voltage drop of the diode. This diode protects the series transistors and the output electrolytic capacitor.

## 3-53 REVERSE CURRENT LOADING

3-54 Active loads connected to the power supply may actually deliver a reverse current to the power supply during a portion of its operating cycle. An external source cannot be allowed to pump current into the supply without loss of regulation and possible damage to the output capacitor. To avoid these effects, it is necessary to preload the supply with a dummy load resistor so that the power supply delivers current through the entire operating cycle of the load device.

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#### SECTION IV PRINCIPLES OF OPERATION



Figure 4-1. Overall Block Diagram

## 4-1 OVERALL BLOCK DIAGRAM DISCUSSION

4-2 The power supply, as shown on the overall block diagram on Figure 4-1, consists of a power transformer, a rectifier and filter, a series regulator, the mixer and error amplifiers, an "OR" gate, a constant voltage input circuit, a constant current input circuit, a reference regulator circuit, a bias supply, and a metering circuit.

4-3 The input line voltage passes through the power transformer to the rectifier and filter. The rectifier-filter converts the AC input to raw DC which is fed to the positive terminal via the regulator and current sampling resistor network. The regulator, part of the feedback loop, is made to alter its conduction to maintain a constant output voltage or current. The voltage developed across the current sampling resistor network is the input to the constant current input circuit. The constant voltage input circuit obtains its input by sampling the output voltage of the supply.

4-4 Any changes in output voltage/current are detected in the constant voltage/constant current input circuit, amplified by the mixer and error amplifiers, and applied to the series regulator in the correct phase and amplitude to counteract the change in output voltage/output current. The reference circuit provides stable reference voltages which are used by the constant voltage/current input circuits for comparison purposes. The bias supply furnishes voltages which are used throughout the instrument for biasing purposes. The metercircuit provides an indication of output voltage or current for both operating modes.



Figure 4-2. Simplified Schematic

#### 4-5 SIMPLIFIED SCHEMATIC

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4-6 A simplified schematic of the power supply is shown in Figure 4-2. It shows the operating controls; the ON-off switch, the voltage and current programming controls R10 and R16. Figure 4-2 also shows the internal sources of bias and reference voltages and their nominal magnitudes with an input of 115 VAC.

4-7 Diode CR34, connected across the output

terminals of the power supply, is a protective device which prevents internal damage that might occur if a reverse voltage were applied across the output terminals. Output capacitor, C20, is also connected across the output terminals when the normal strapping pattern shown on Figure 4-2 is employed. Note that this capacitor can be removed if an increase in the programming speed is desired. Under these conditions, capacitor C19 serves to insure loop stability.

## 4-8 <u>DETAILED CIRCUIT ANALYSIS</u> (Refer to overall schematic diagram at rear of manual)

#### 4-9 FEEDBACK LOOP

4-10 The feedback loop functions continuously to keep the output voltage constant, during constant voltage operation, and the output current constant, during constant current operation. For purposes of this discussion, assume that the unit is in constant voltage operation and that the programming resistors R10 A and B have been adjusted so that the supply is yielding the desired output voltage. Further assume that the output voltage instantaneously rises (goes positive) due to a variation in the external load circuit.

4-11 Note that the change may be in the form of a slow rise in the output voltage or a positive going AC signal. An AC signal is coupled to summing point A6 through capacitor C1 and a DC voltage is coupled to A6 through R10.

4-12 The rise in output voltage causes the voltage at A6 and thus the base of QIA to decrease (go negative). QIA now decreases its conduction and its collector voltage rises. The positive going error voltage is amplified and inverted by Q3 and fed to the bases of series transistors Q6 and Q7 via emitter followers Q5 and Q4. The negative going input causes Q6 and Q7 to decrease their conduction so that they drop more of the line voltage, and reduce the output voltage to its original level.

4-13 If the external load resistance is decreased to a certain crossover point, the output current increases until transistor Q2A begins to conduct. During this time, the output voltage has also decreased to a level so that the base of QlA is at a high positive potential. With QIA in full conduction, its collector voltage decreases by the amount necessary to back bias OR gate diode CR3 and the supply is now in the constant current mode of operation. The crossover point at which constant current operation commences is determined by the setting of CURRENT control R16. The operation of the feedback loop during the constant current operating mode is similar to that occuring during constant voltage operation except that the input to the differential amplifier comparison circuit is obtained from the current sampling resistor network.

#### 4-14 SERIES REGULATOR

4-15 The series regulator consists of transistor stages Q6 and Q7 (see schematic at rear of manual). Transistor Q6 is the series element, or pass transistor, which controls the output. Transistor Q7, together with shunt resistors R81, R82, and R83, are connected in a manner which minimizes the power dissipated in series transistor Q6. The bias voltage for Q7 is developed across zener diode VR5. The The conduction of Q7 will decrease as the collectorto-emitter voltage of Q6 approaches the voltage developed across the biasing diodes. At low output voltages Q7 is completely cutoff and all of the load current flows through the shunt resistors. The voltage that is dropped across Q7 and the shunt resistors reduces the voltage dropped across Q6, thus diminishing its power dissipation. The reliability of the regulator is further increased by mounting the shunt resistors outside the rear of the cabinet so that the internal components are operated under lower temperature conditions. Diode CR11, connected across Q6, protects it from reverse voltages that could develop across it during parallel or auto-parallel operation if one supply is turned on before the other. Diodes CR18 and CR19 perform a similar function for Q7.

## 4-16 CONSTANT VOLTAGE INPUT CIRCUIT

4-17 The circuit consists of programming resistor R10A and B, and a differential amplifier stage (Q1 and associated components). Transistor Q1 consists of two transistors housed in a single package. The transistors have matched characteristics minimizing differential voltages due to mismatched stages. Moreover, drift due to thermal differentials is minimized, since both transistors operate at essentially the same temperature.

4-18 The constant voltage input circuit continuously compares a fixed reference voltage with a portion of the output voltage and, if a difference exists, produces an error voltage whose amplitude and phase is proportional to the difference. The error output is fed back to the series regulator, through an OR gate and the mixer/error amplifiers. The error voltage changes the conduction of the series regulator which, in turn, alters the output voltage so that the difference between the two input voltages applied to the differential amplifier is reduced to zero. The above action maintains the output voltage constant.

4-19 Stage Q1B of the differential amplifier is connected to a common (+S) potential through impedance equalizing resistor R5. Resistors R6 and R8 are used to zero bias the input stage, offsetting minor base-to-emitter voltage differences in Q1. The base of Q1A is connected to a summing point at the junction of the programming resistor and the current pullout resistor, R12. Instantaneous changes in output voltage result in an increase or decrease in the summing point potential. Q1A is then made to conduct more or less, in accordance with the summing point voltage change. The resultant output error voltage is fed back to the series regulator via OR-gate diode CR3 and the